

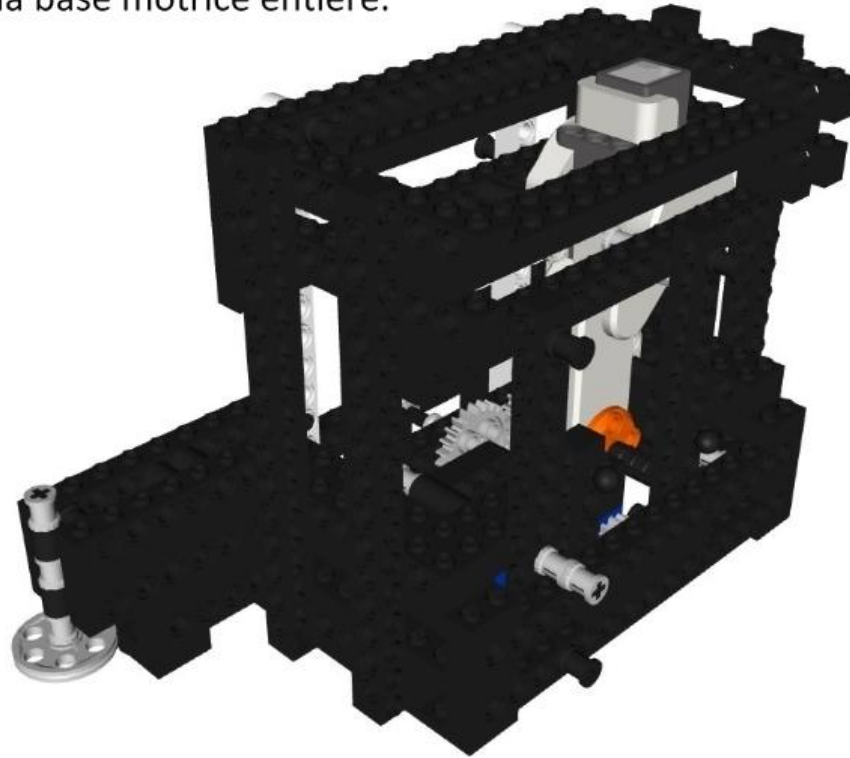
TUTORIEL : BASE ROULANTE DU ROBOT 2010

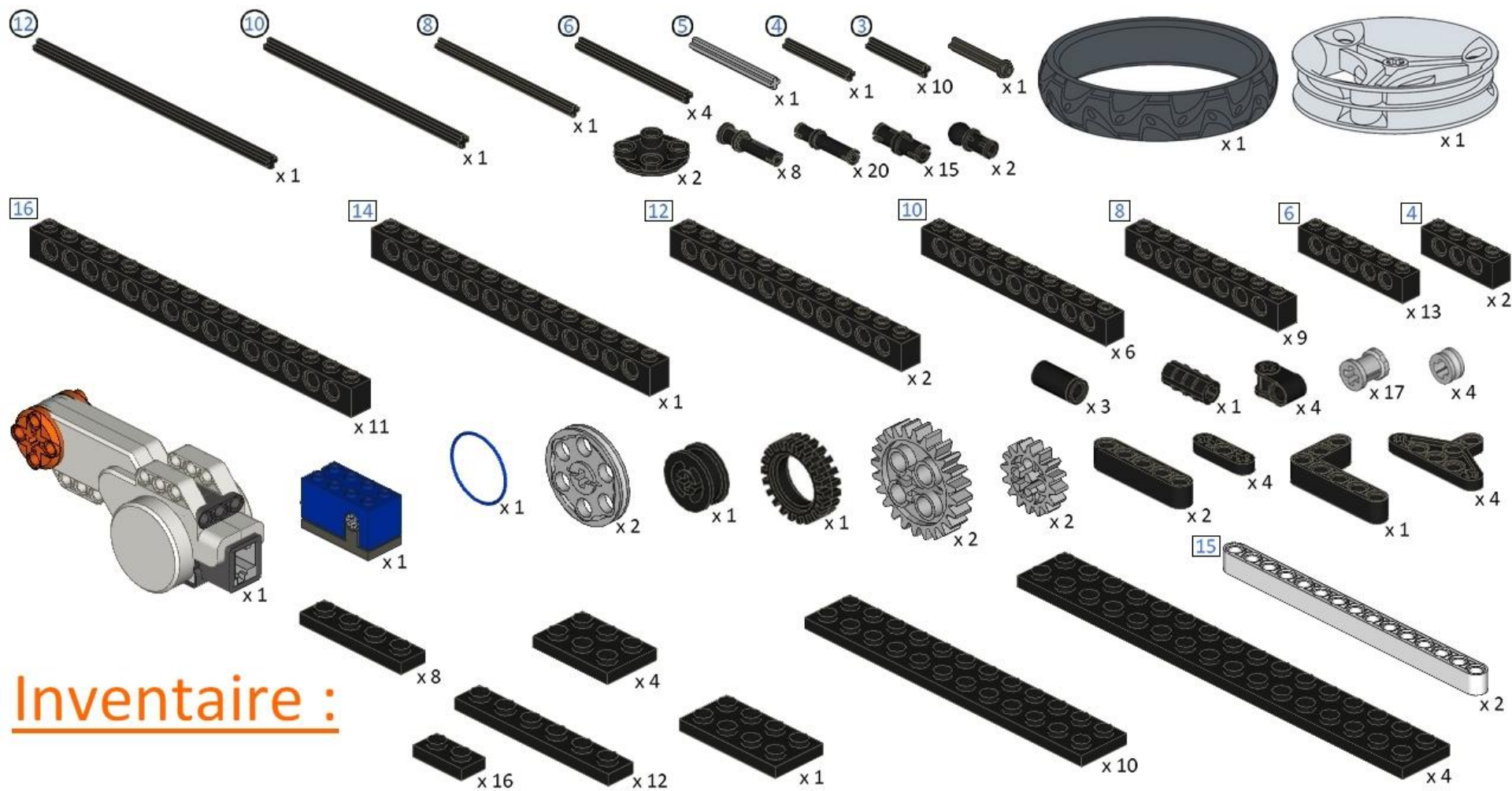


Réalisé par la *PERRIN'S TEAM*

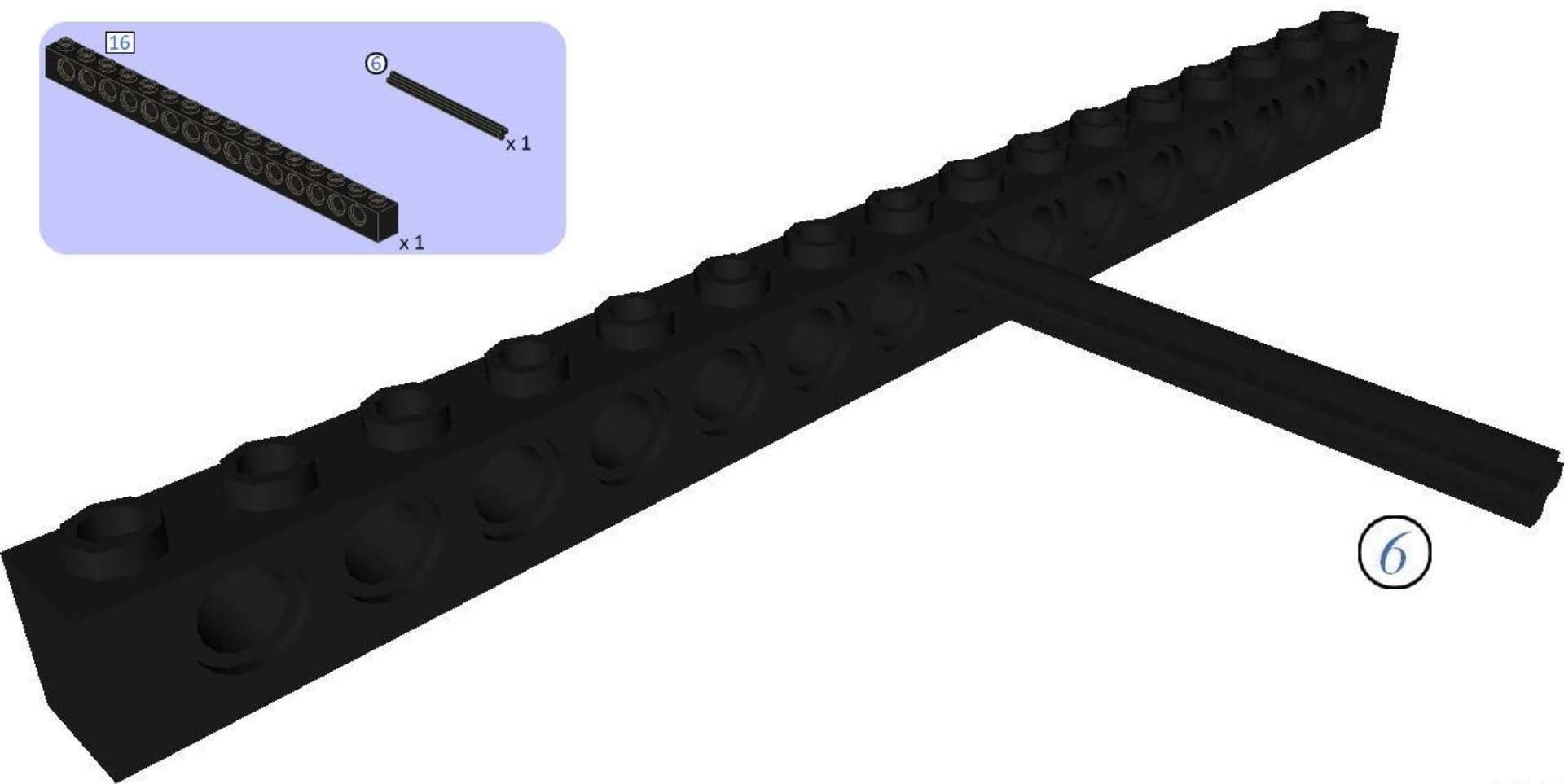
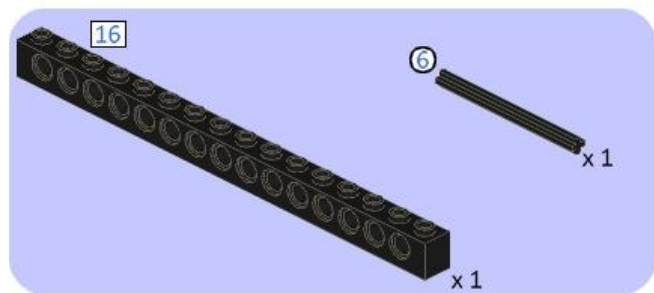
<http://www.perrinsteam.fr>

Grâce à ce tutoriel, vous pourrez réaliser la partie droite de la base motrice du robot 2010 de la Perrin's Team qui participera à la Coupe de France de Robotique. Il vous sera aisé de réaliser la base motrice entière.



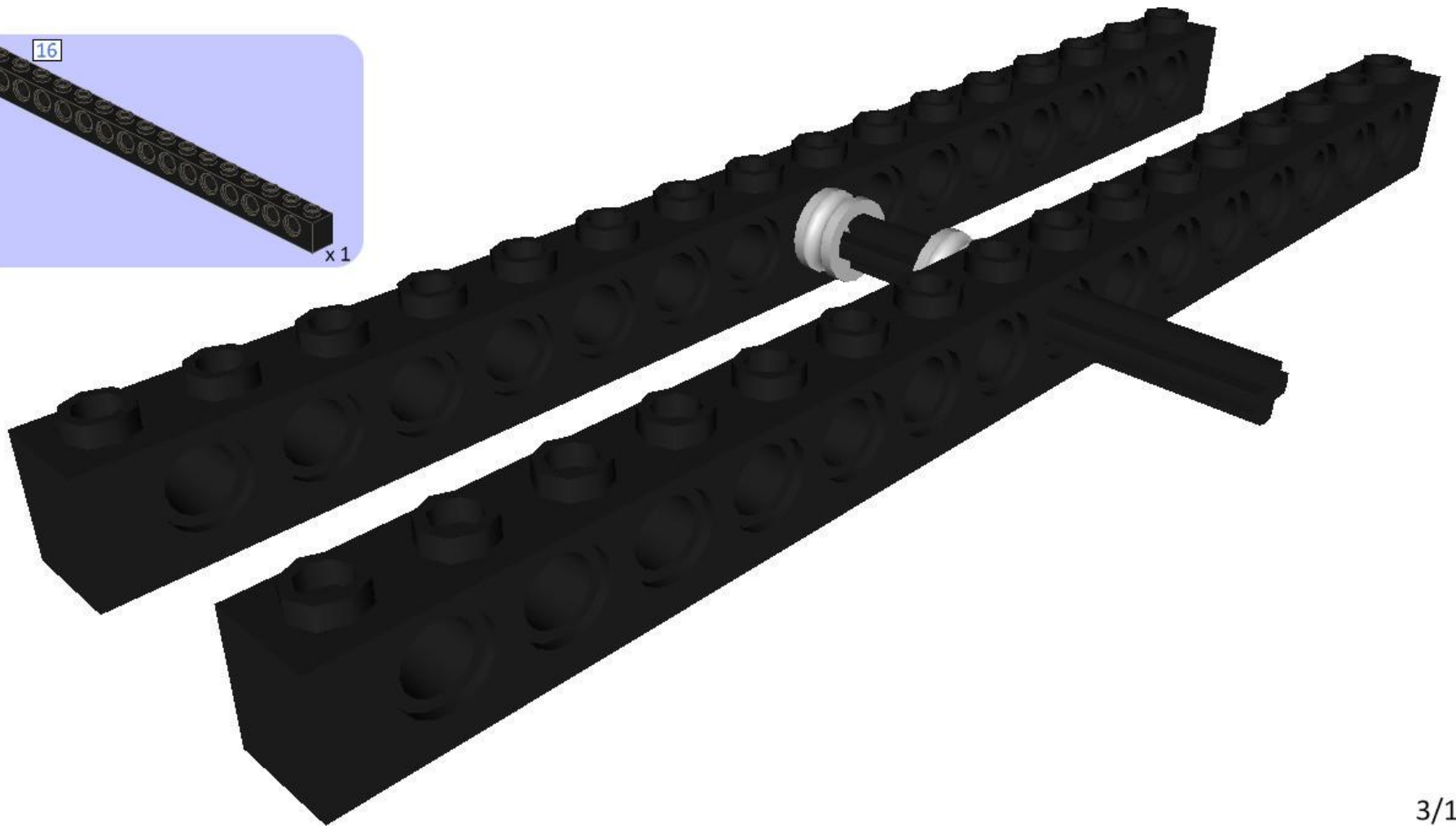
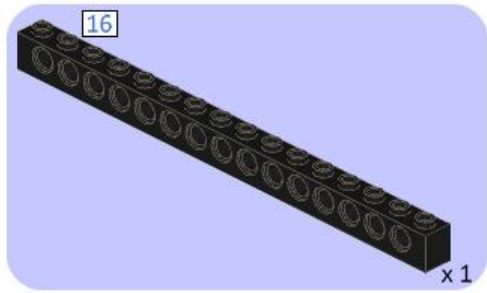


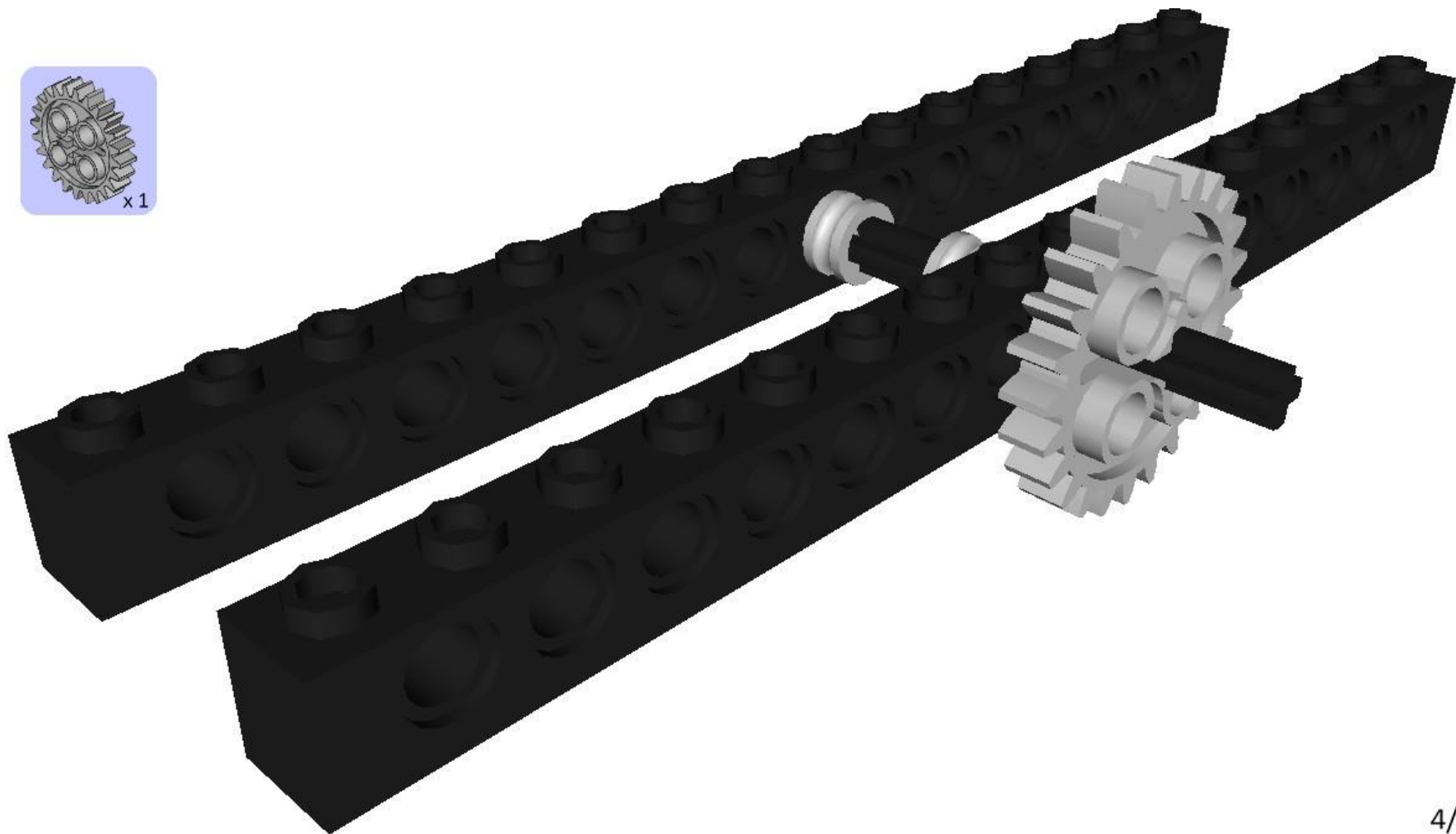
Inventaire :

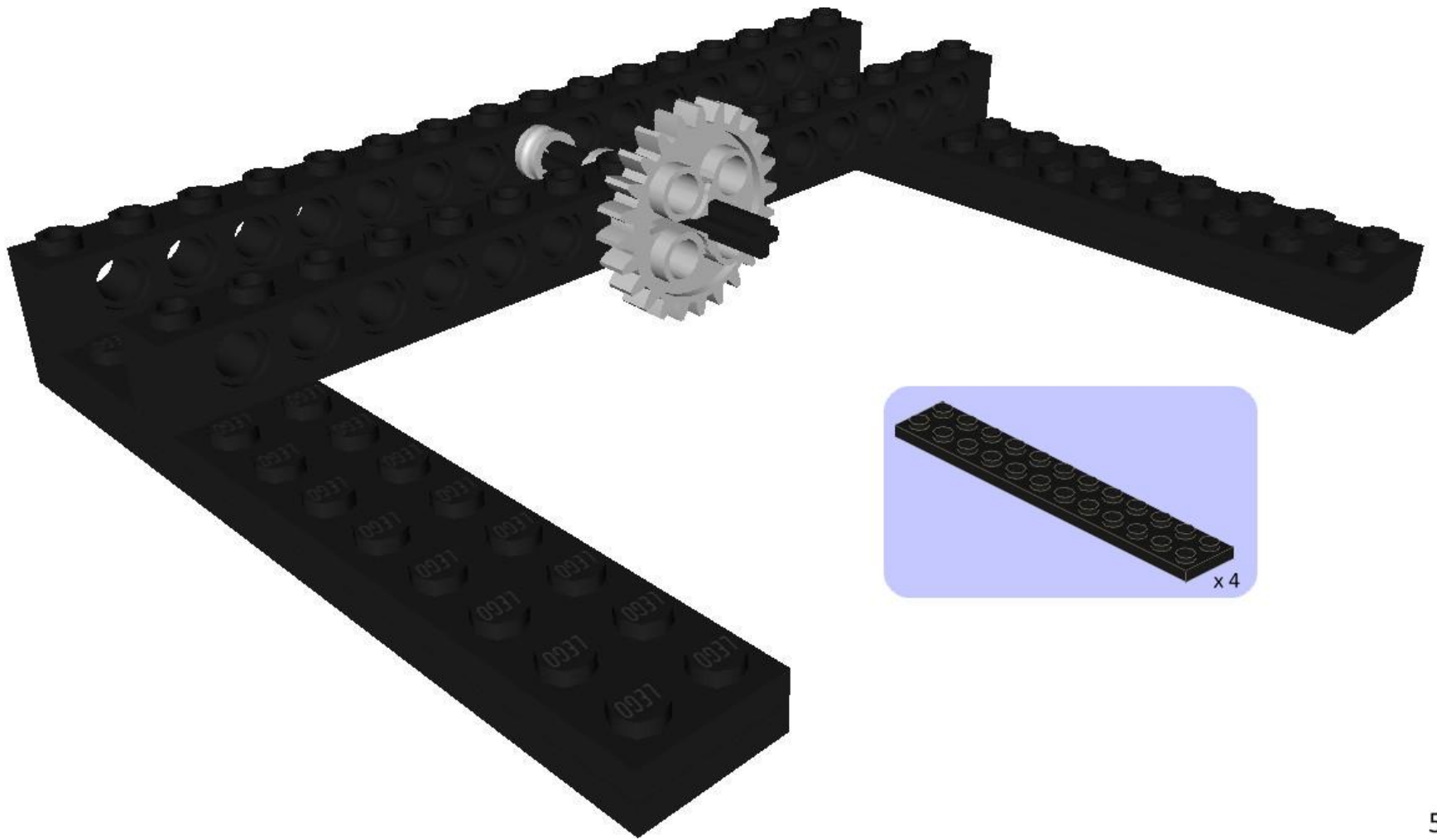


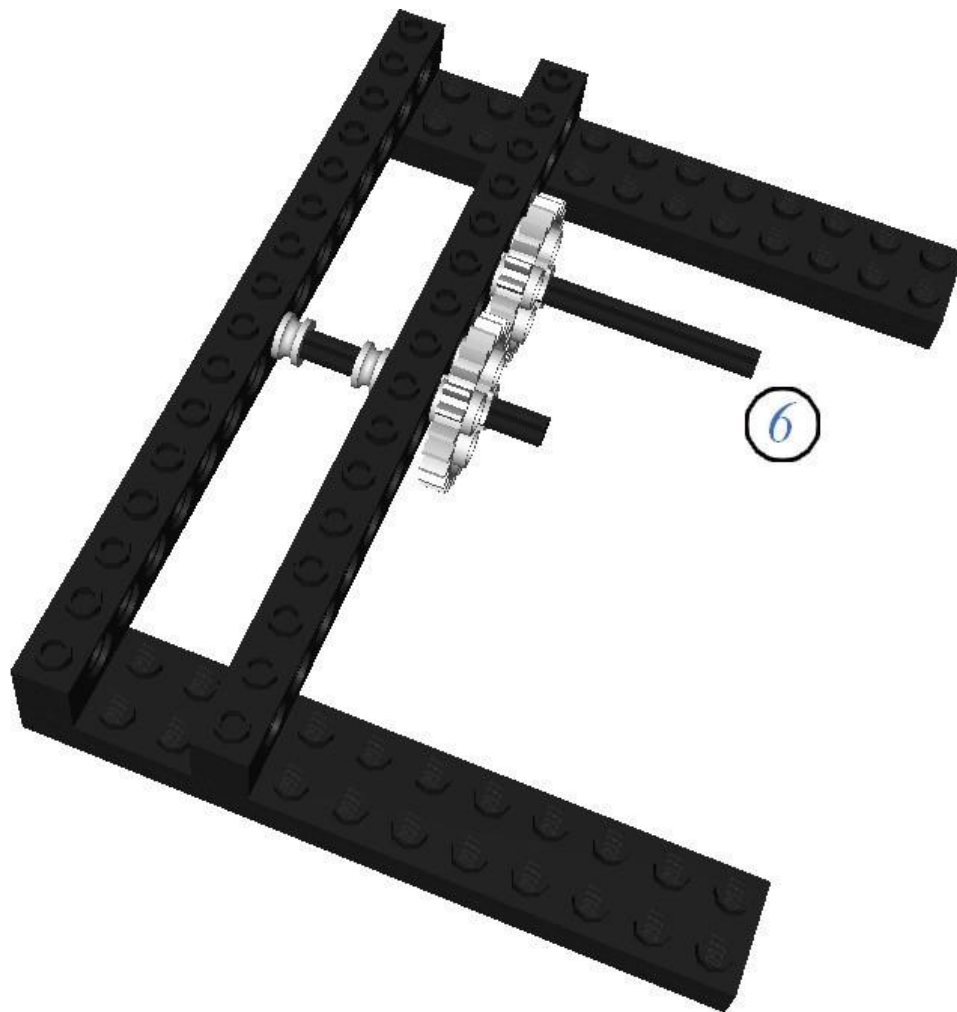
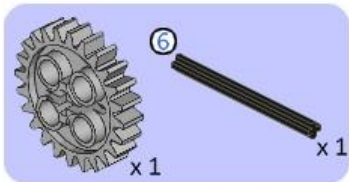


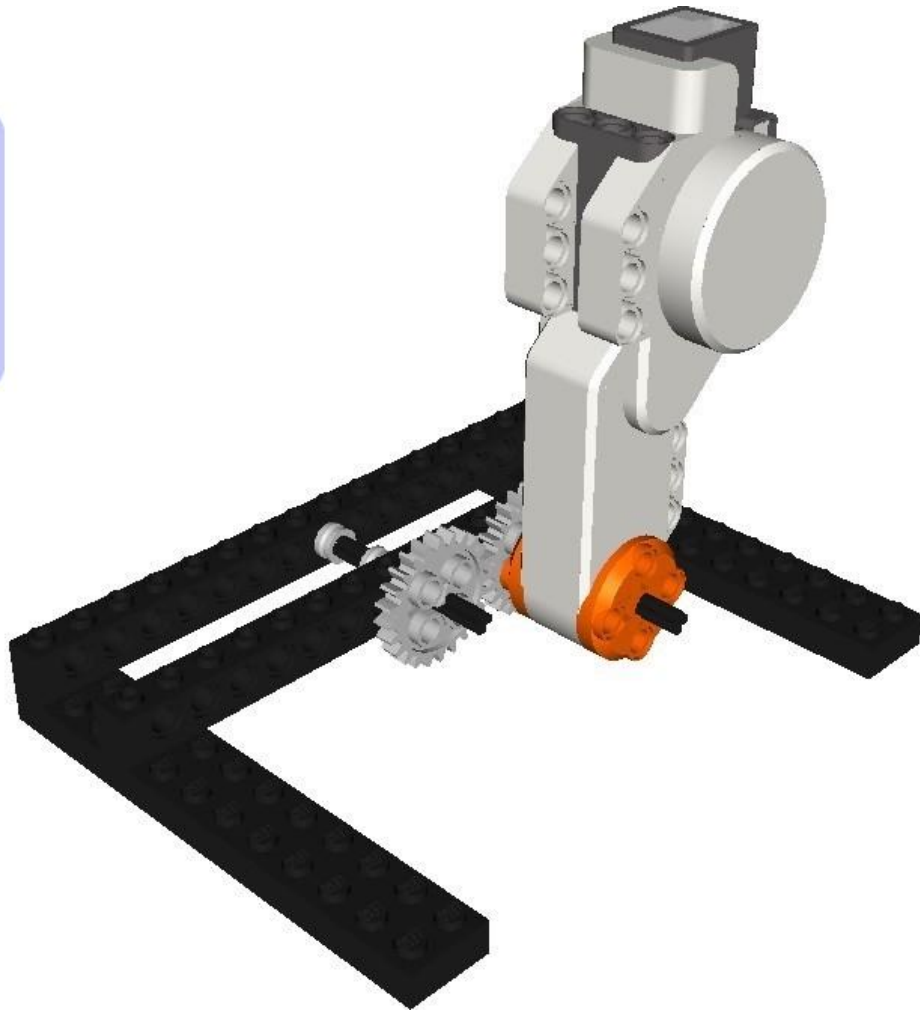
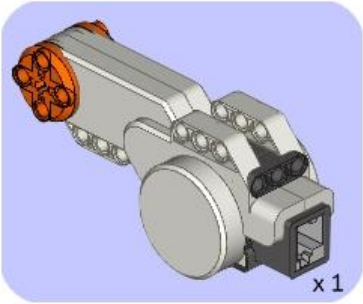
Mettre la roue et le pneu entre les deux rondelles

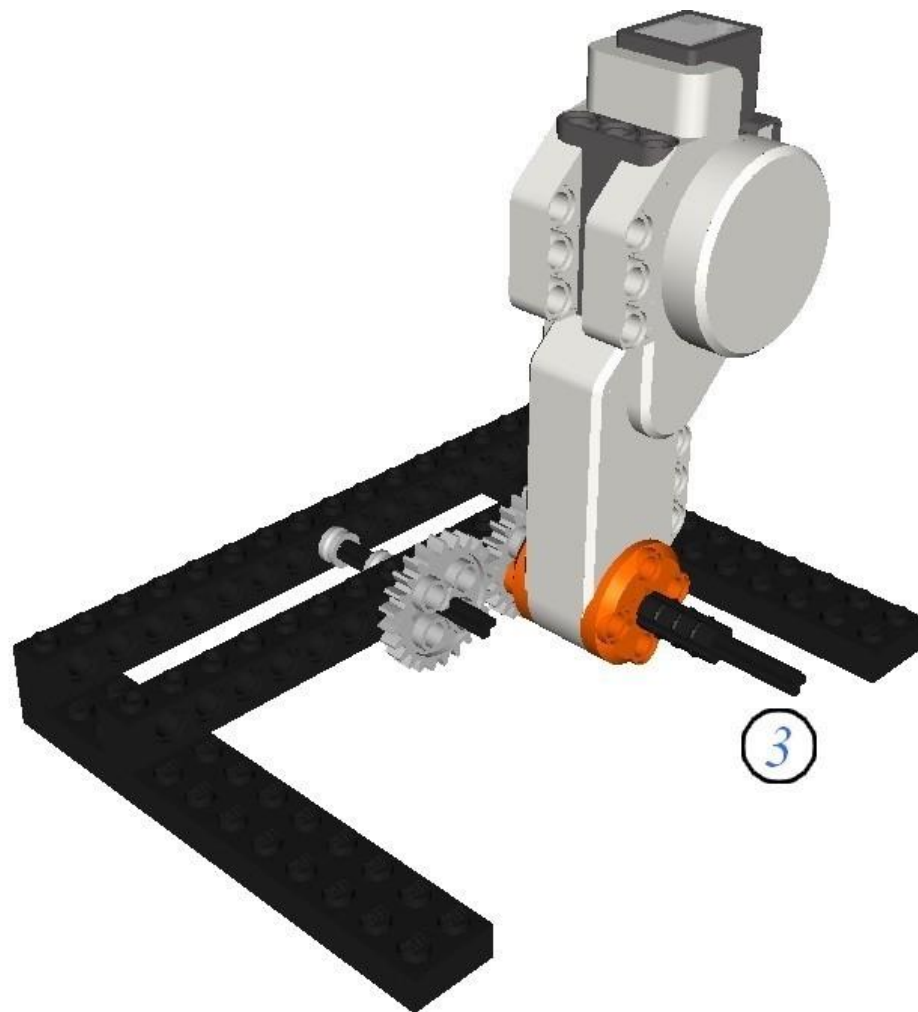


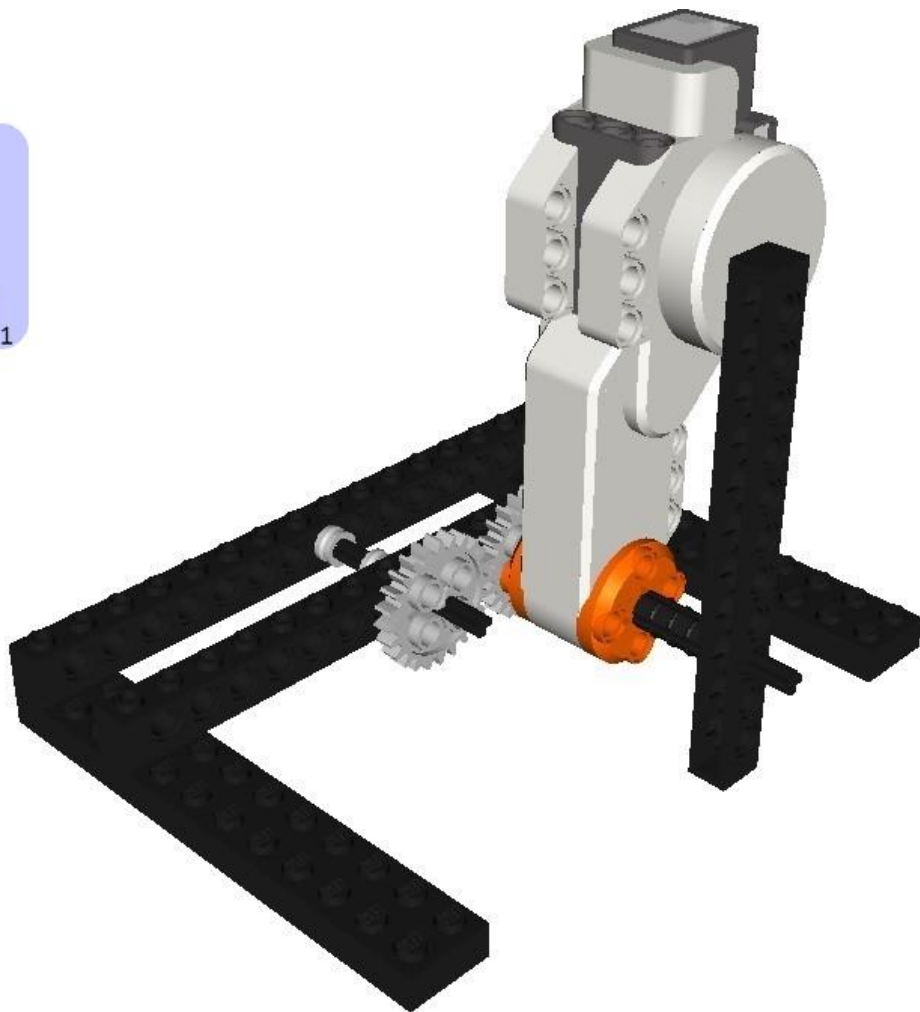
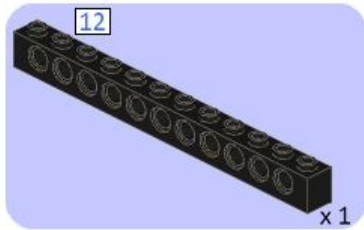


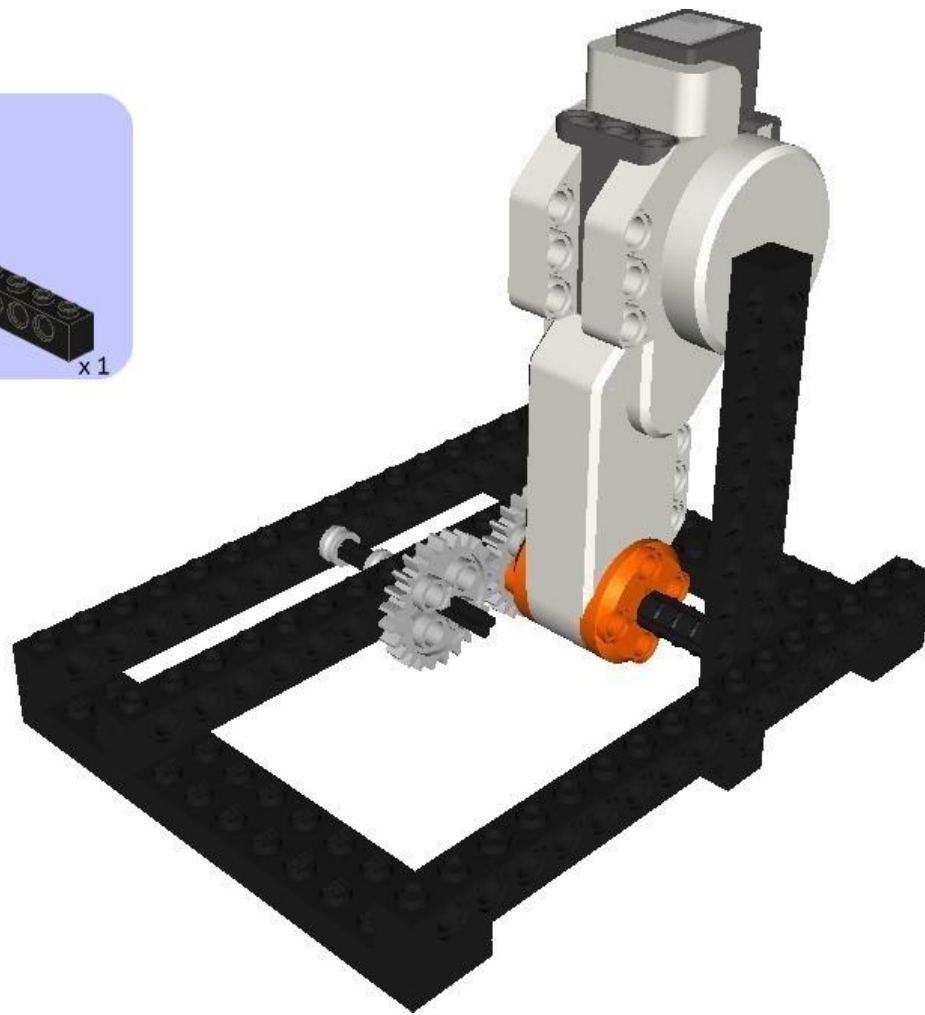
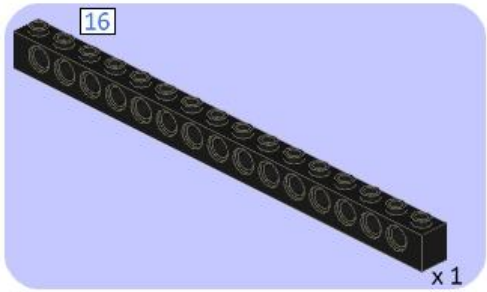


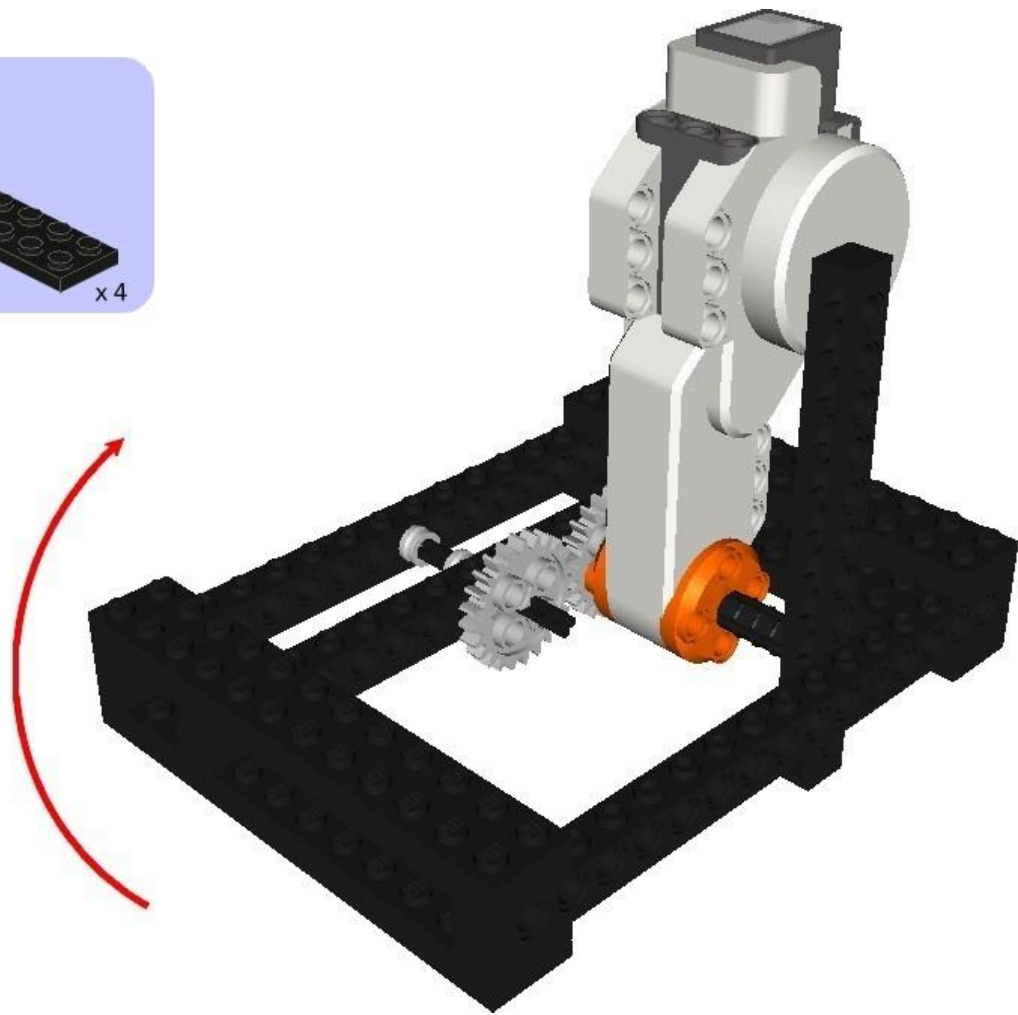
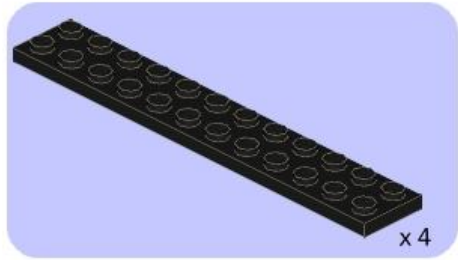


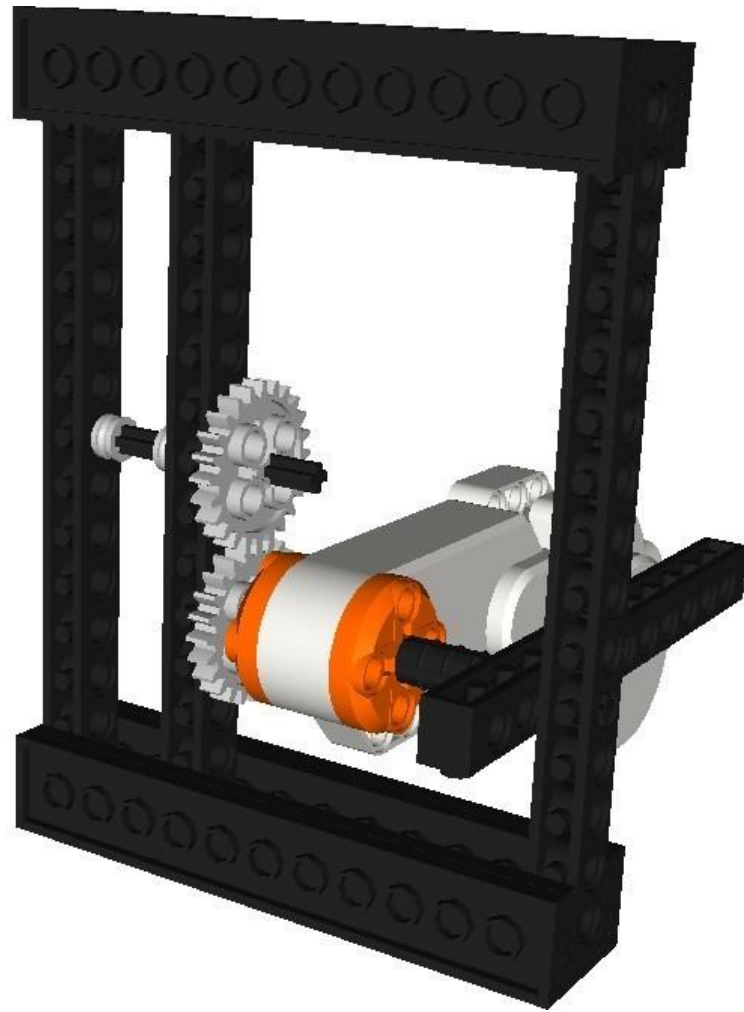


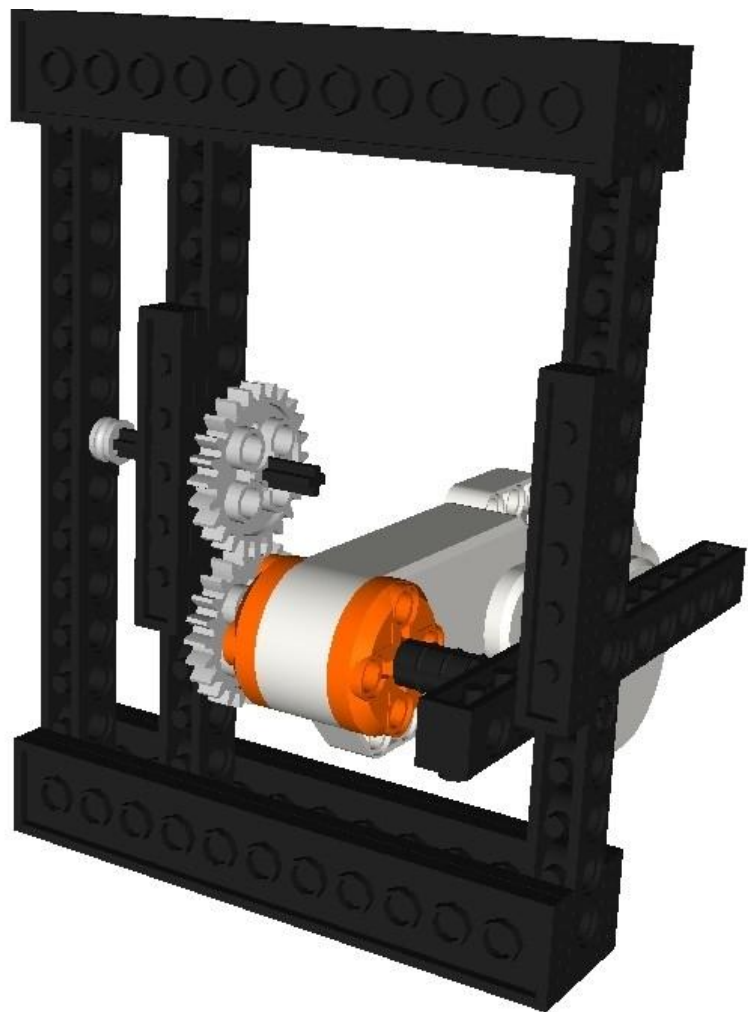


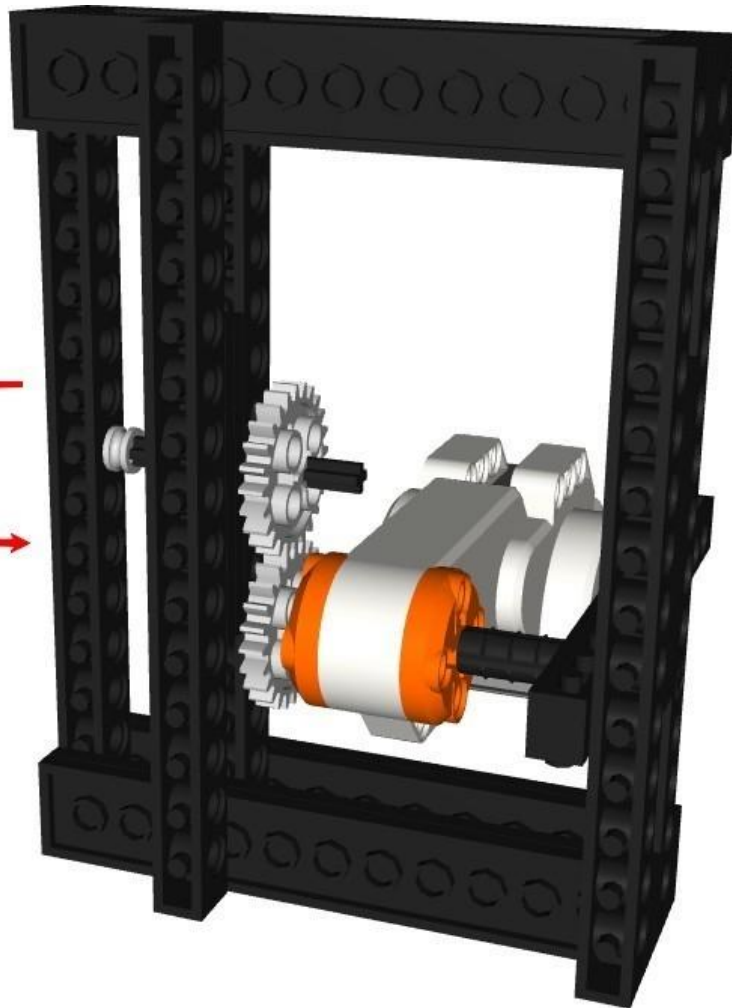
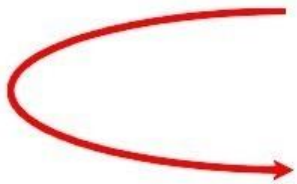
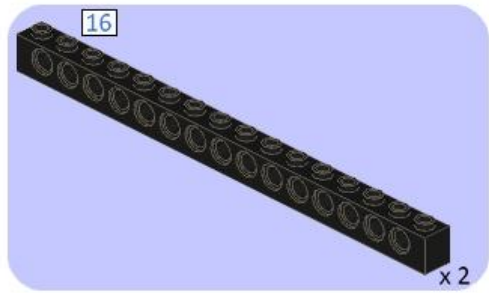


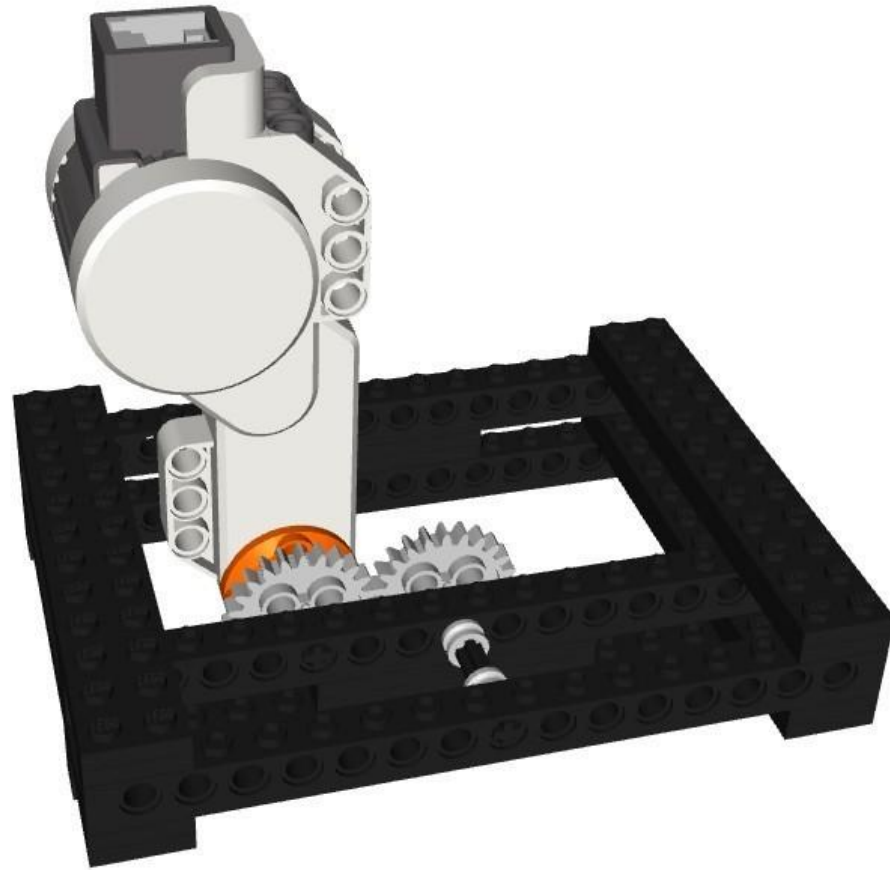


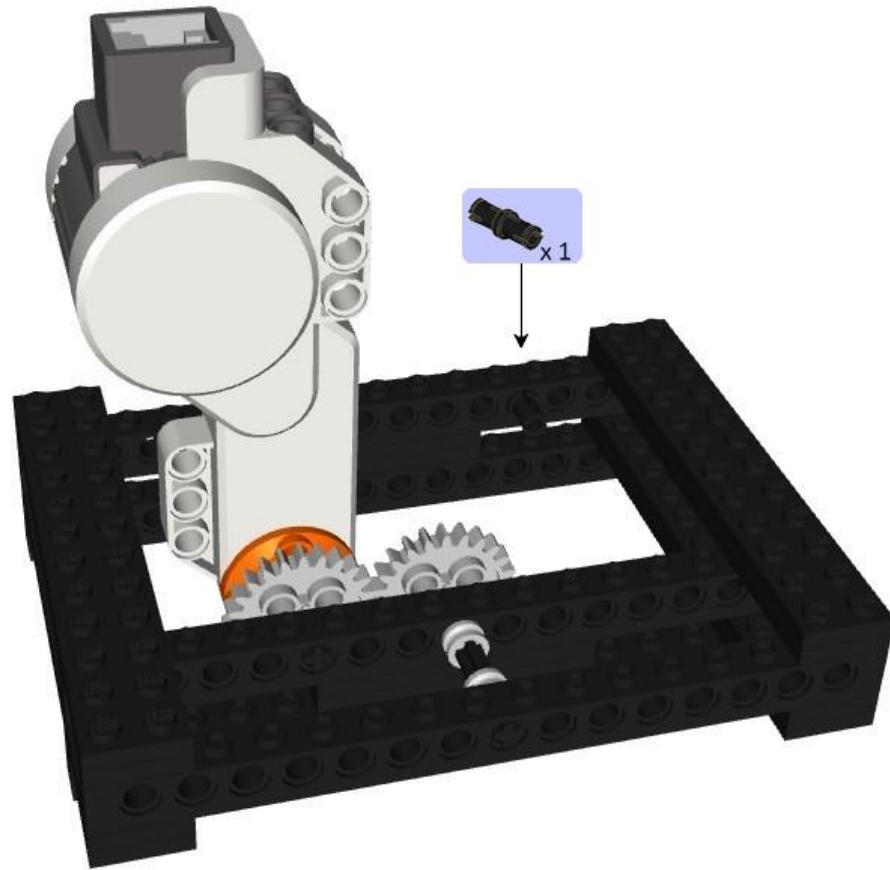


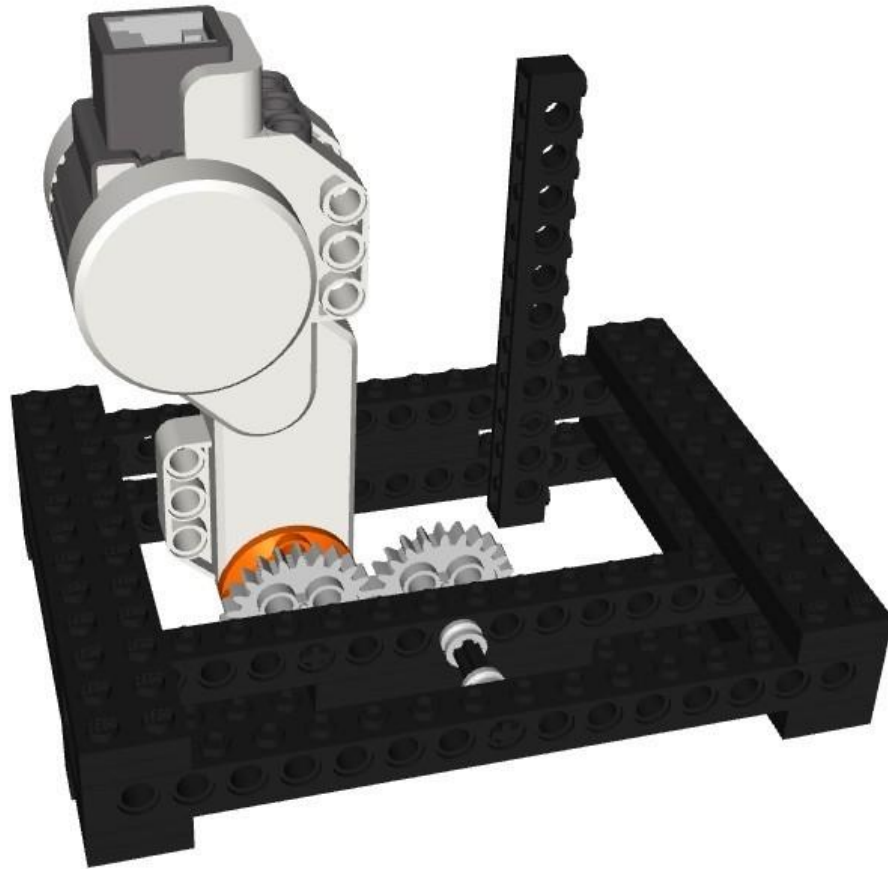
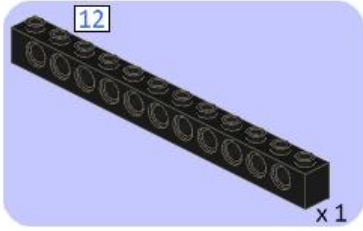


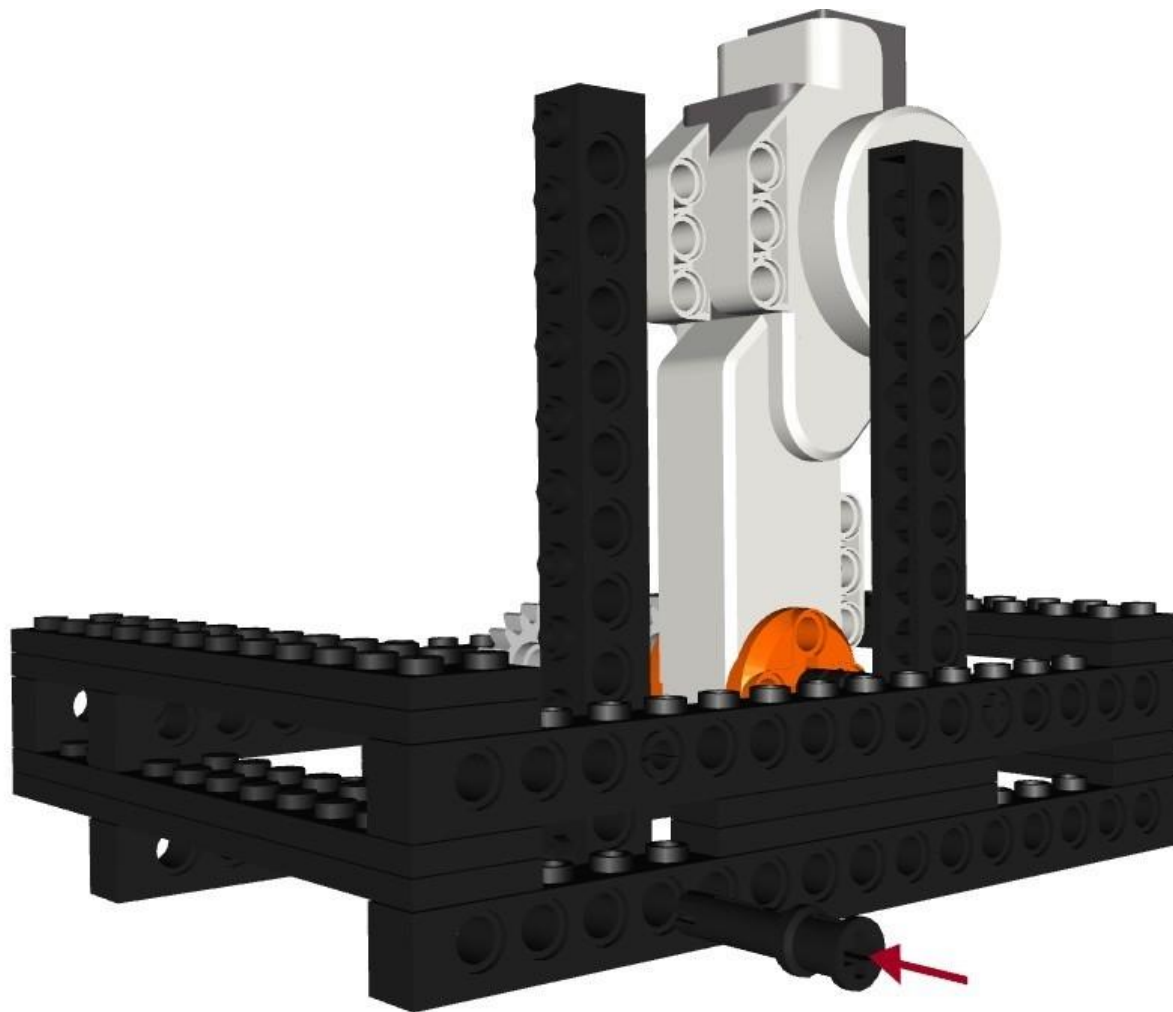




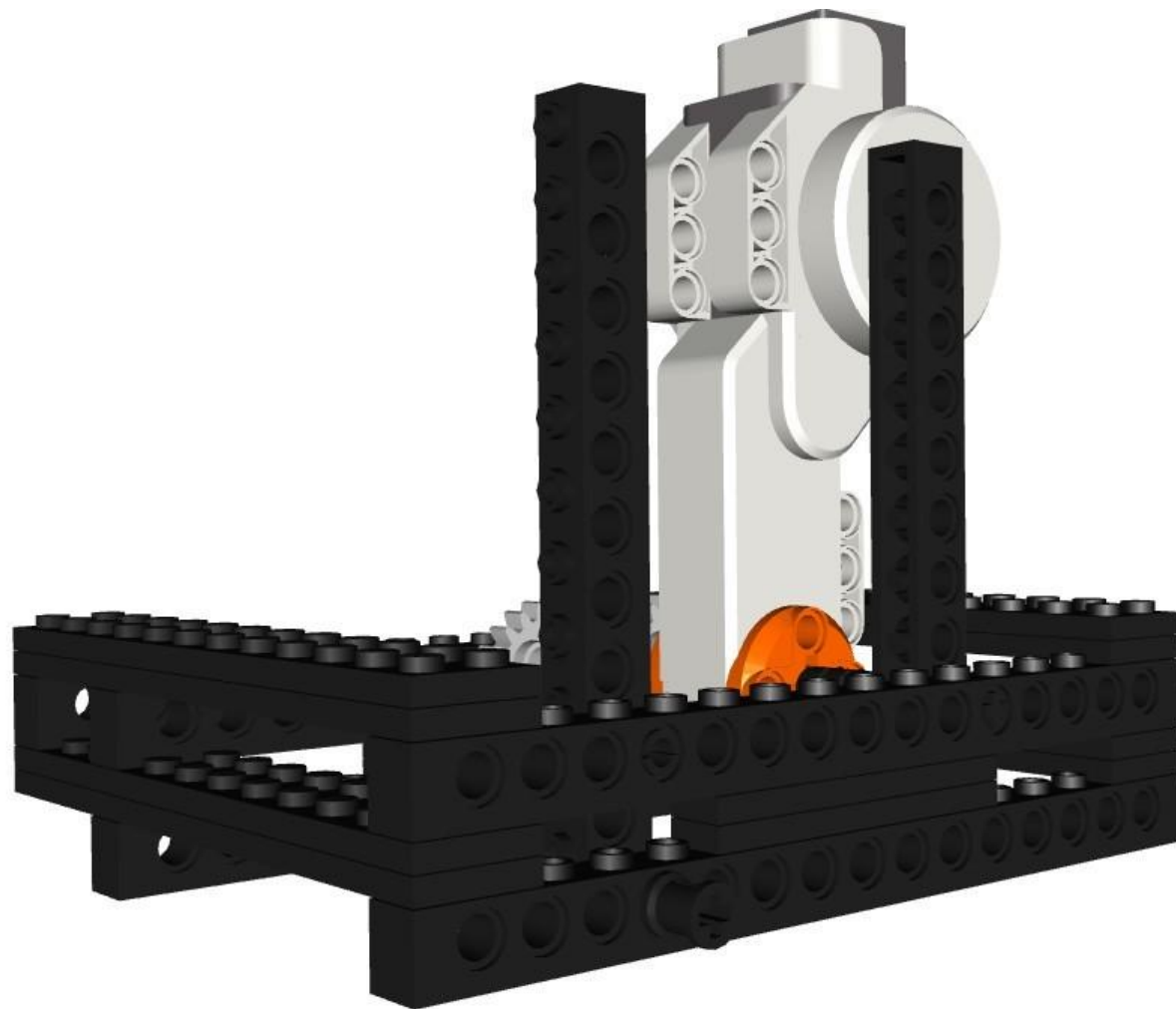


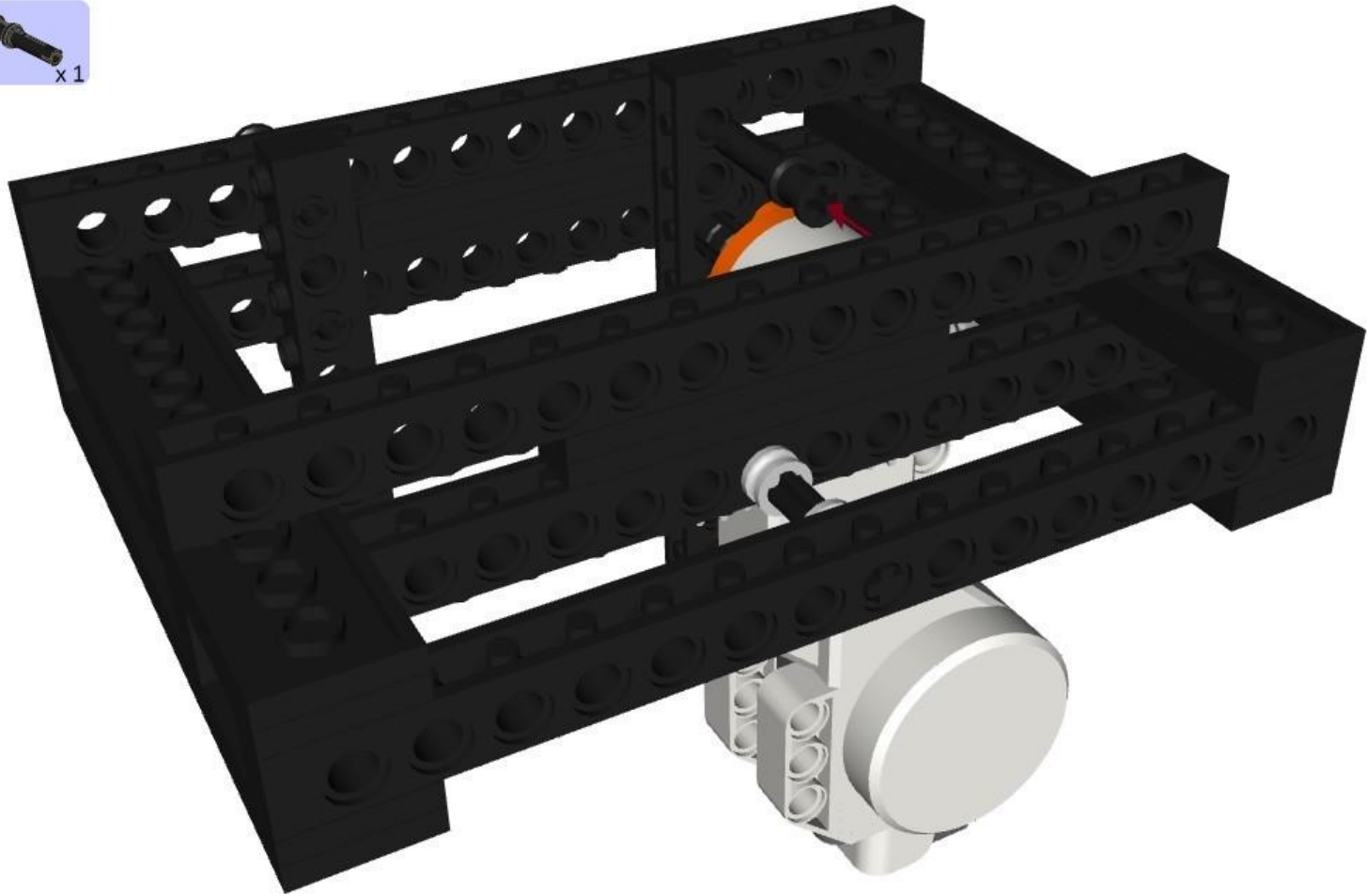




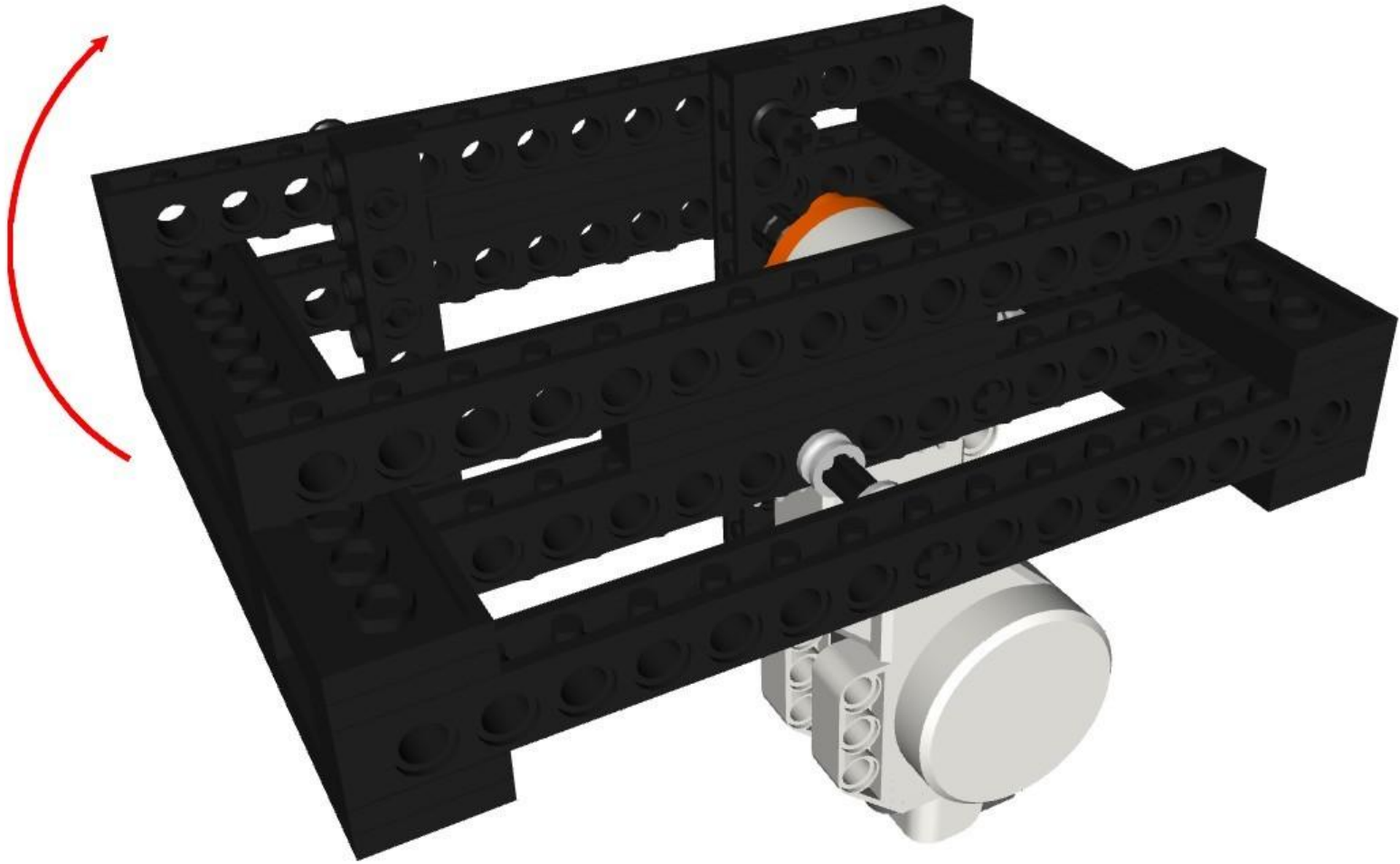


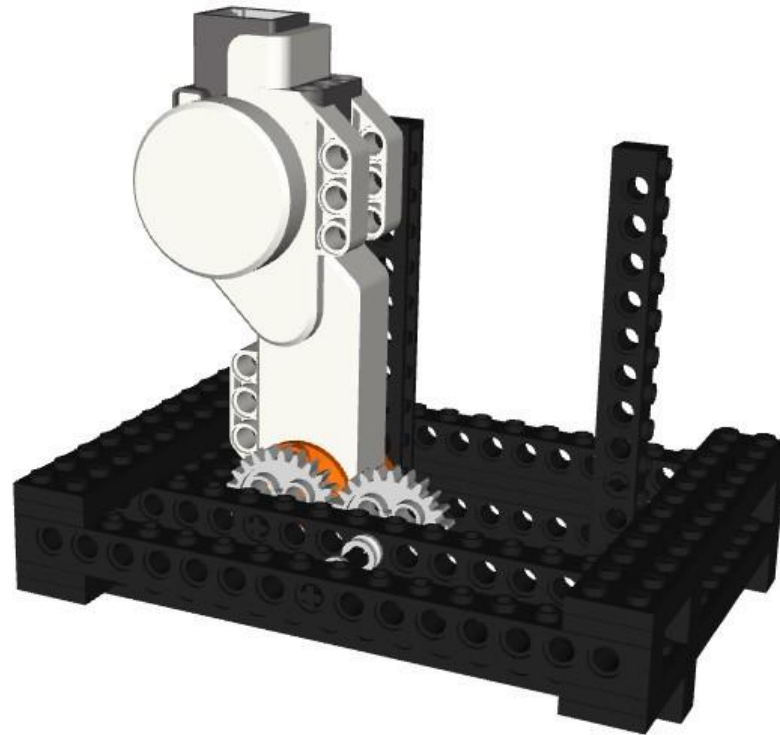
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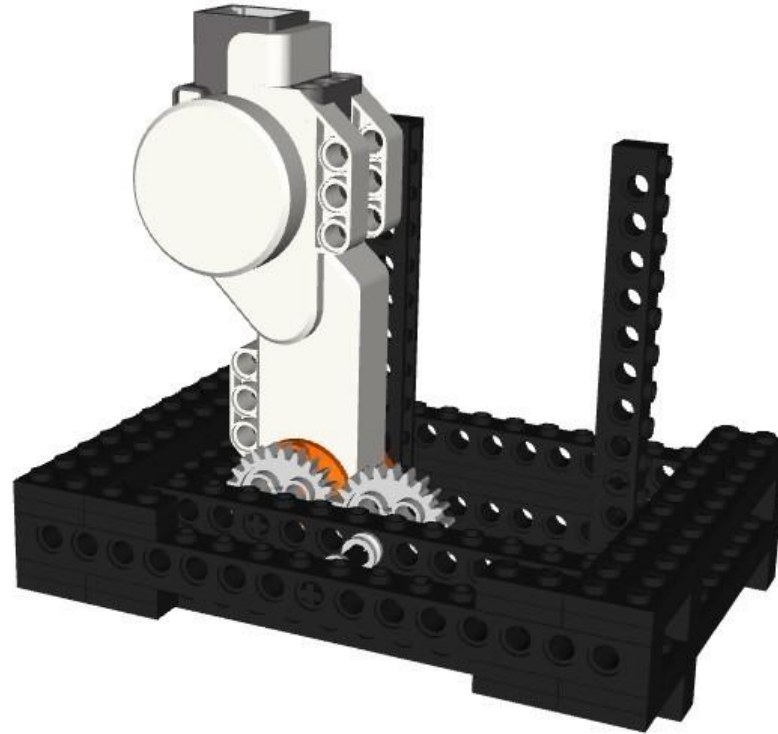
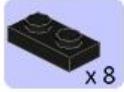


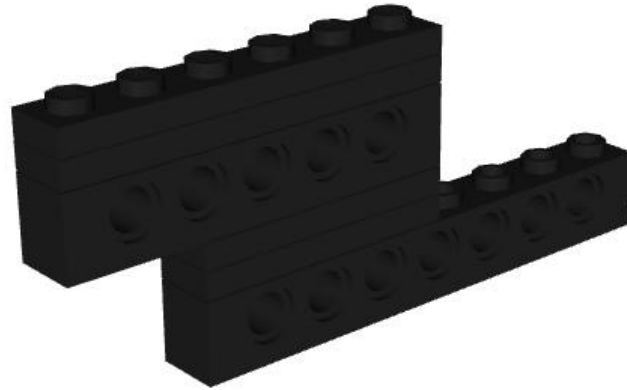
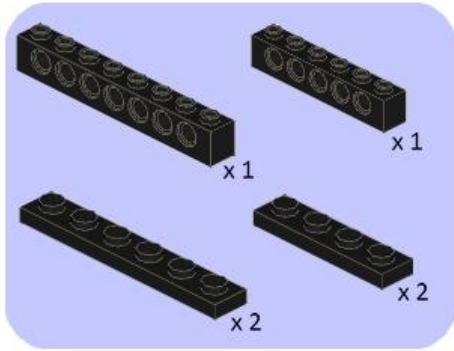


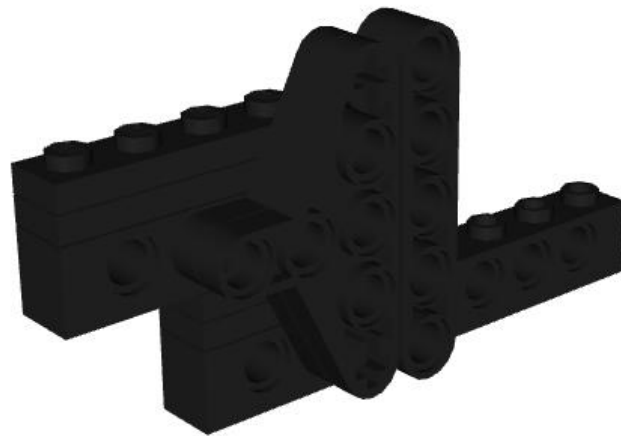
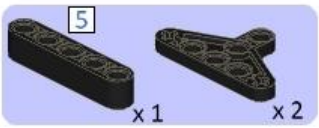
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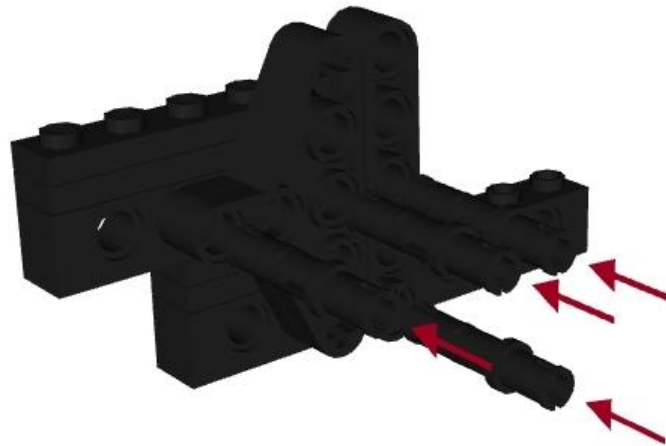


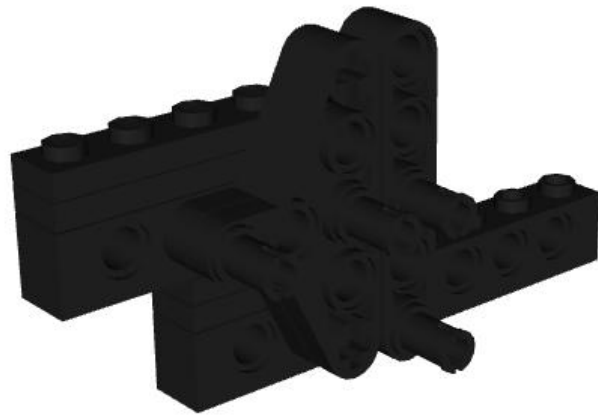


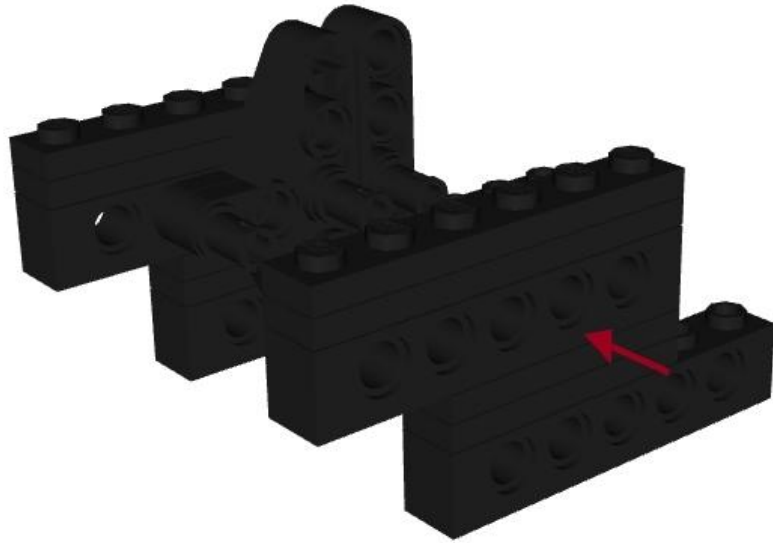
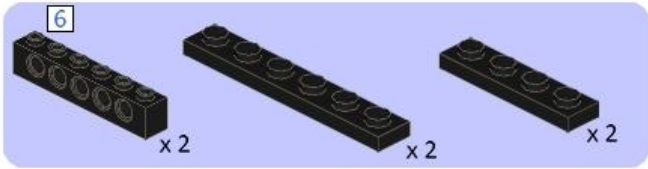


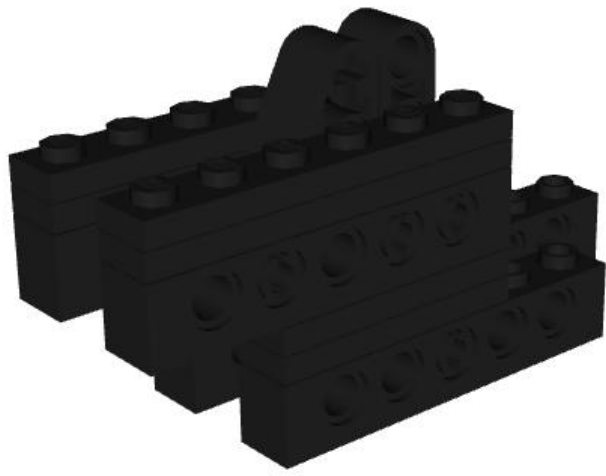


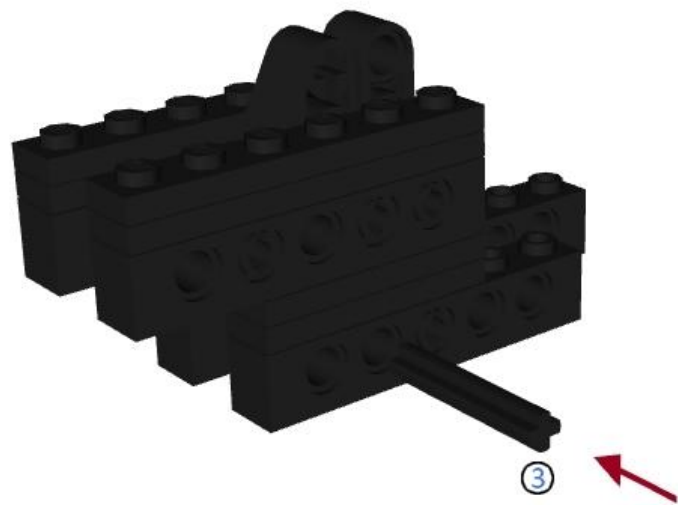


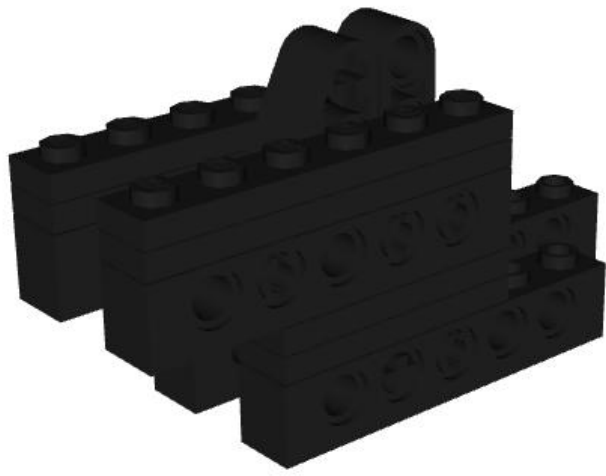


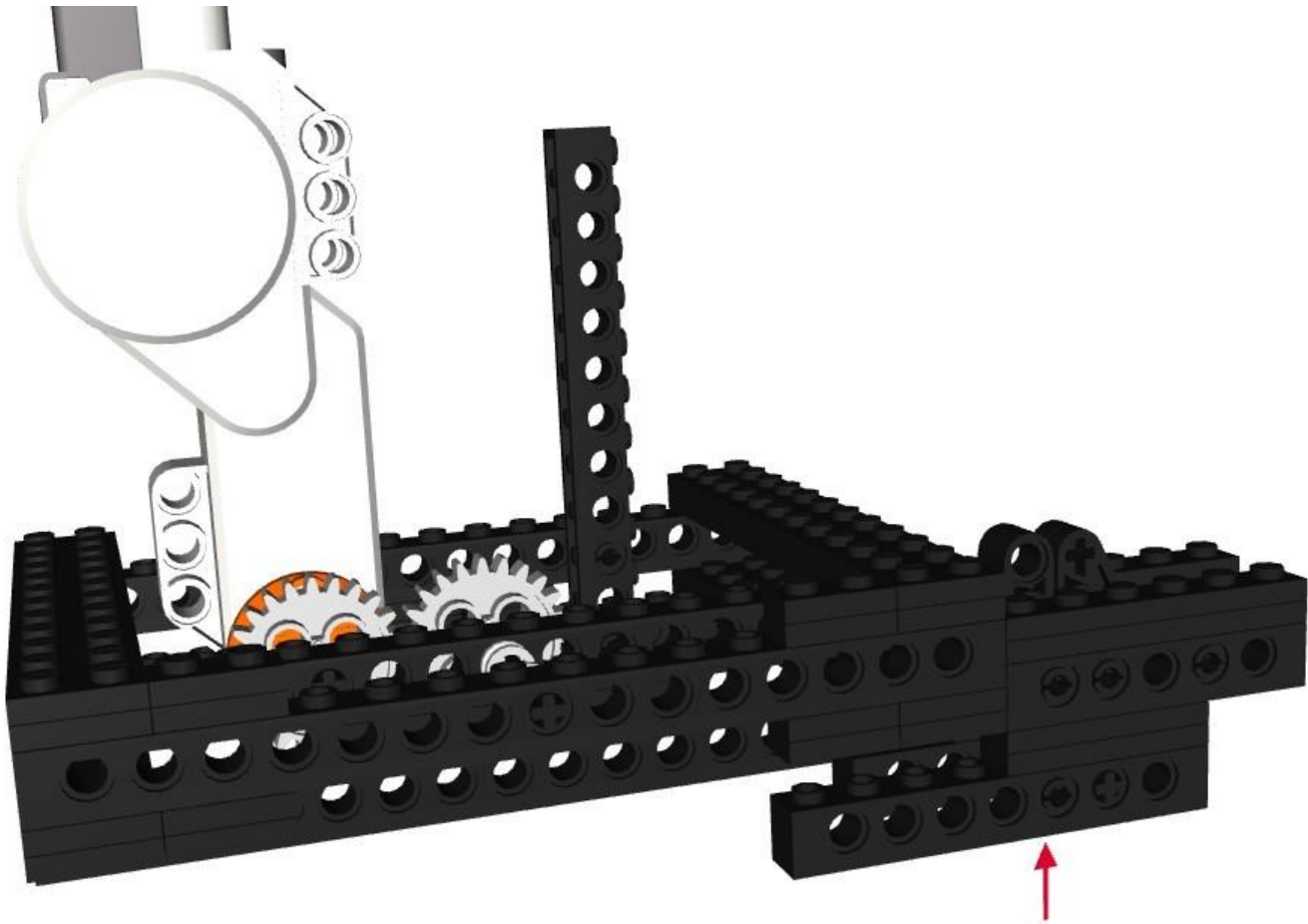


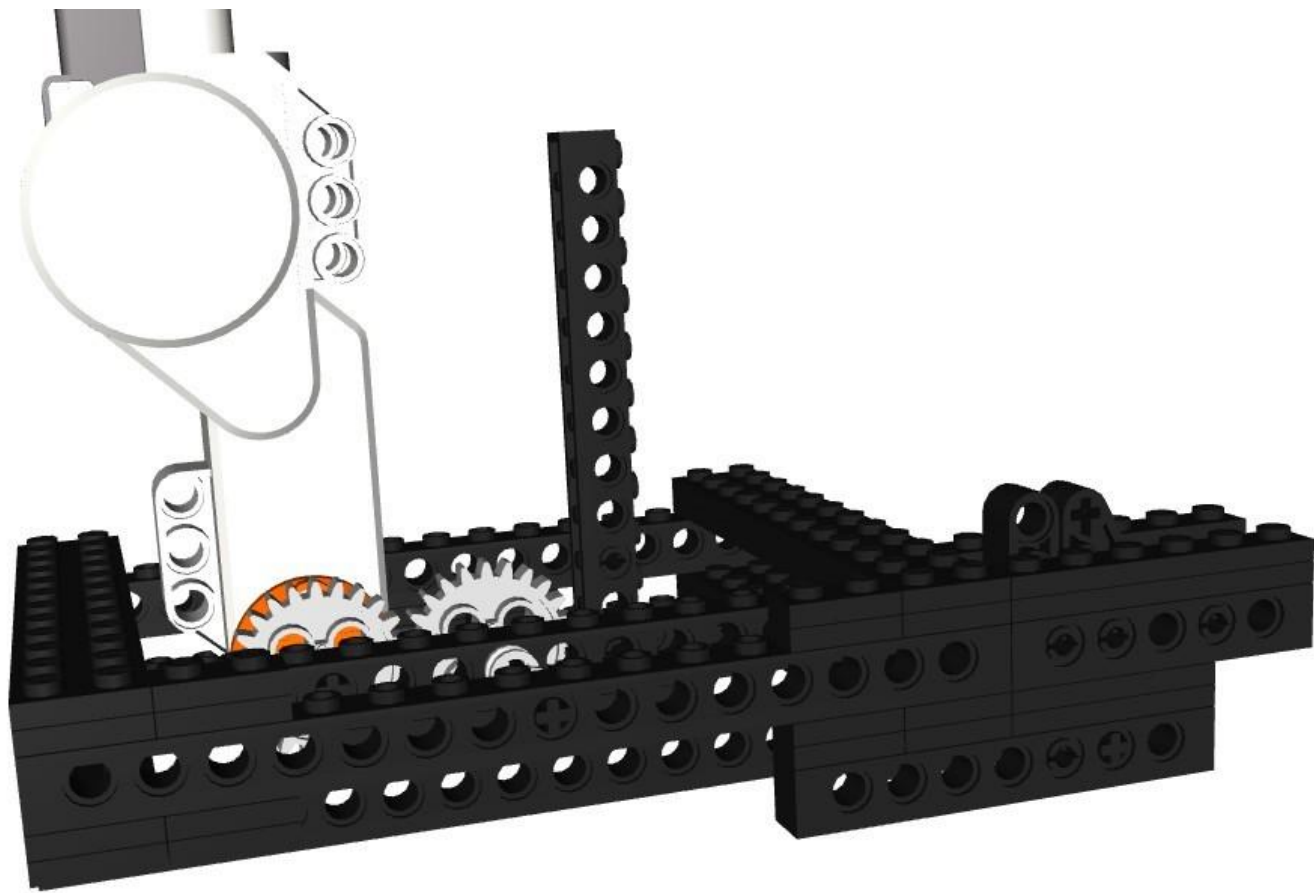


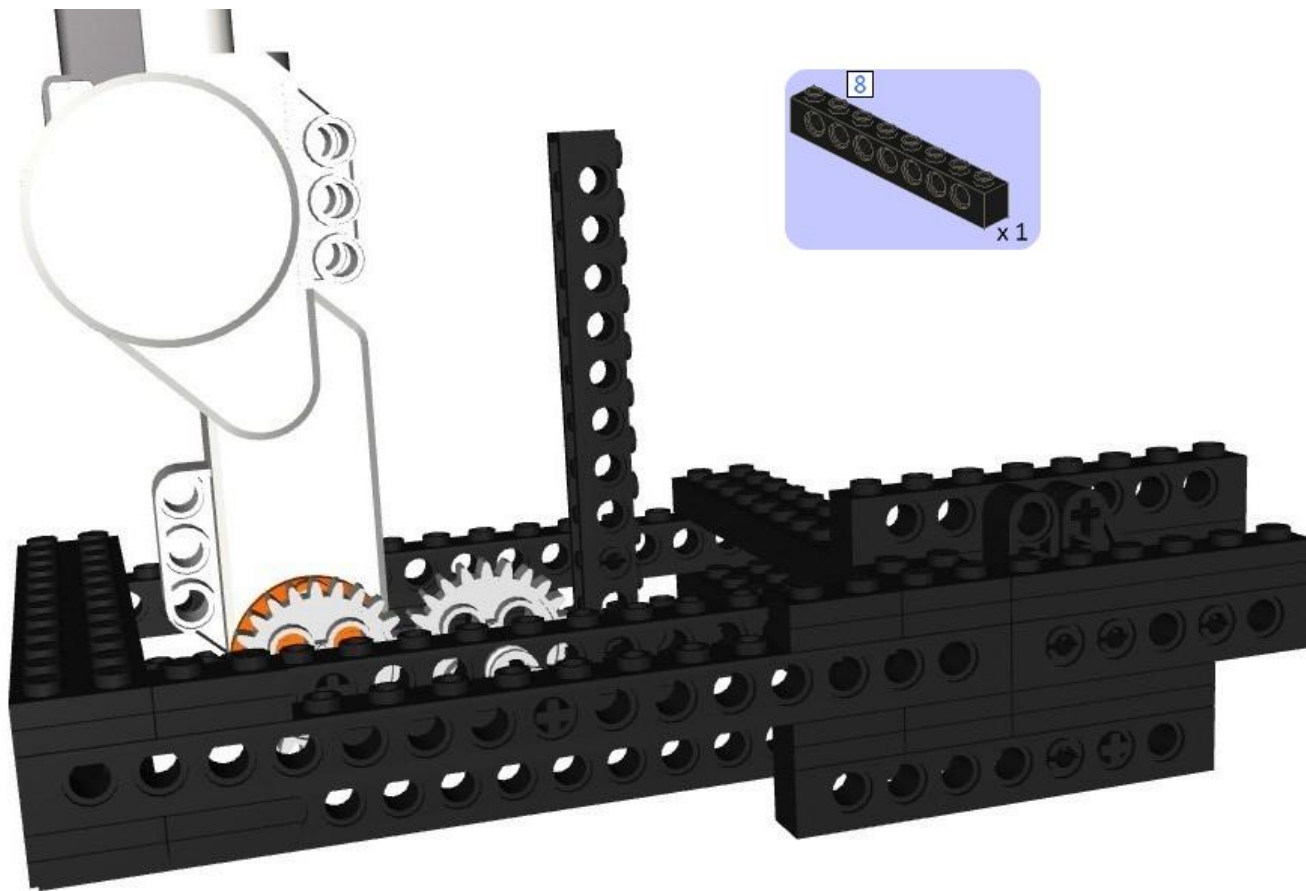


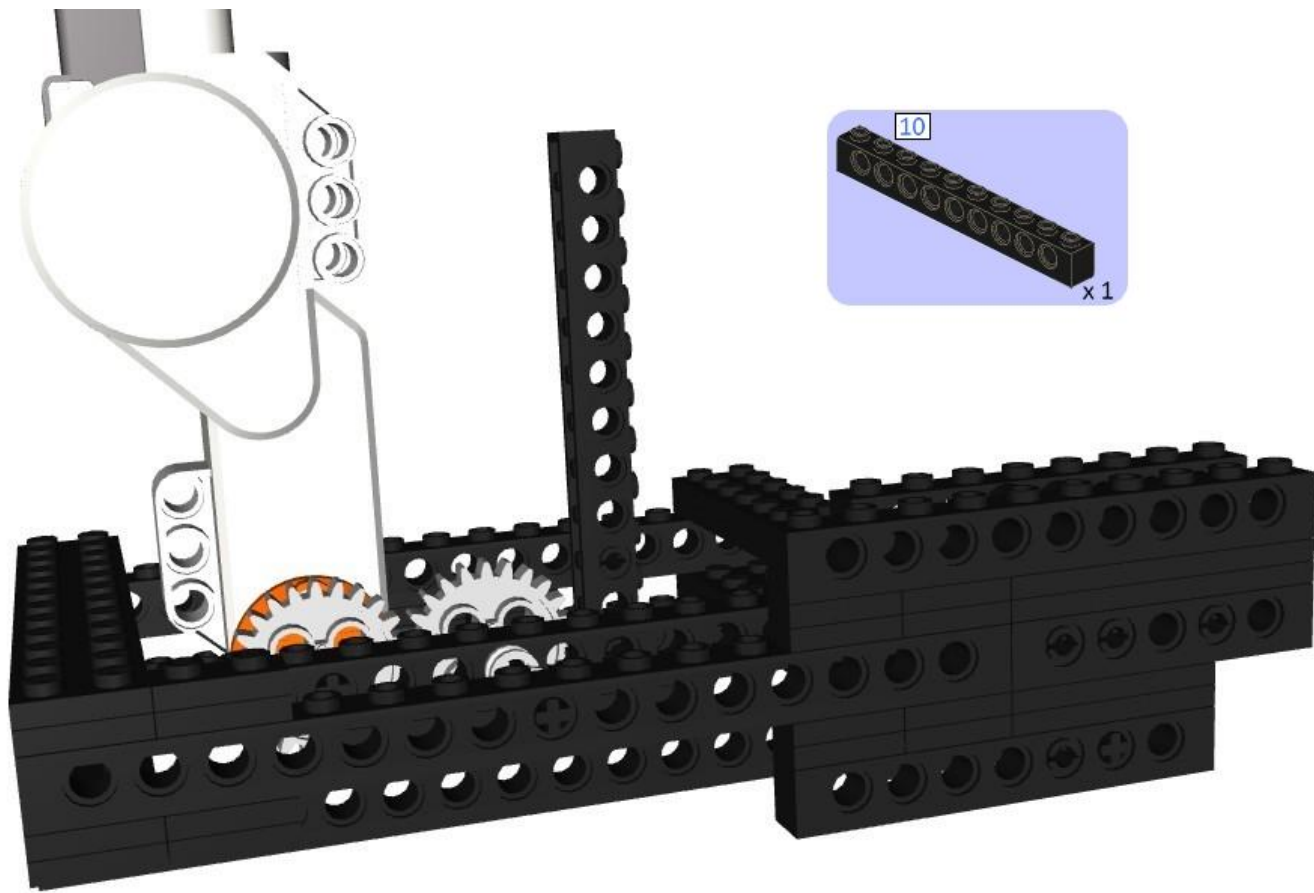


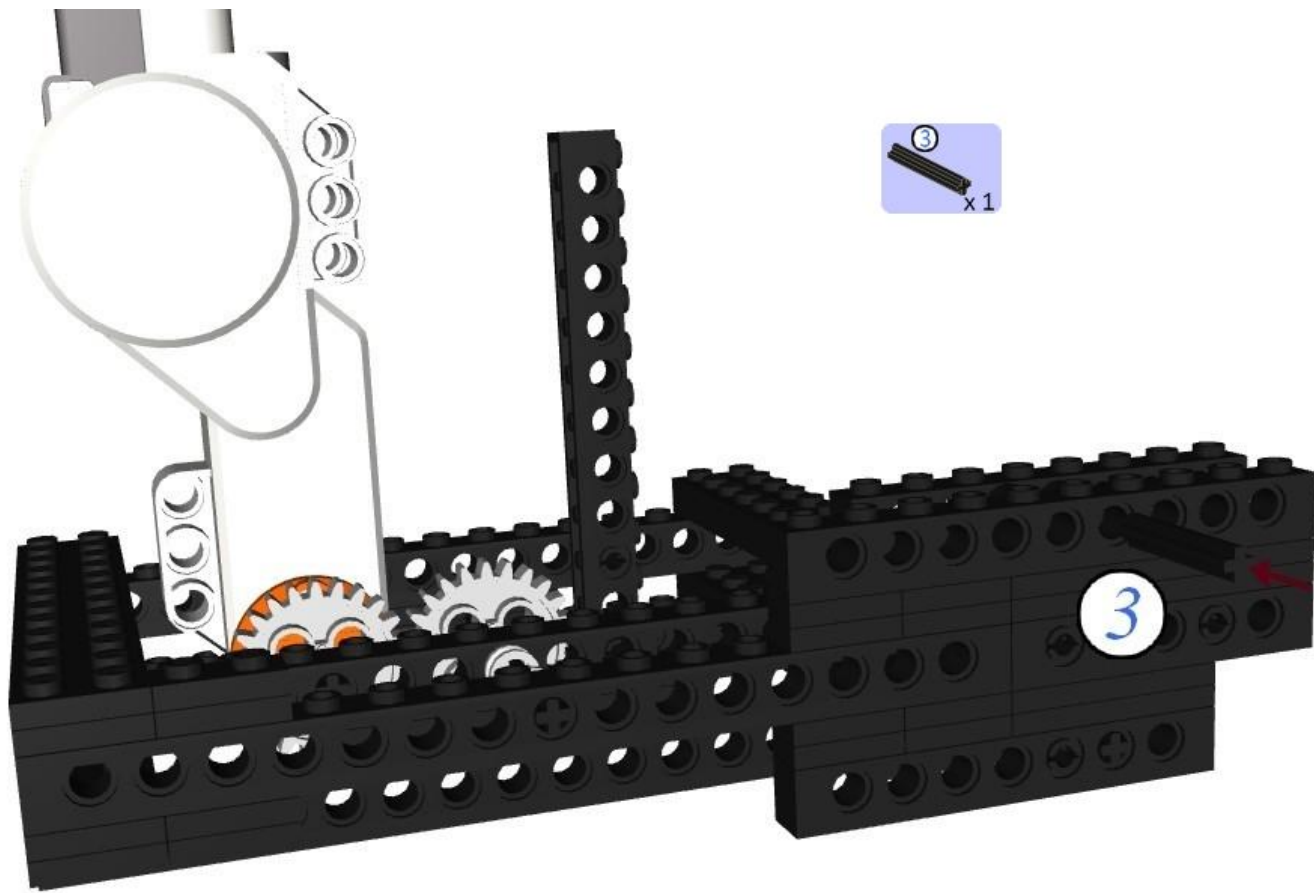


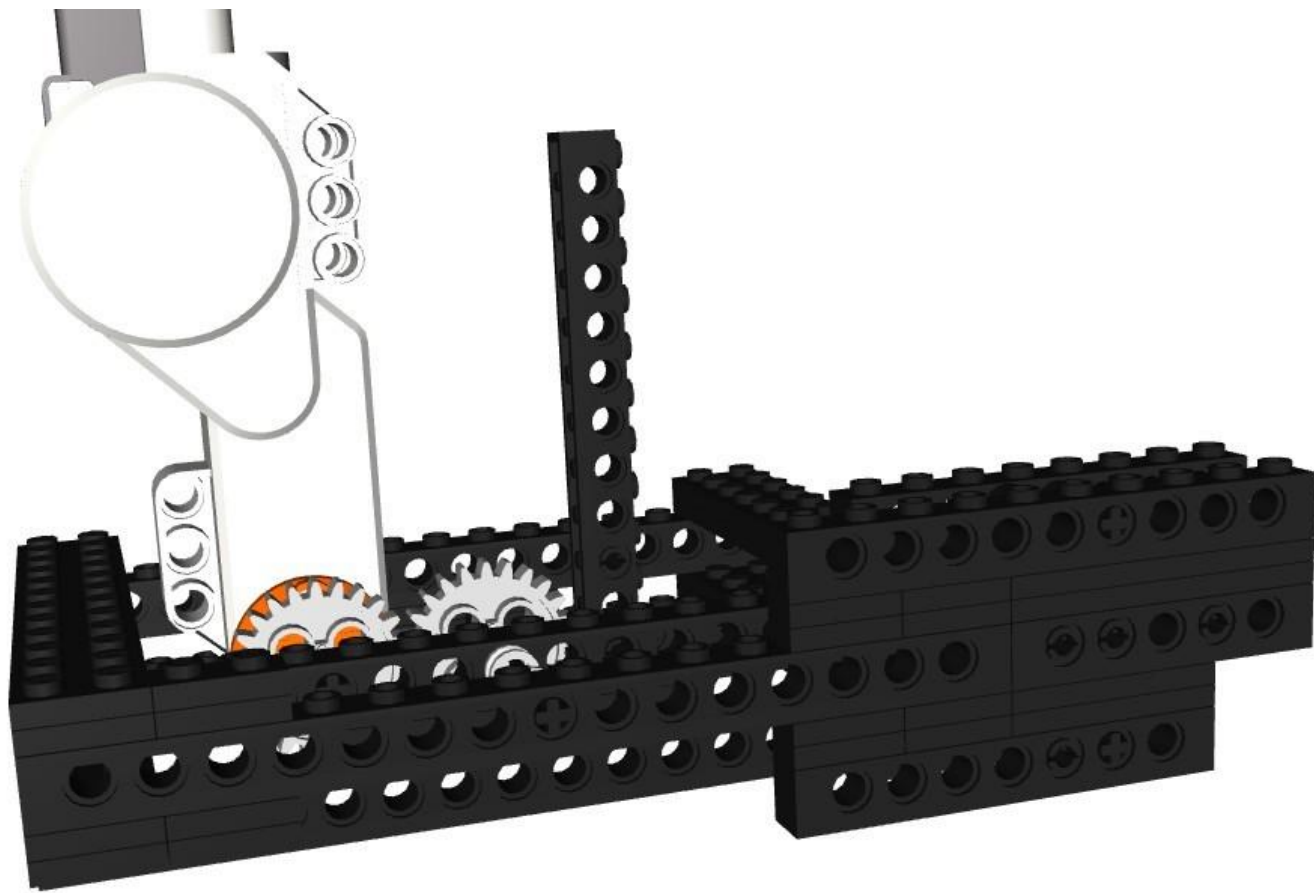


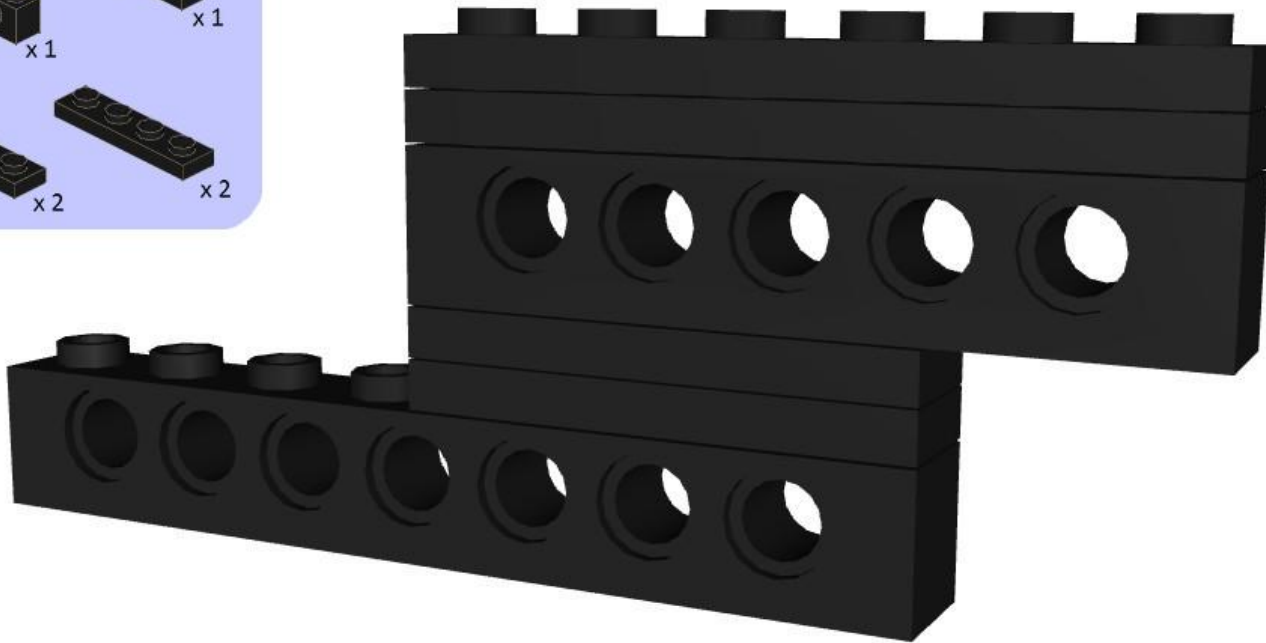
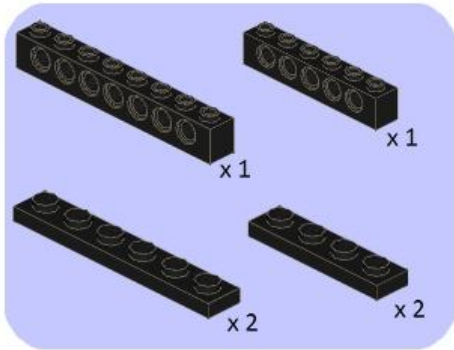


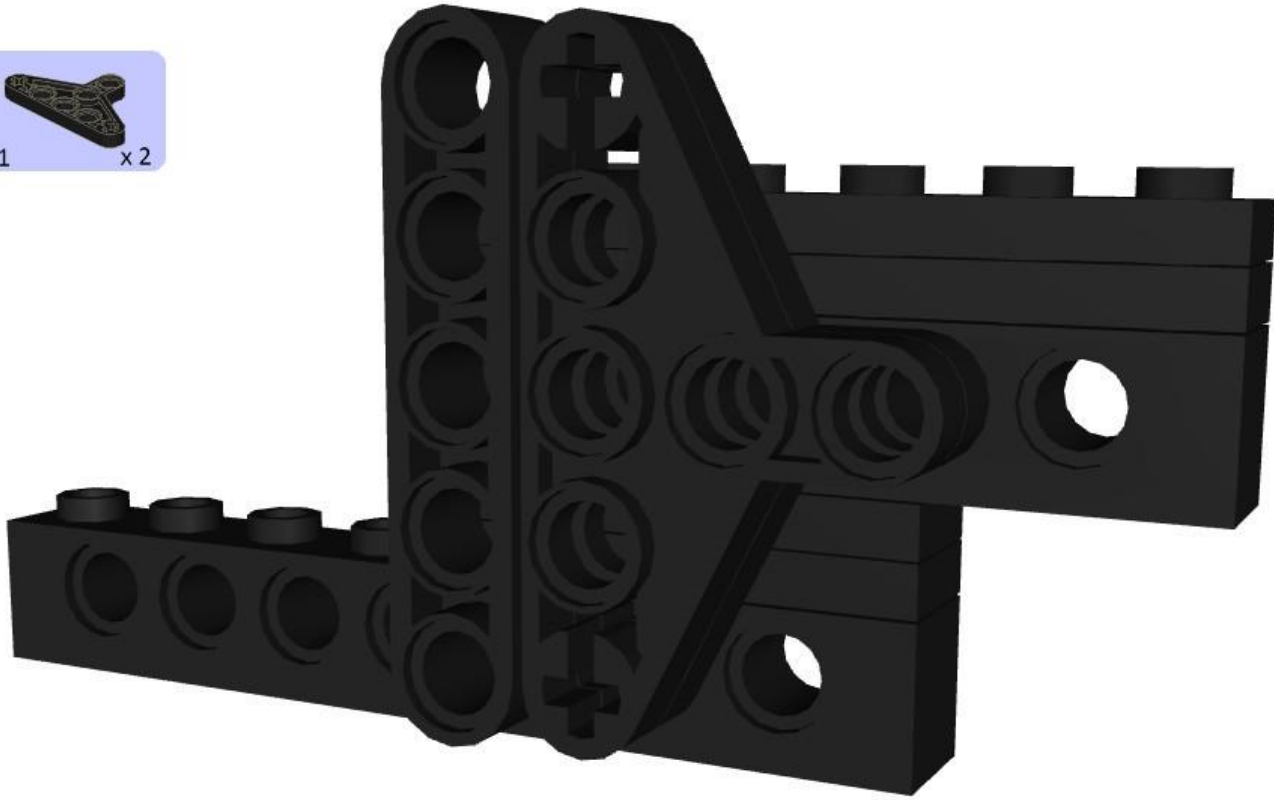
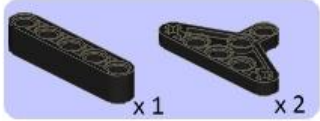


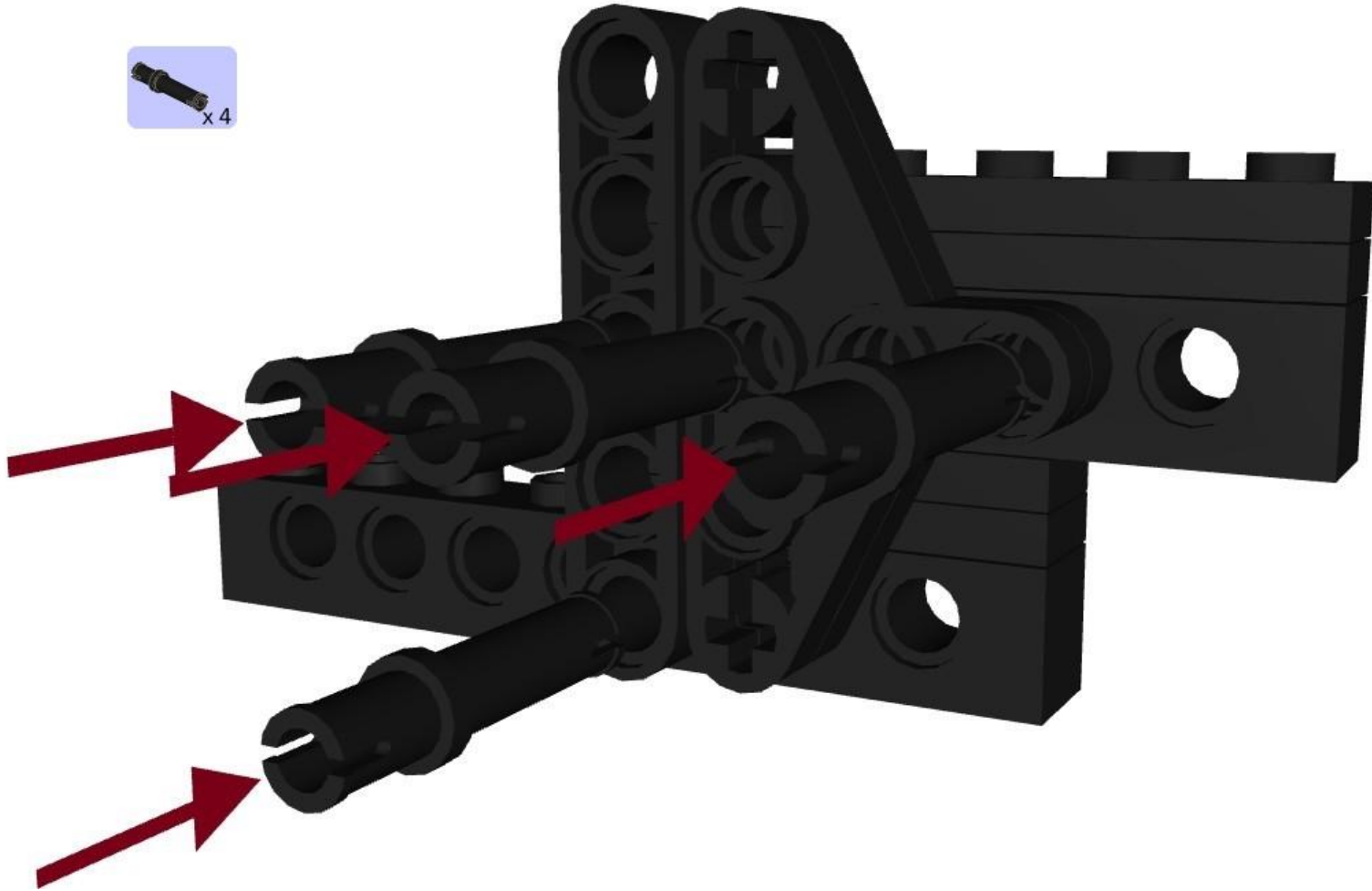


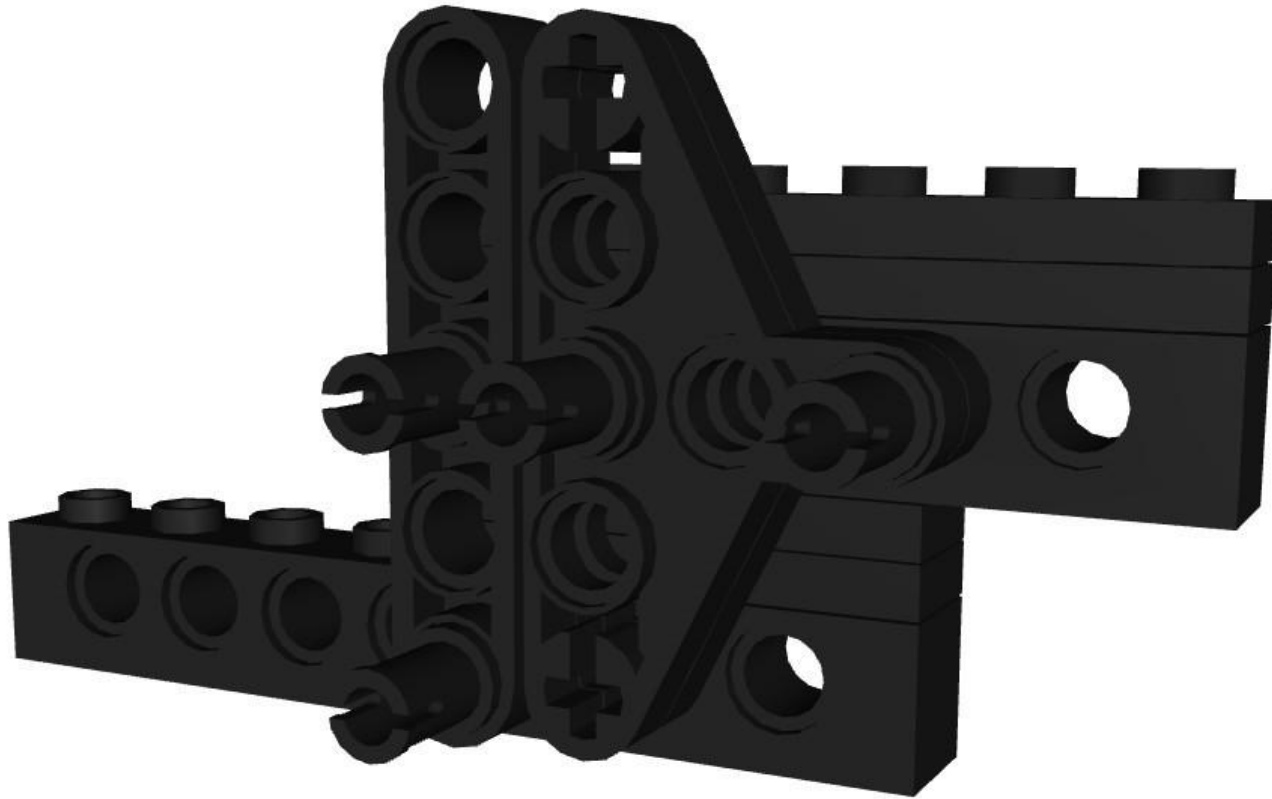




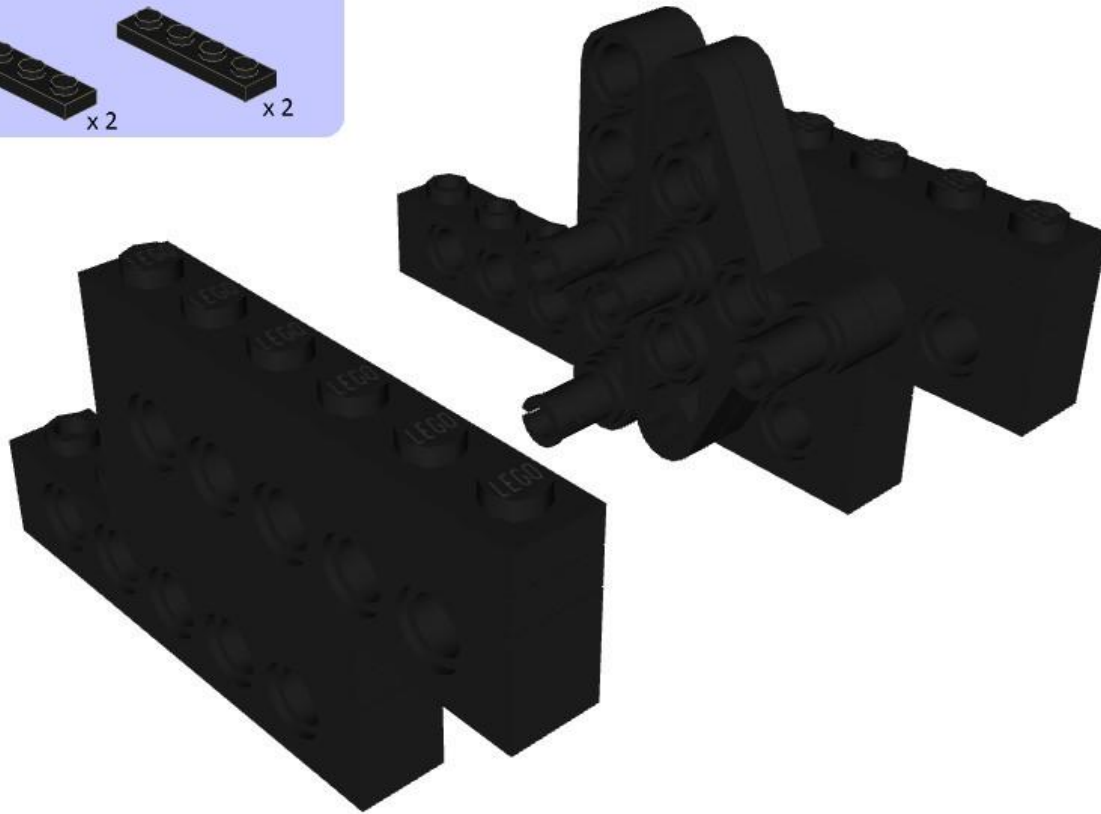
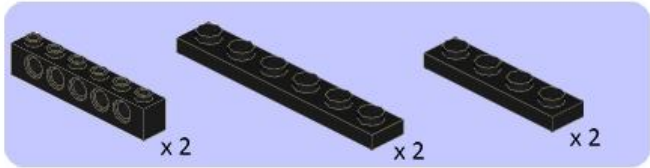


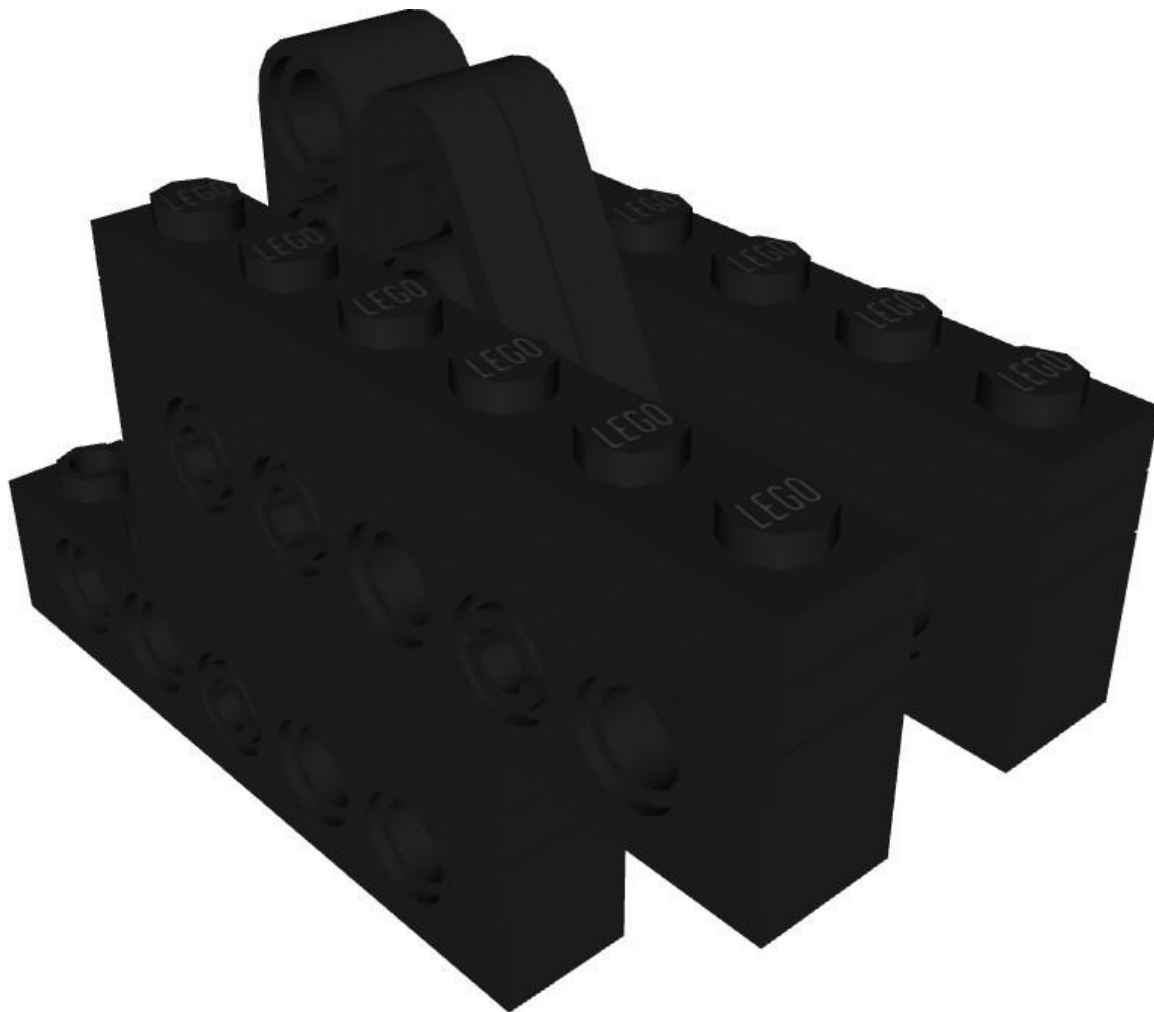


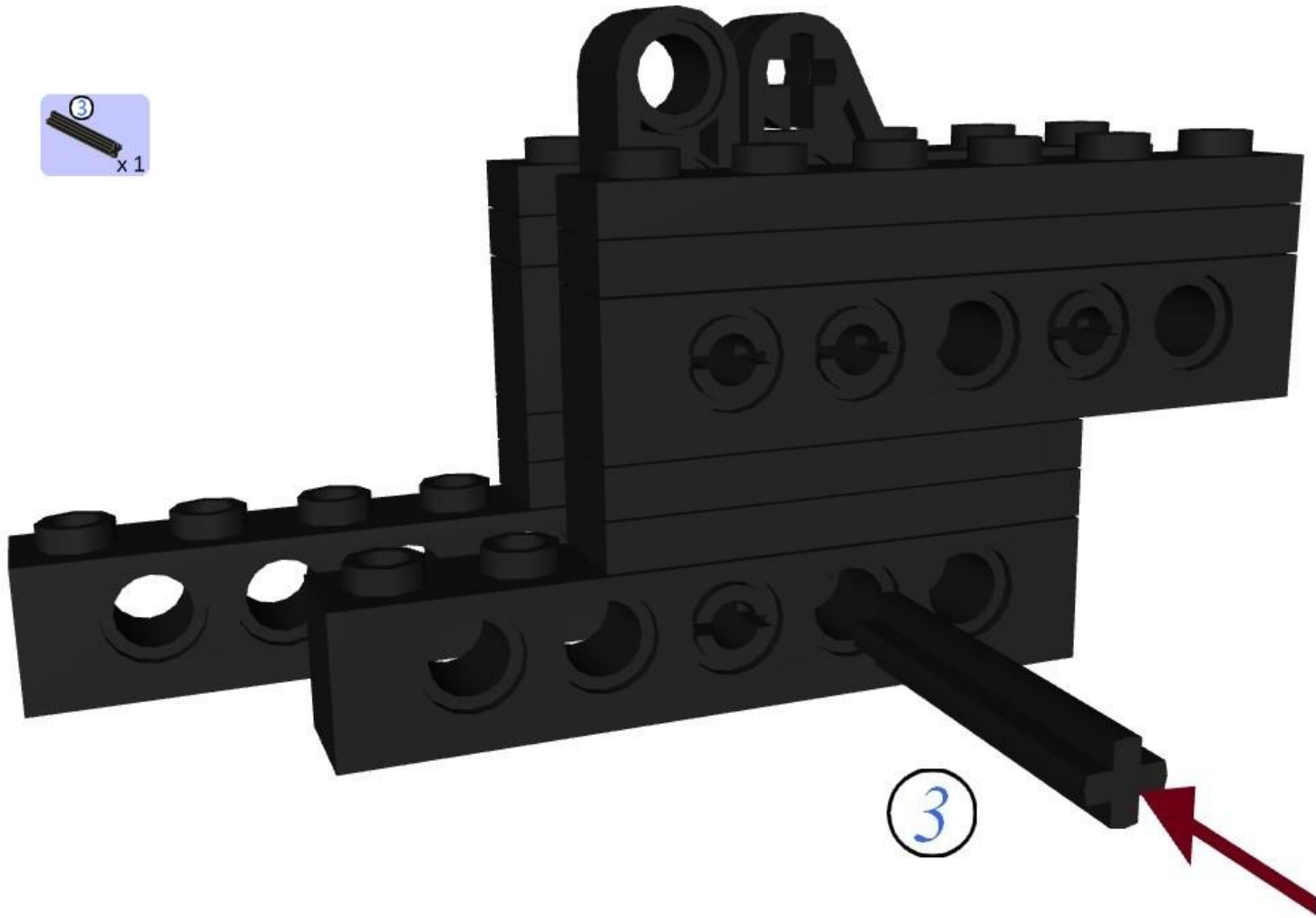


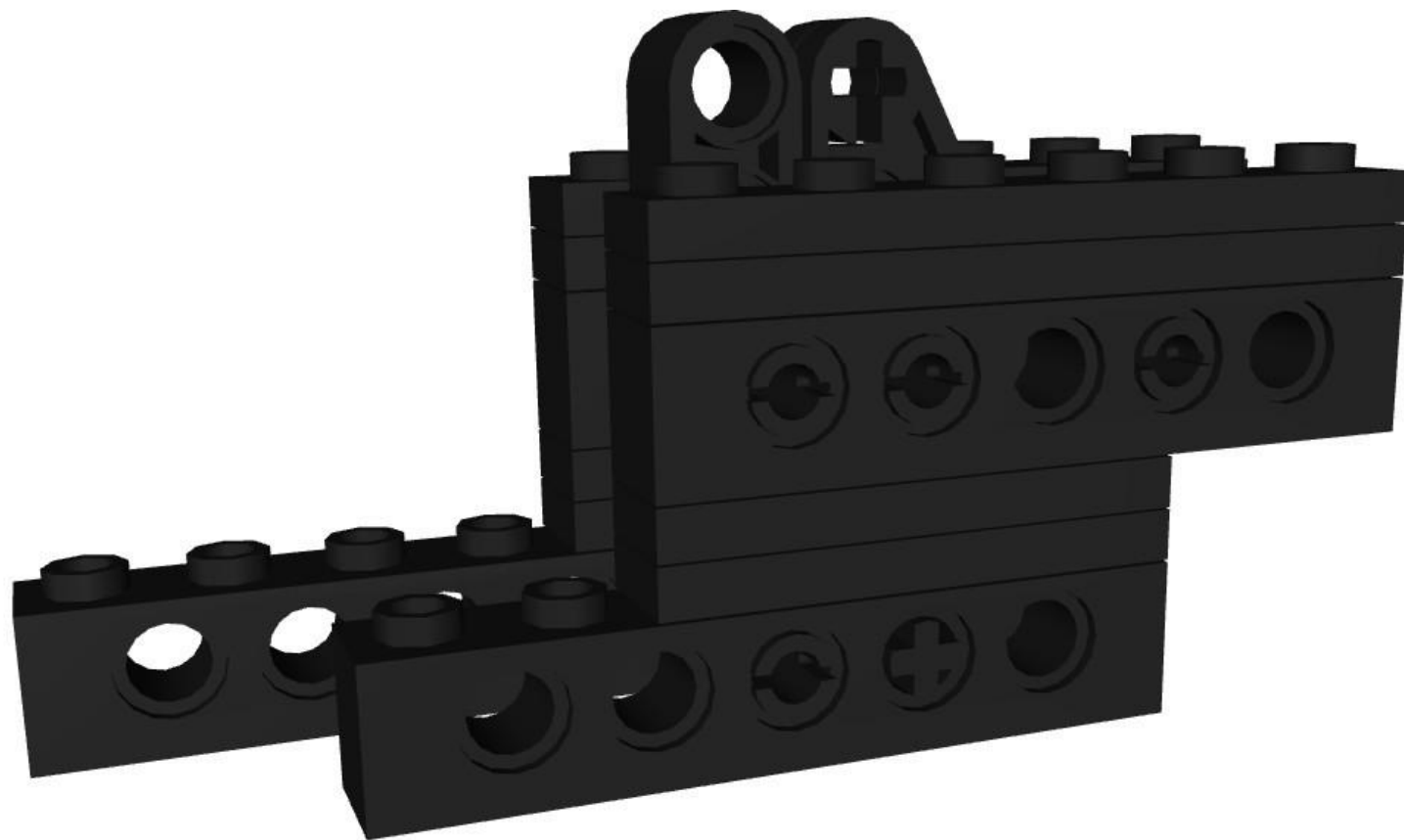


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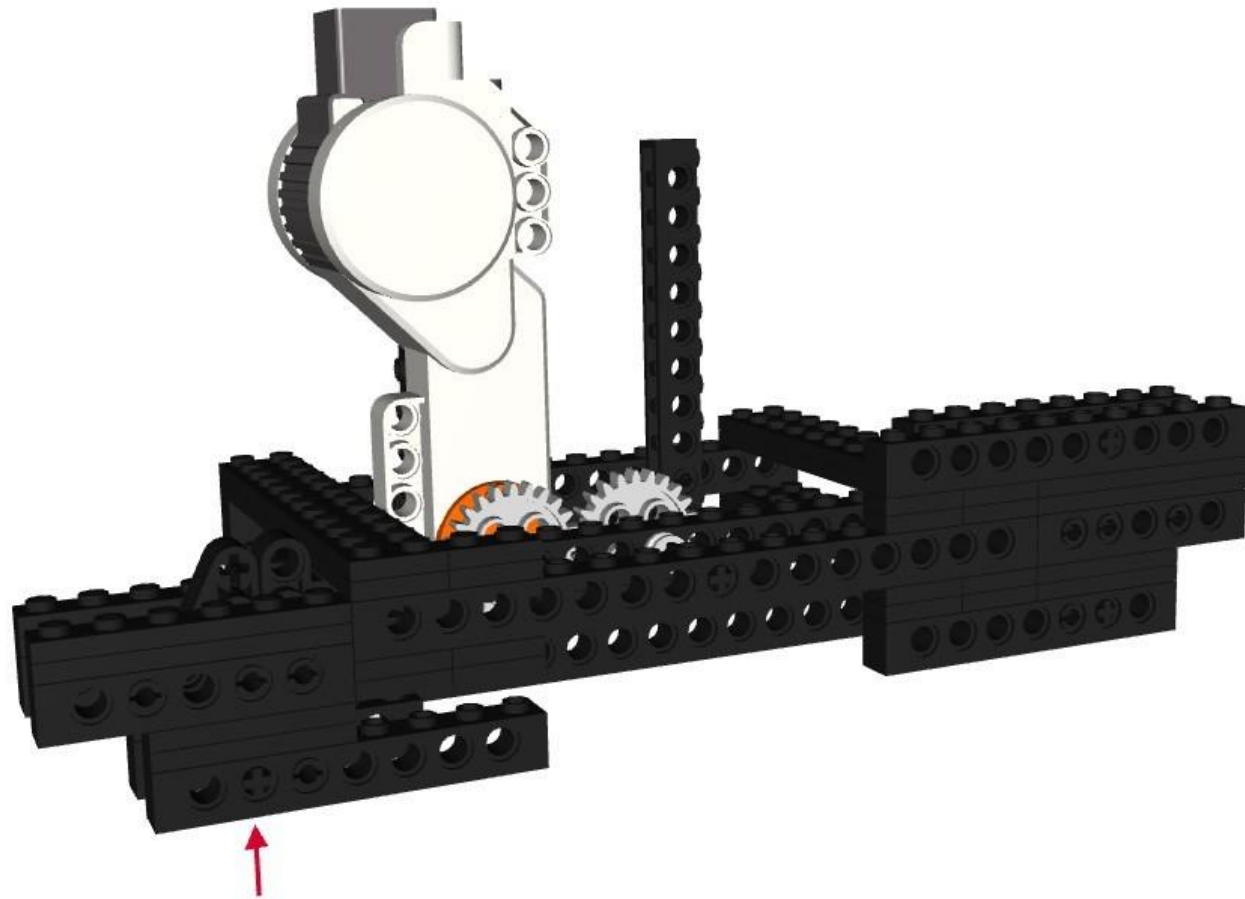


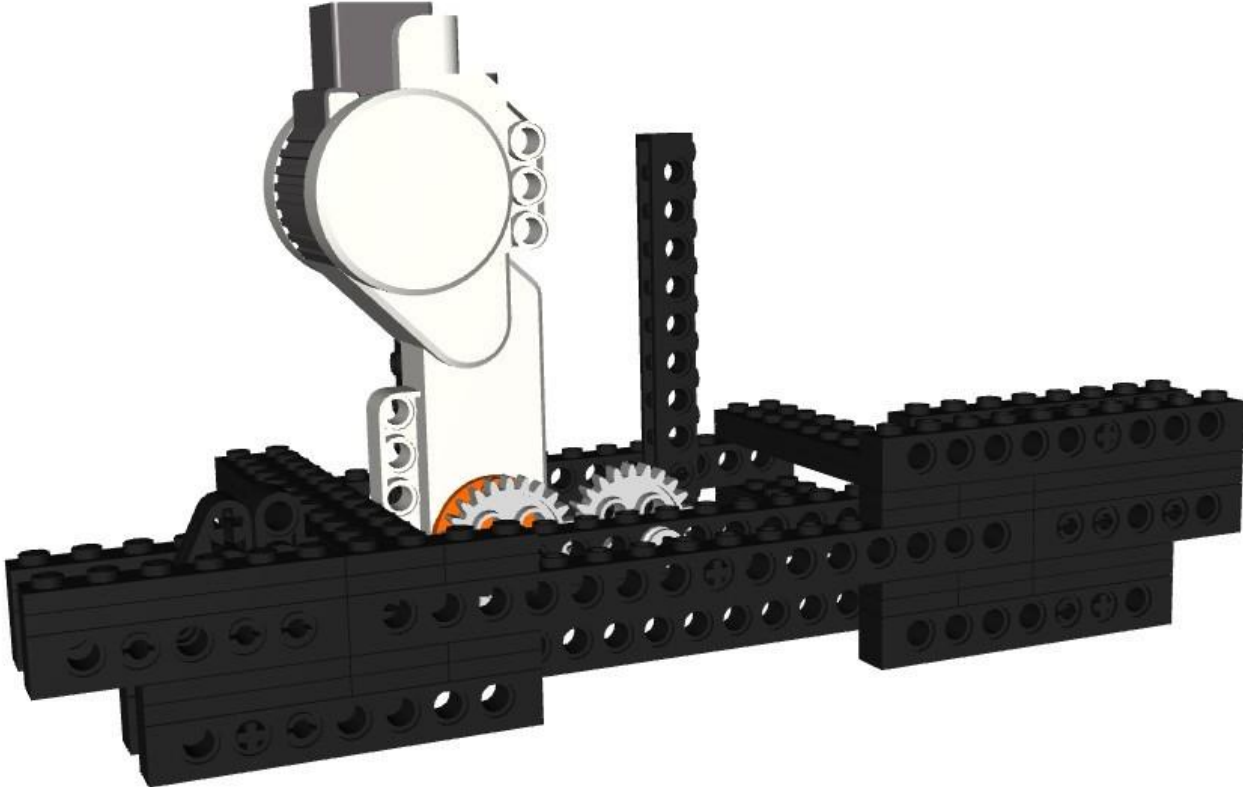


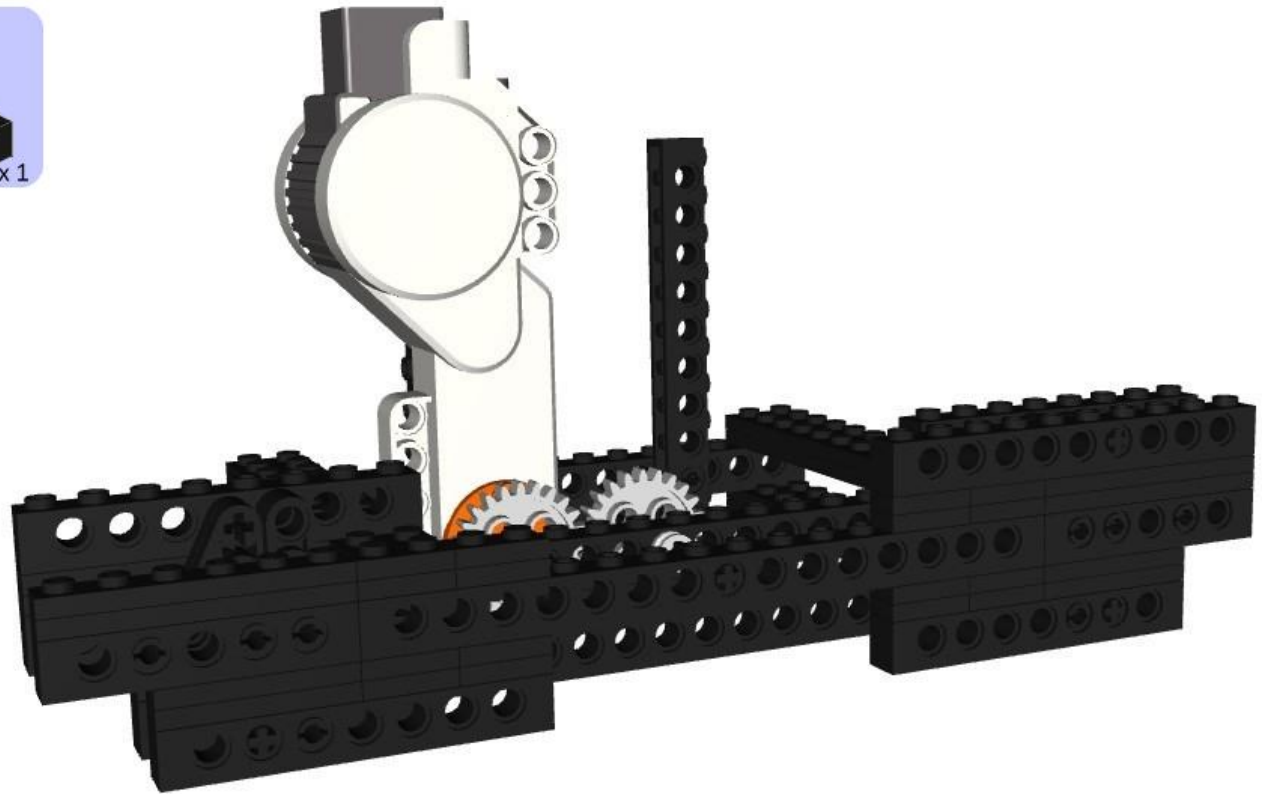
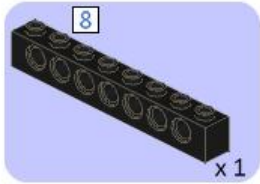


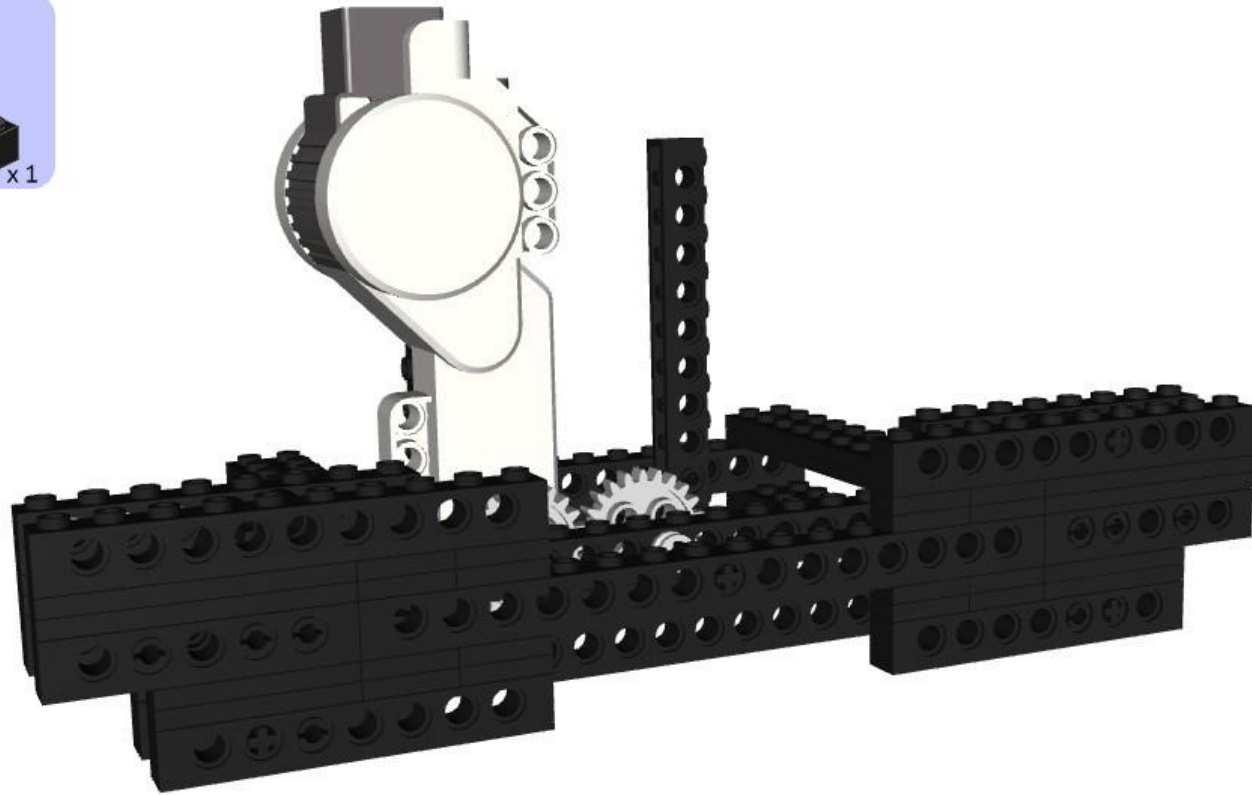
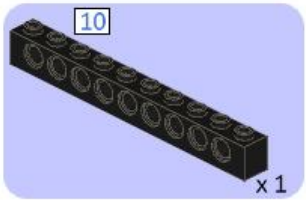


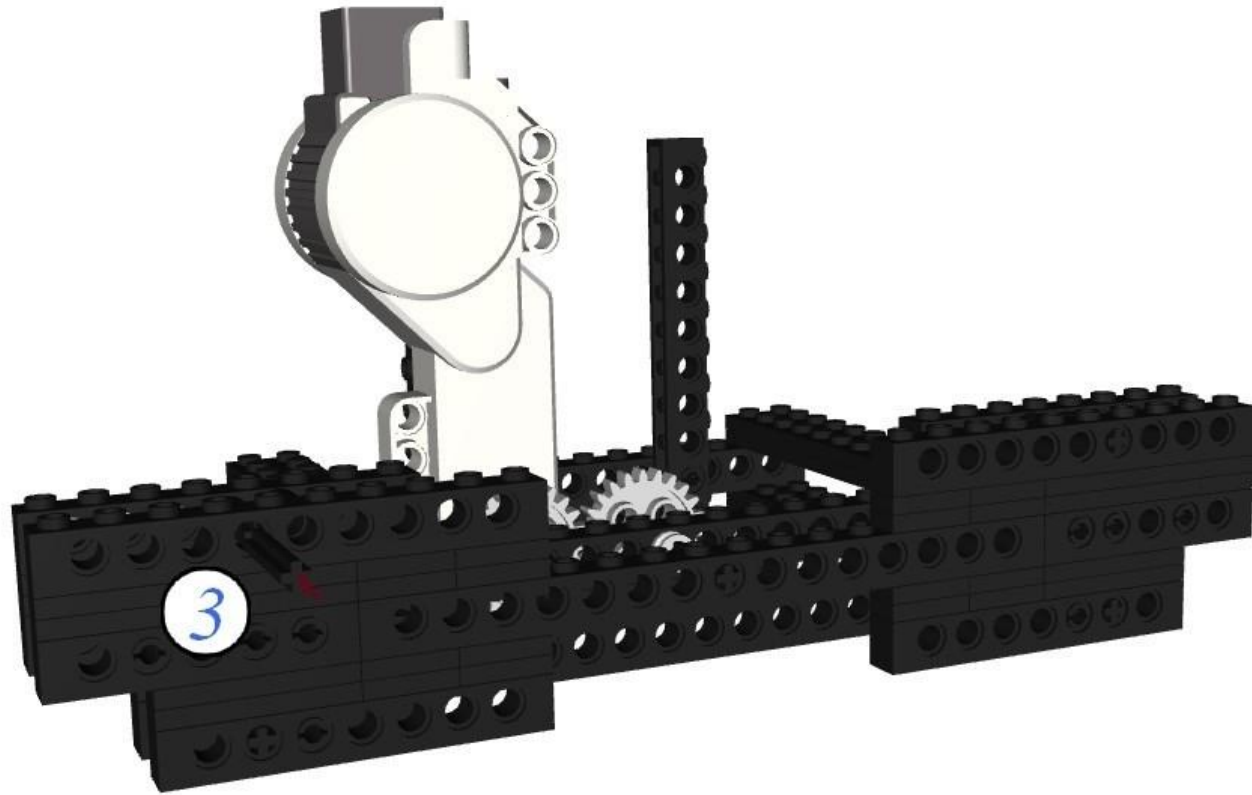
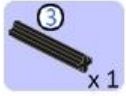
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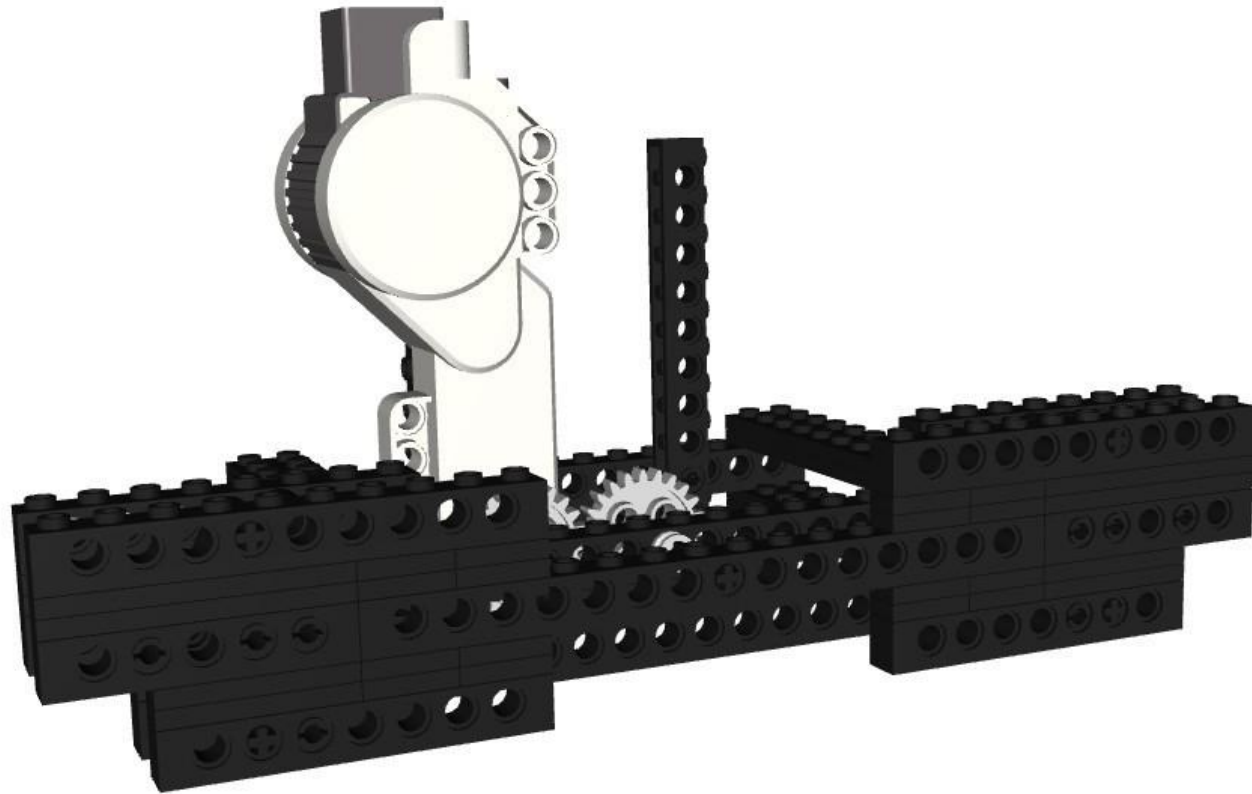


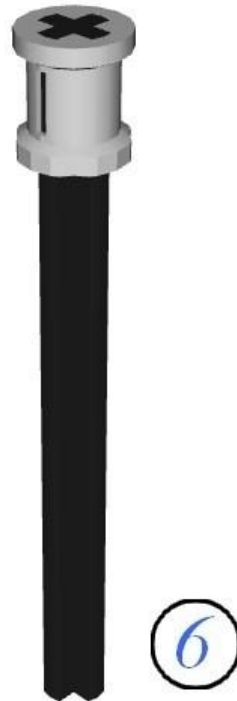
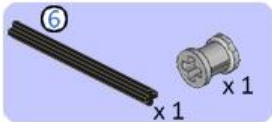




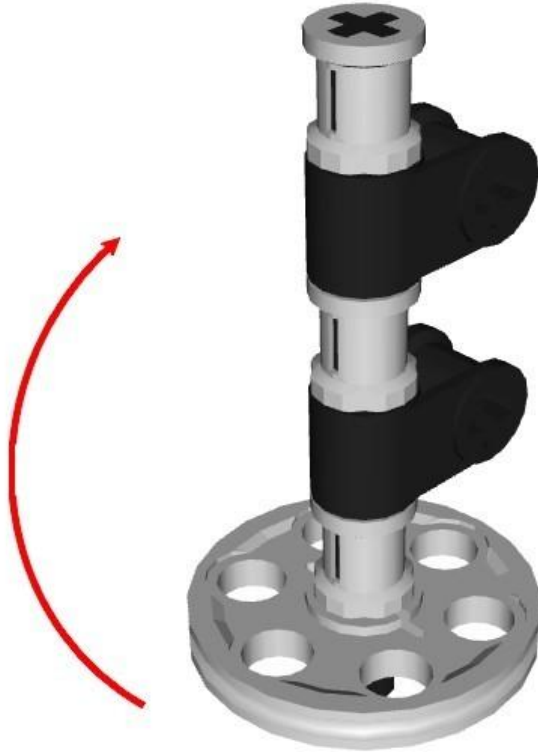
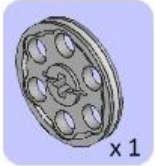








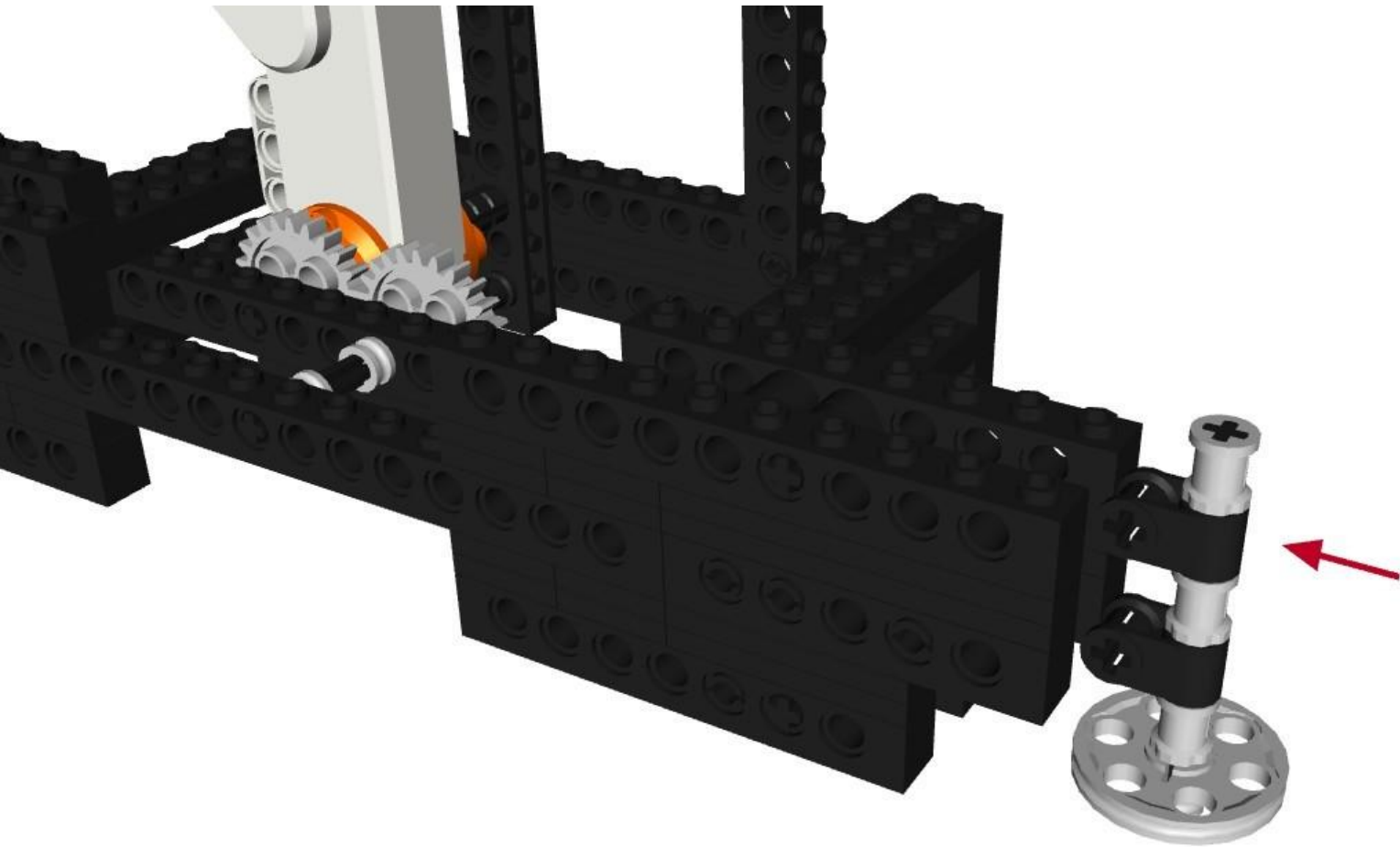


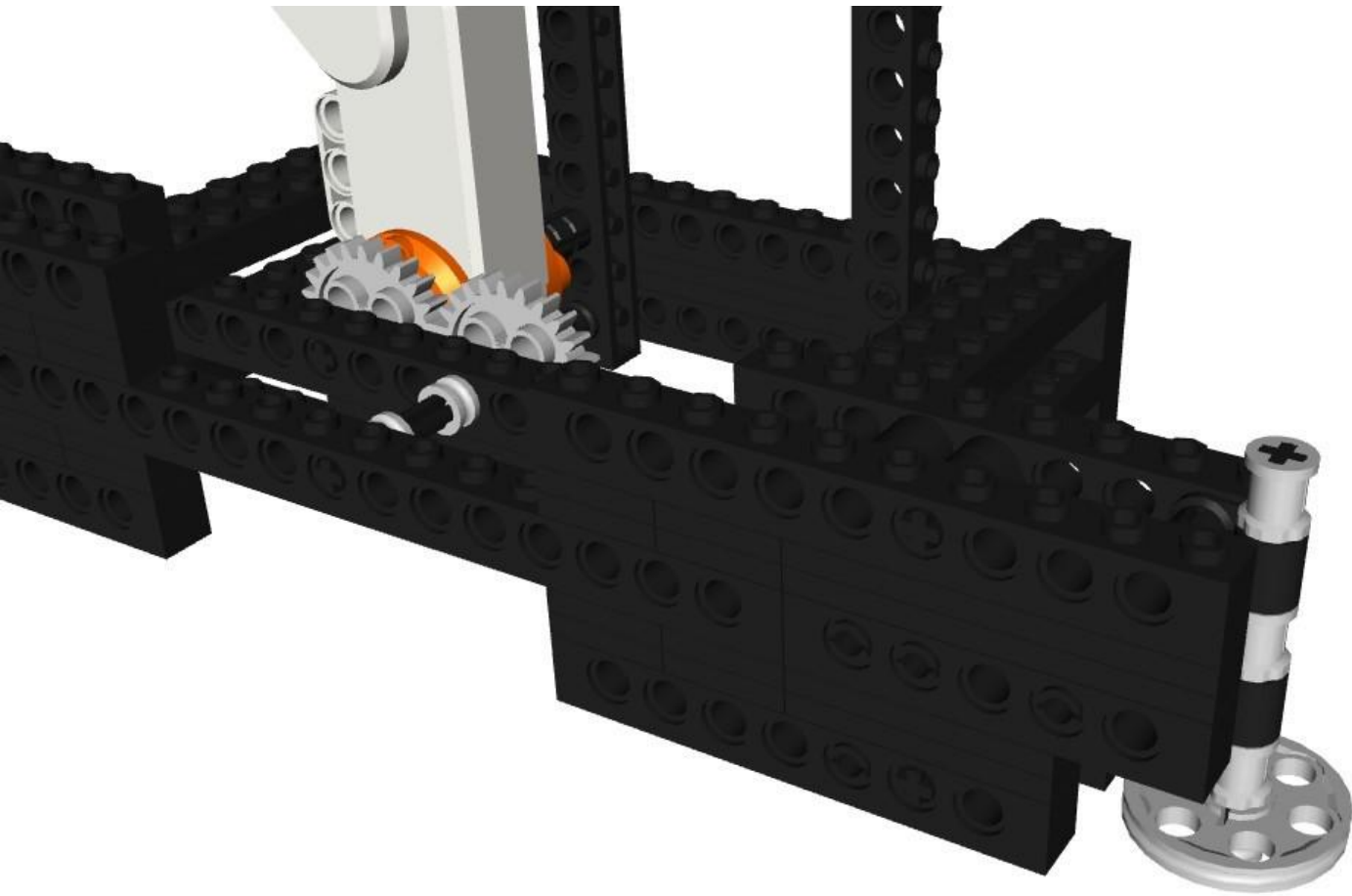


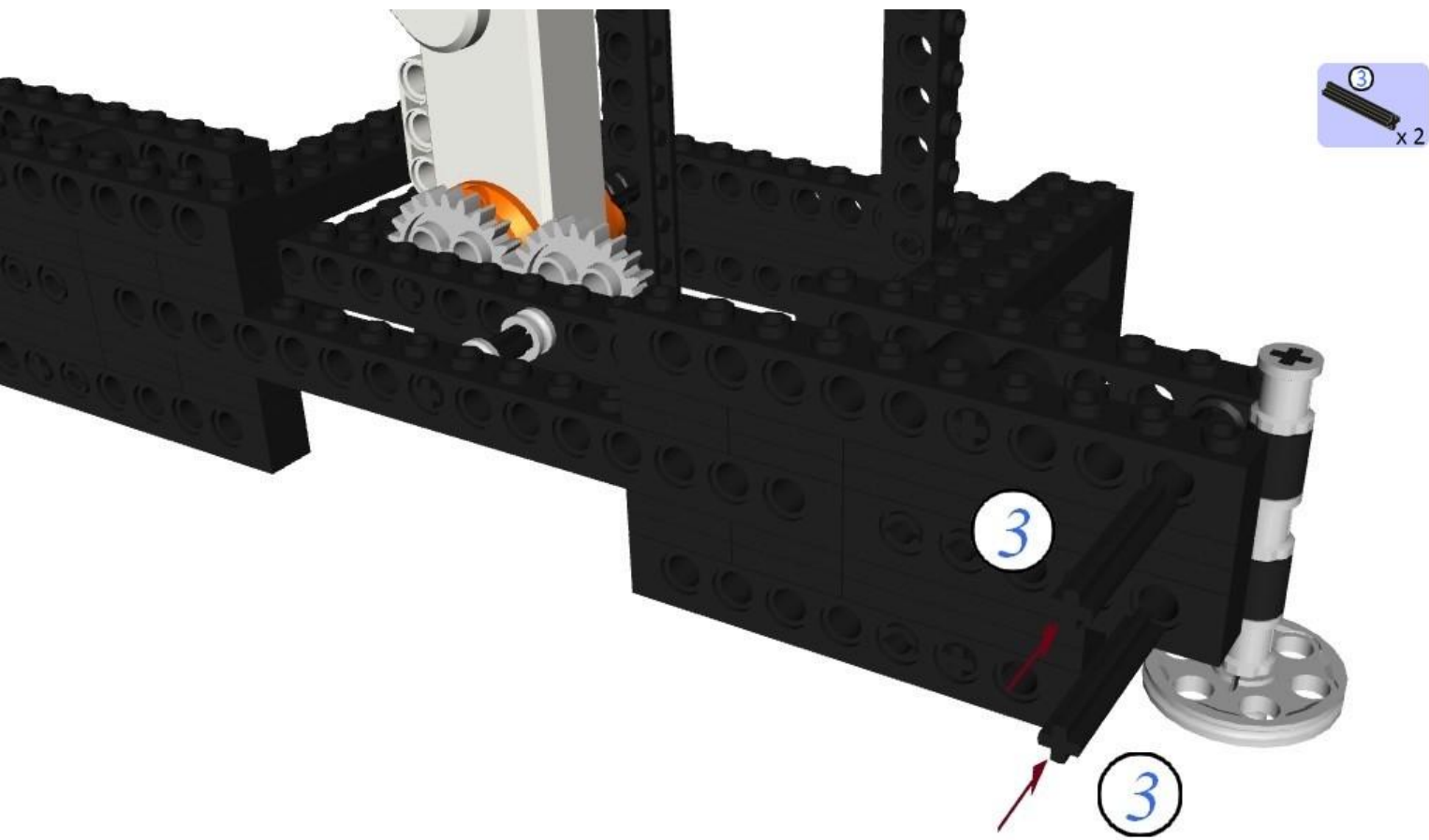


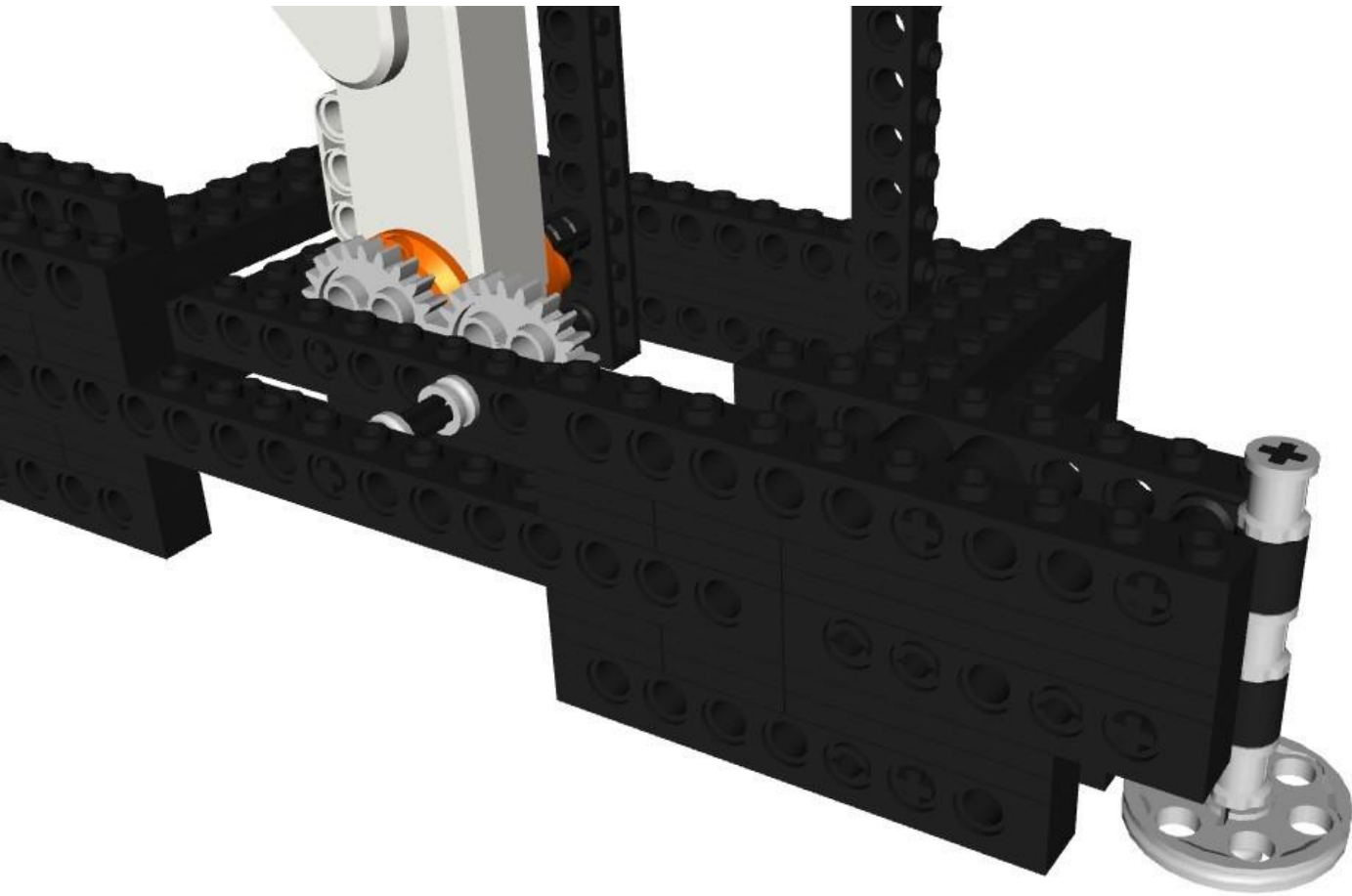


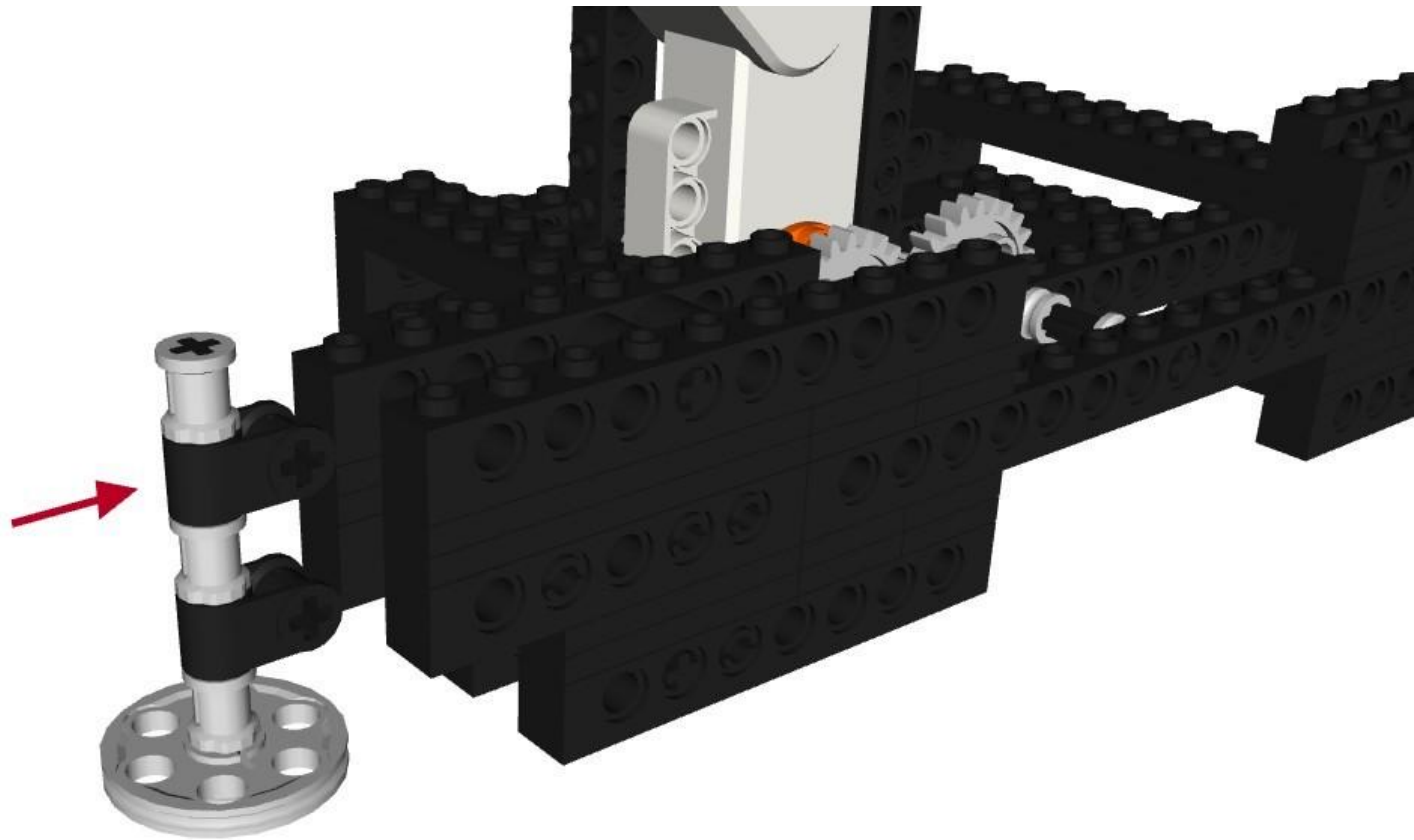
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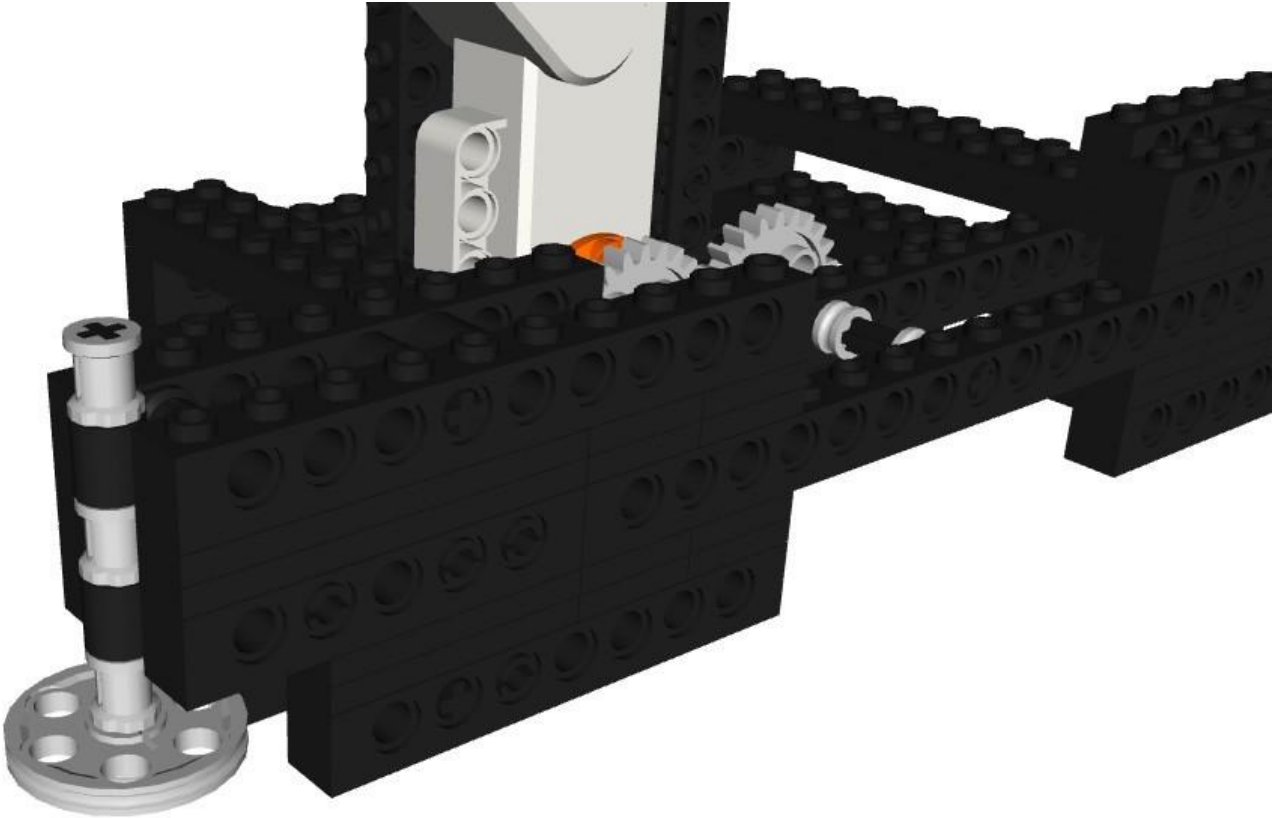


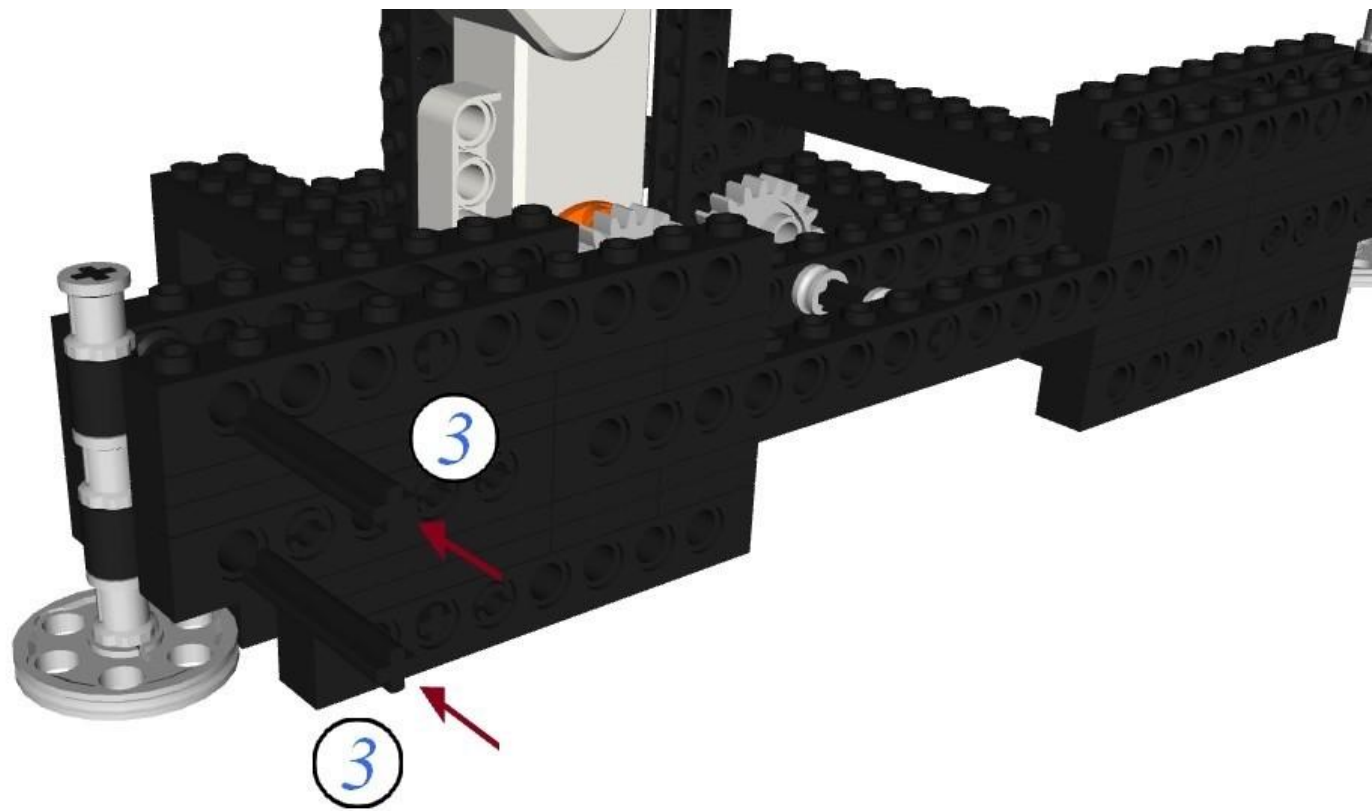
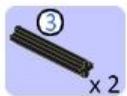


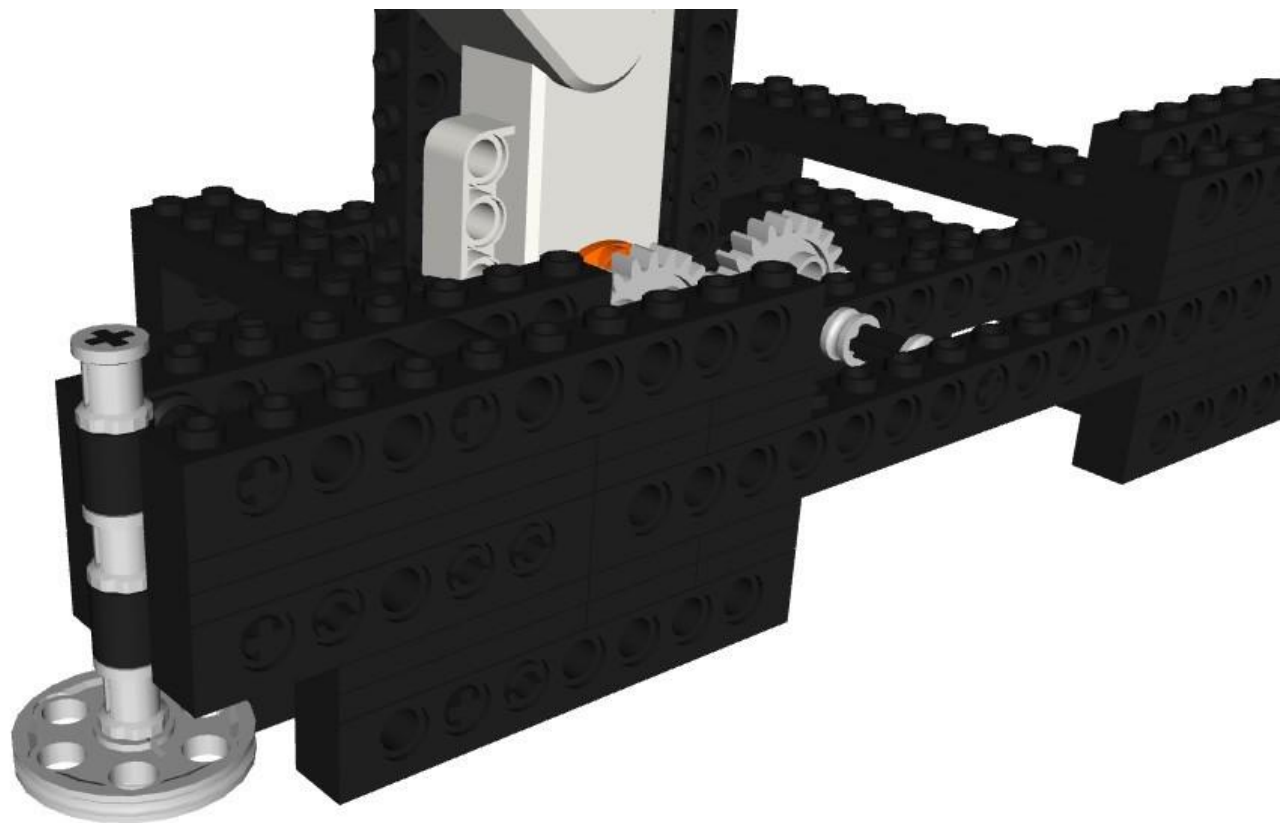




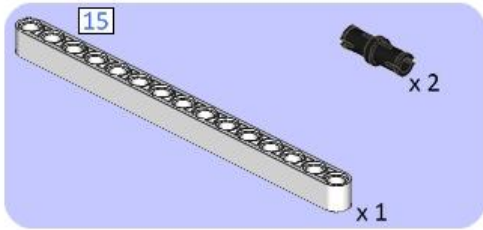
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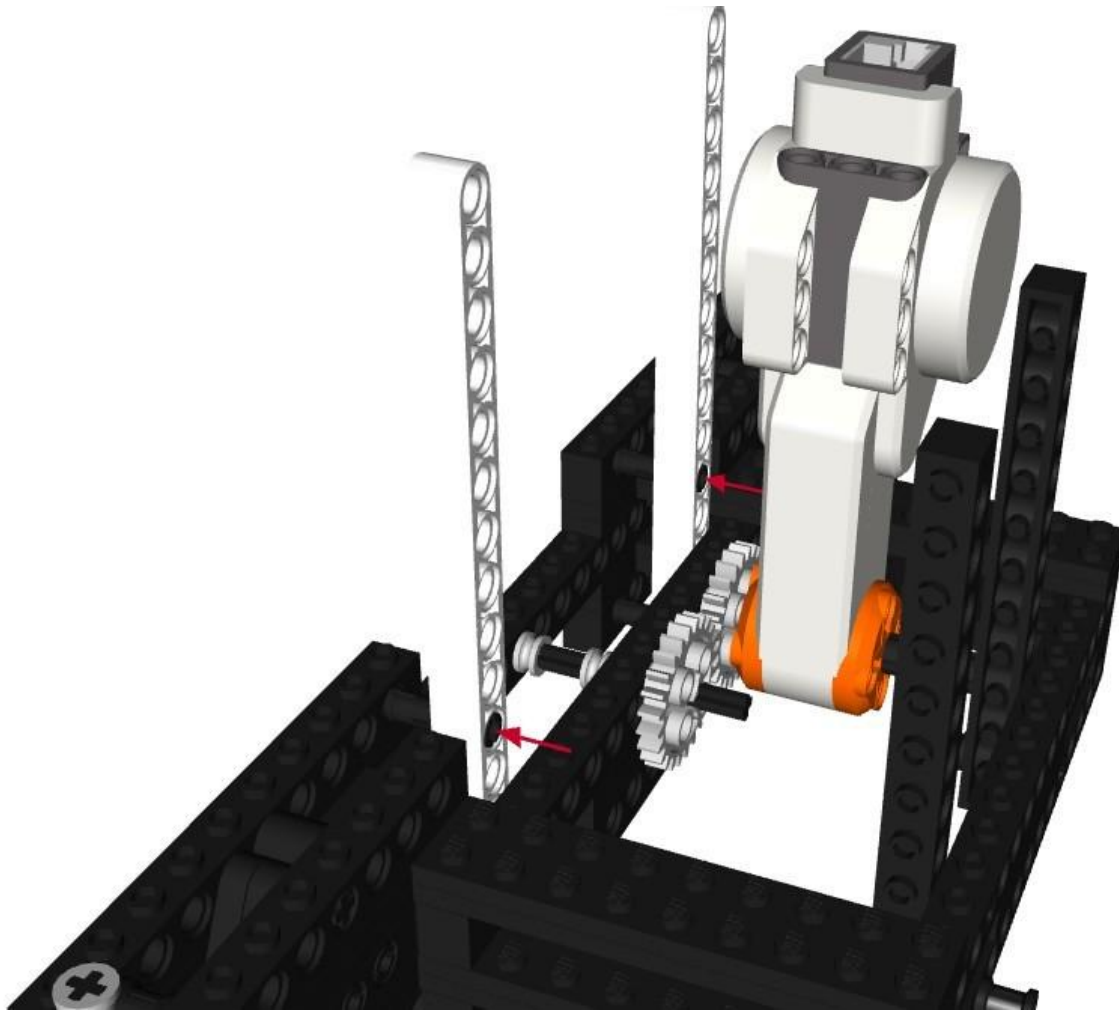


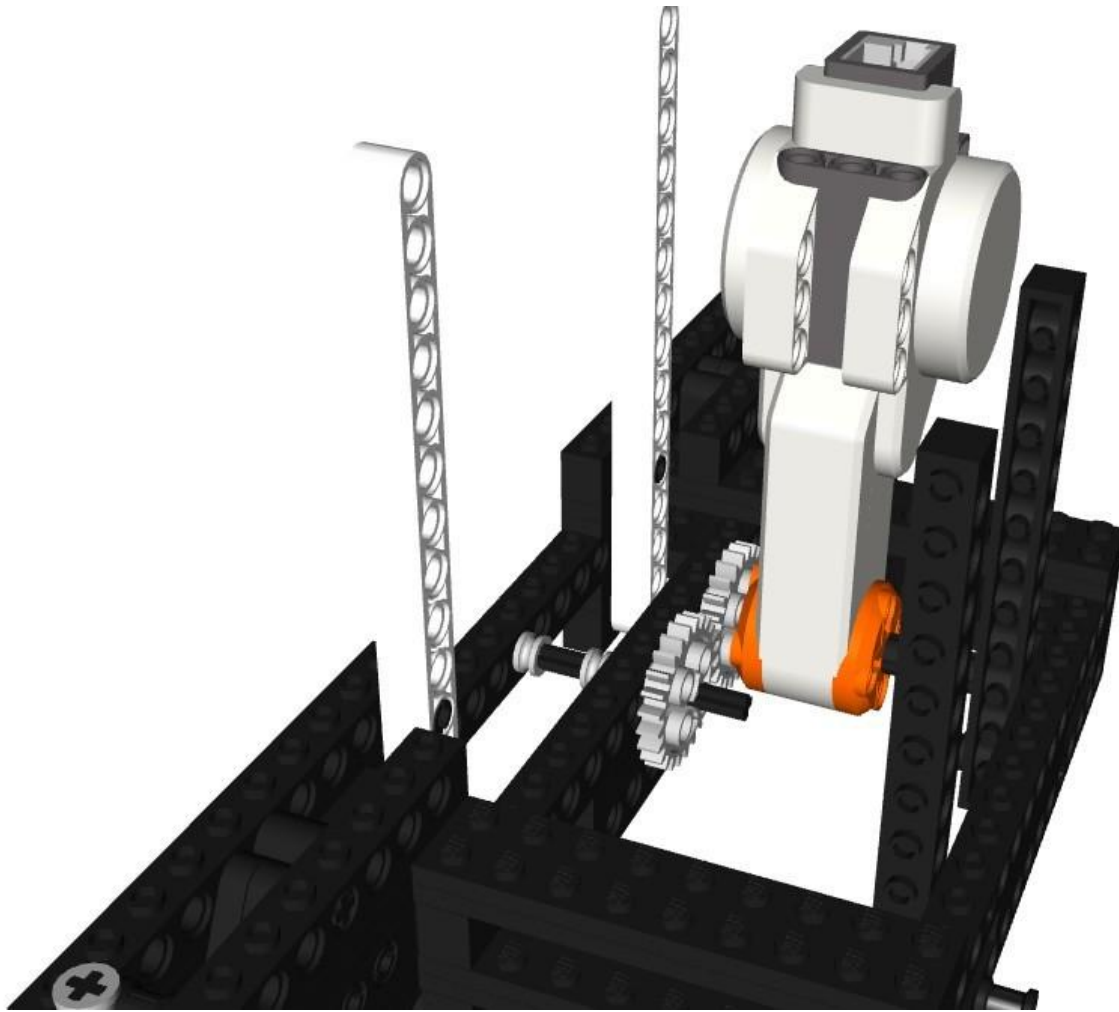


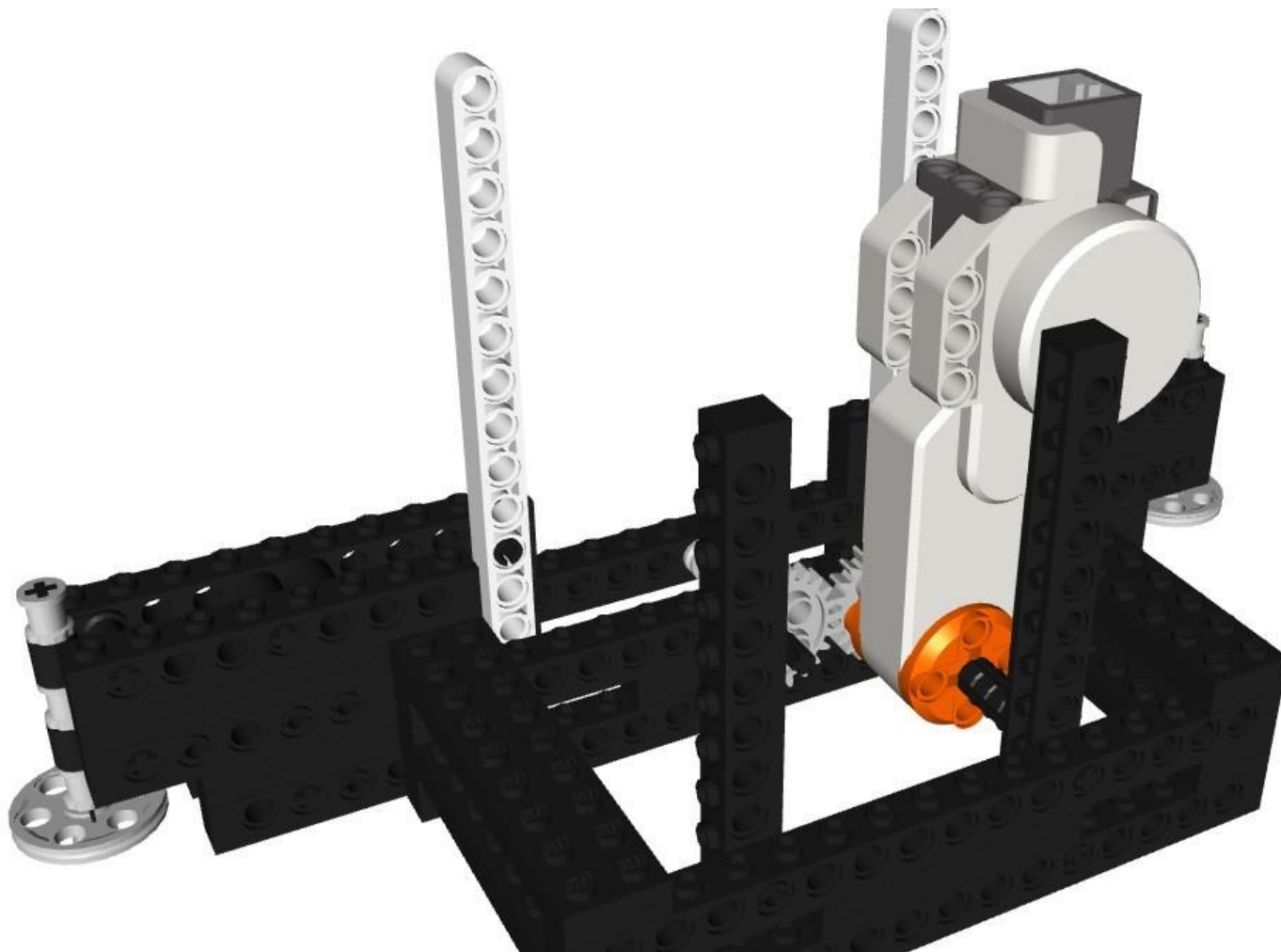


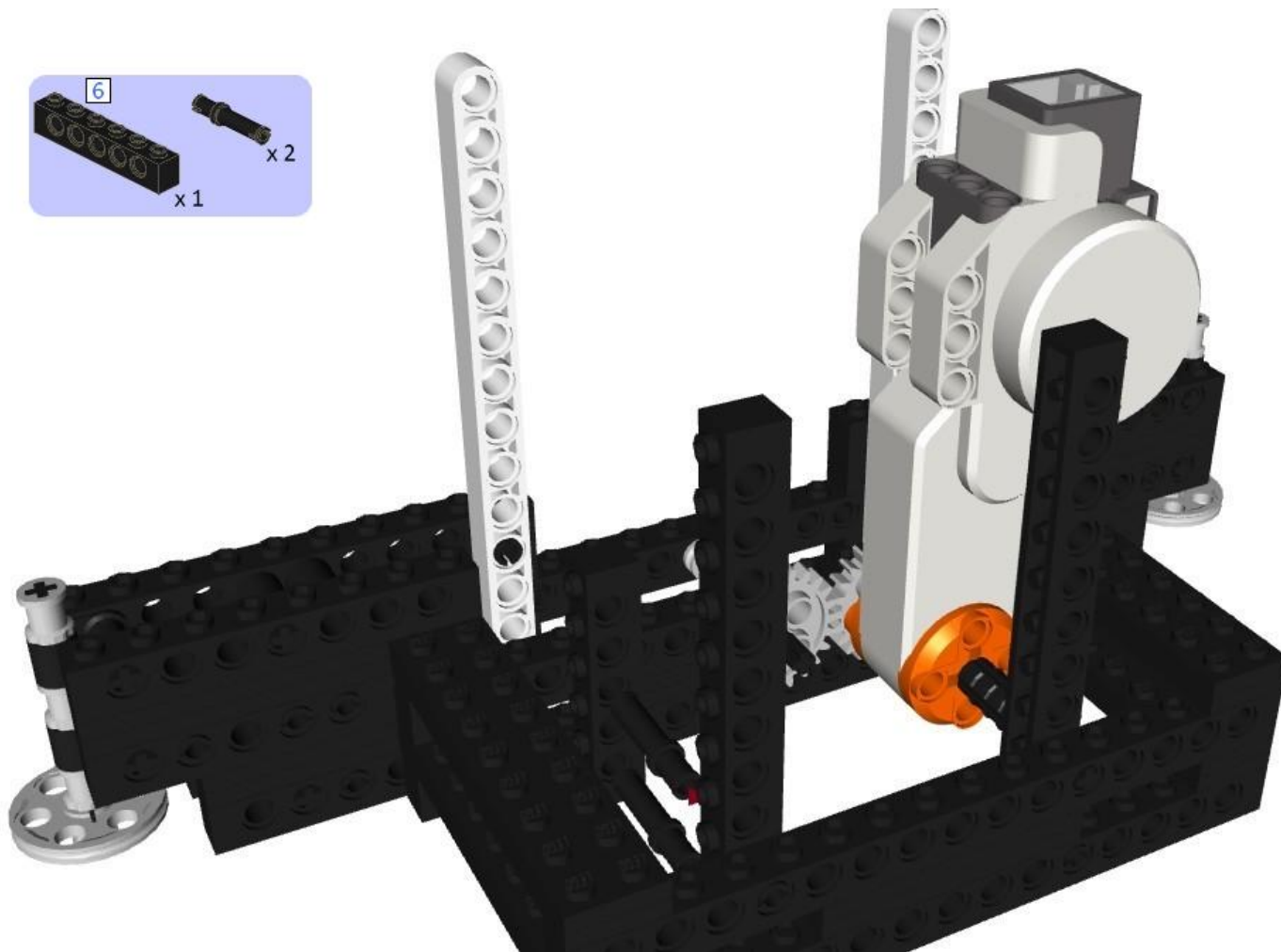
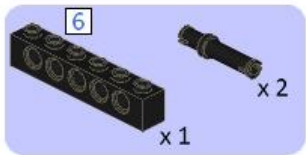
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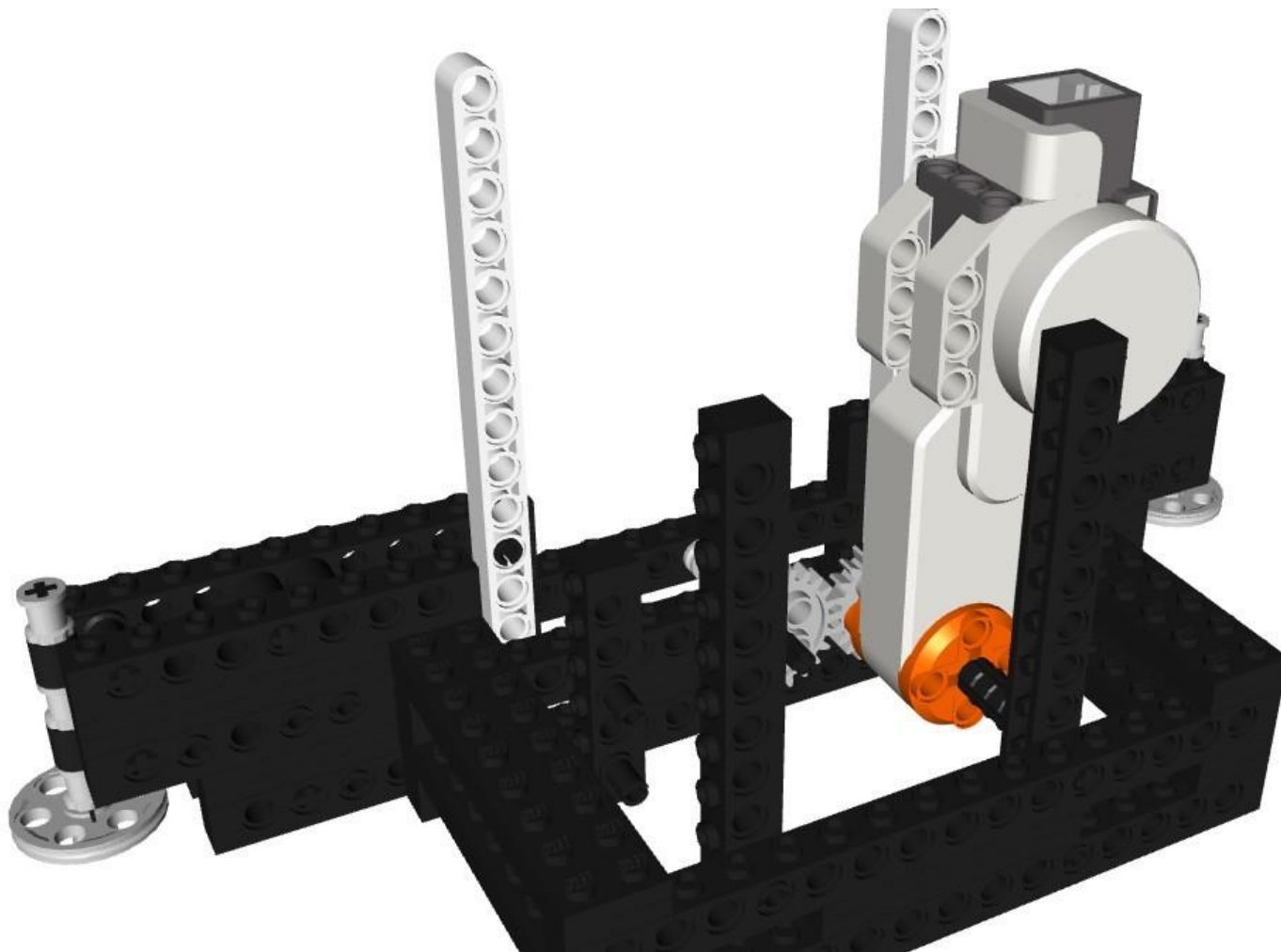




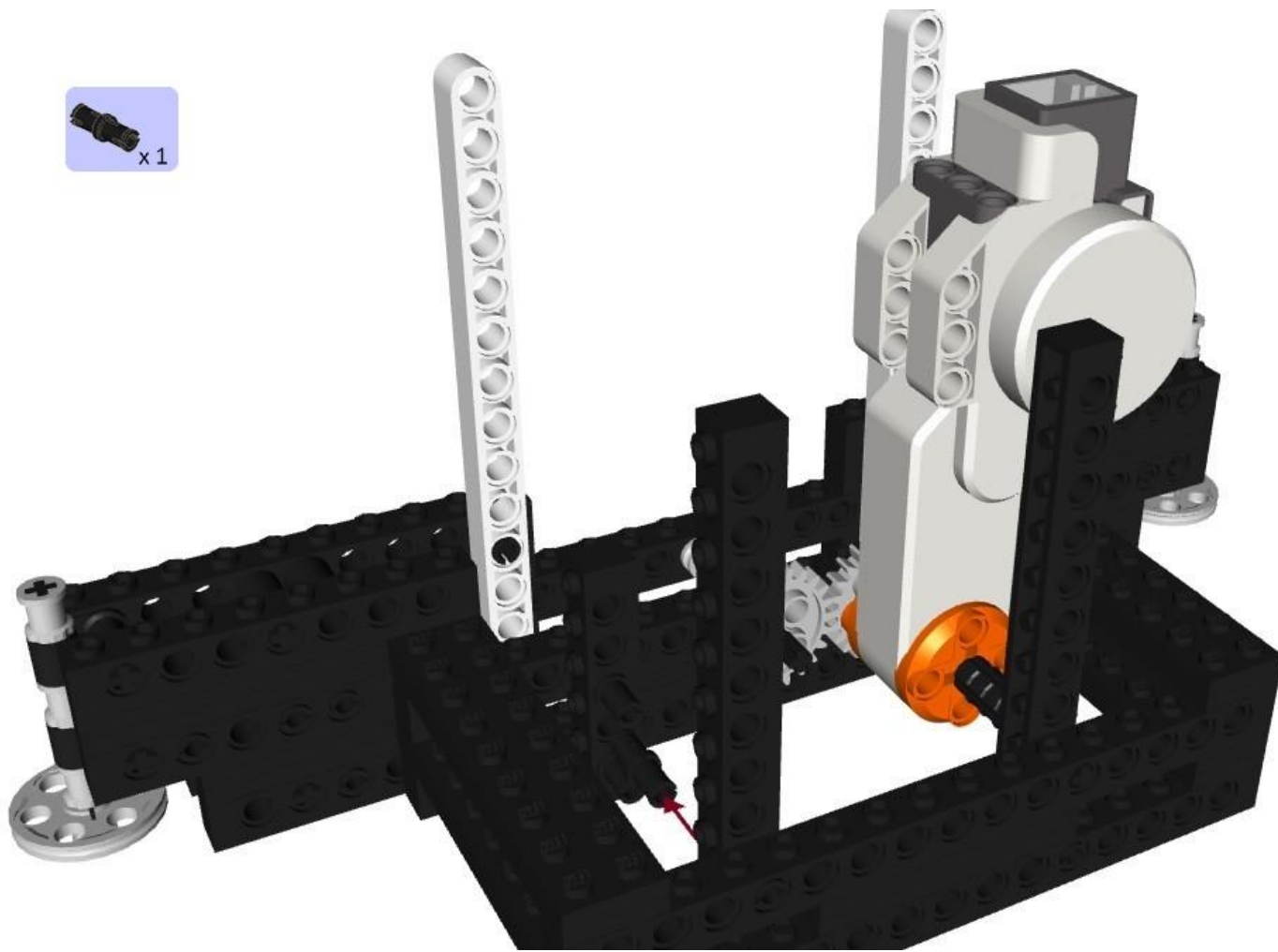


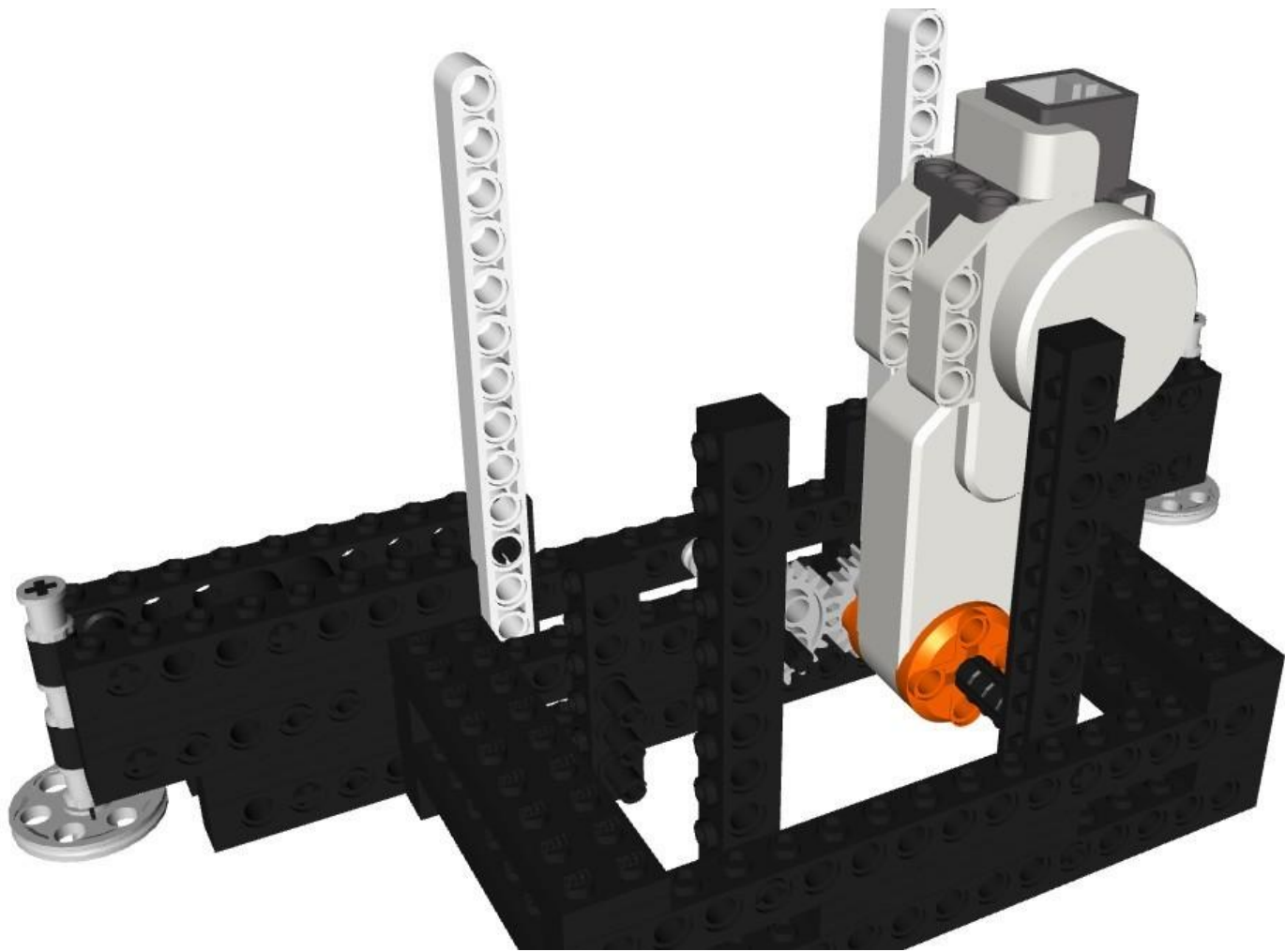




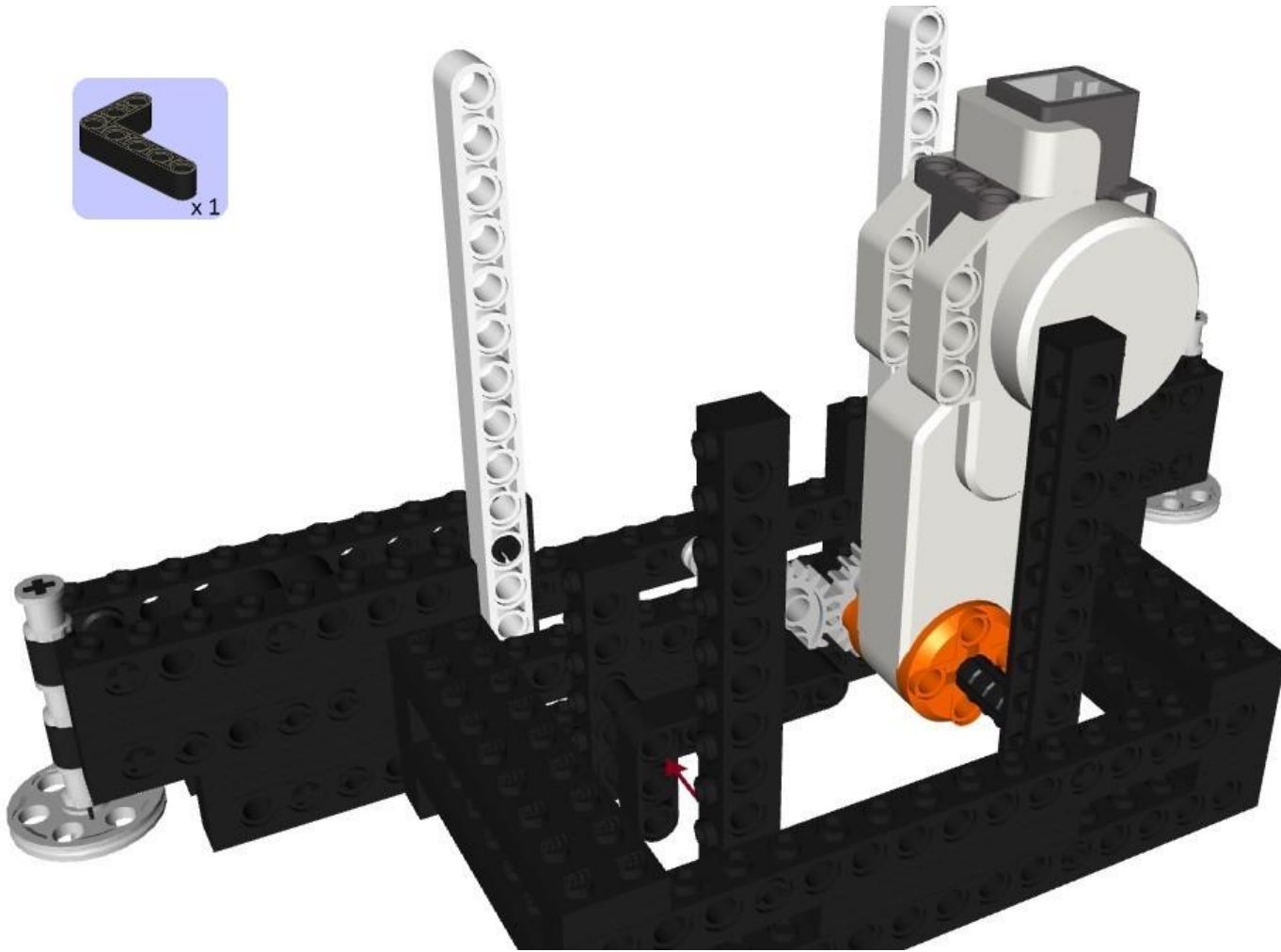
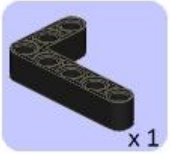


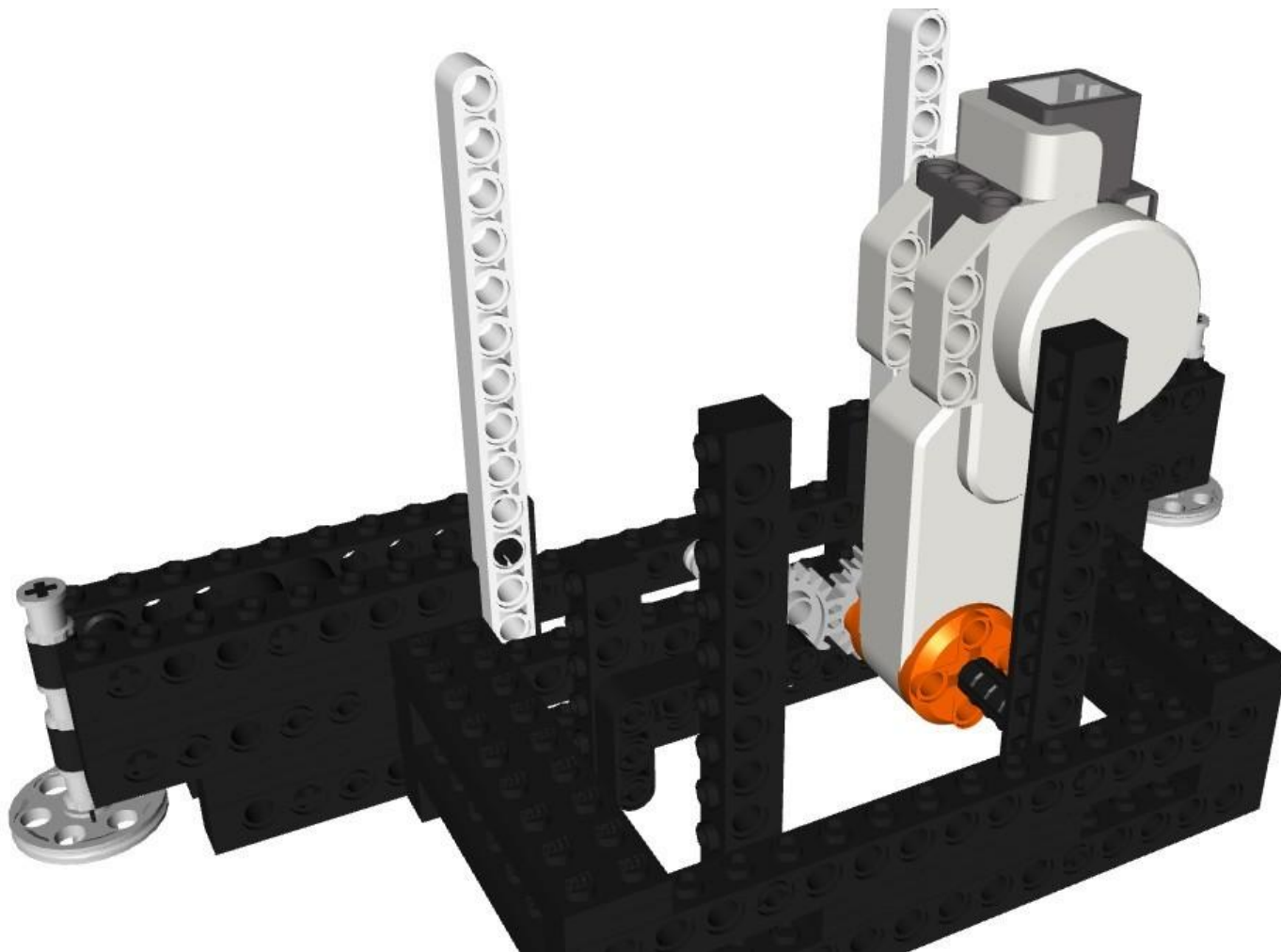
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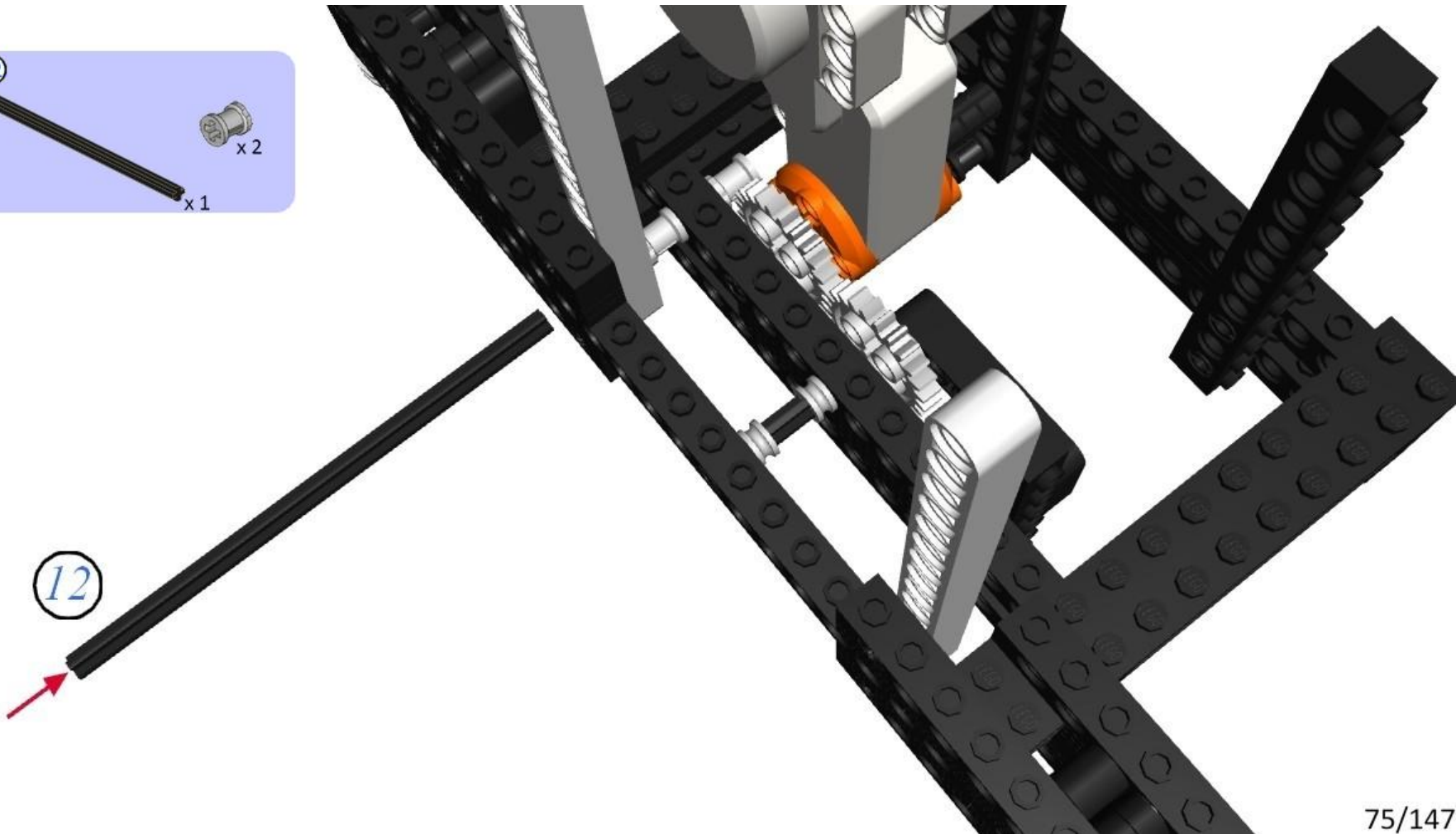


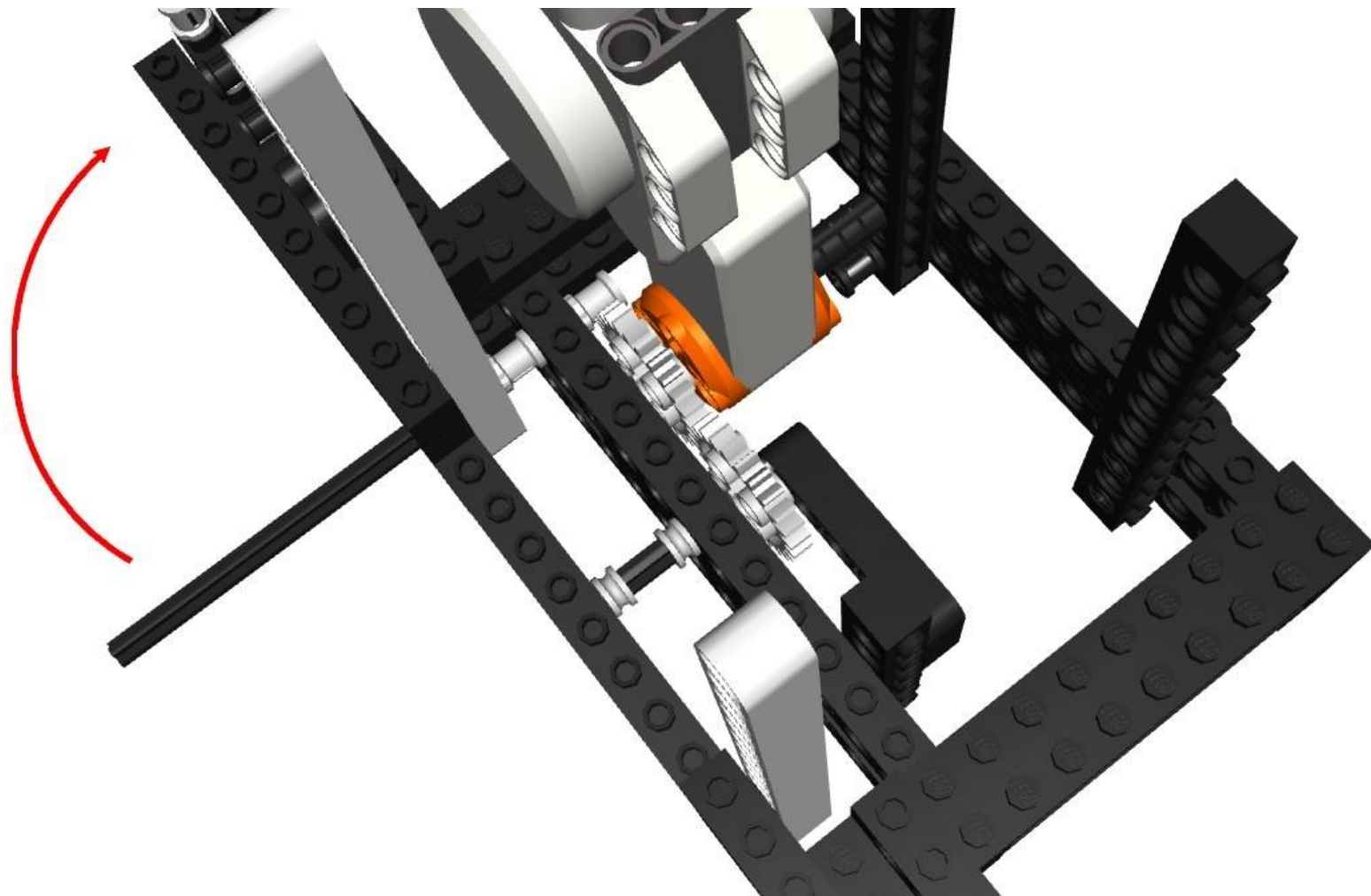
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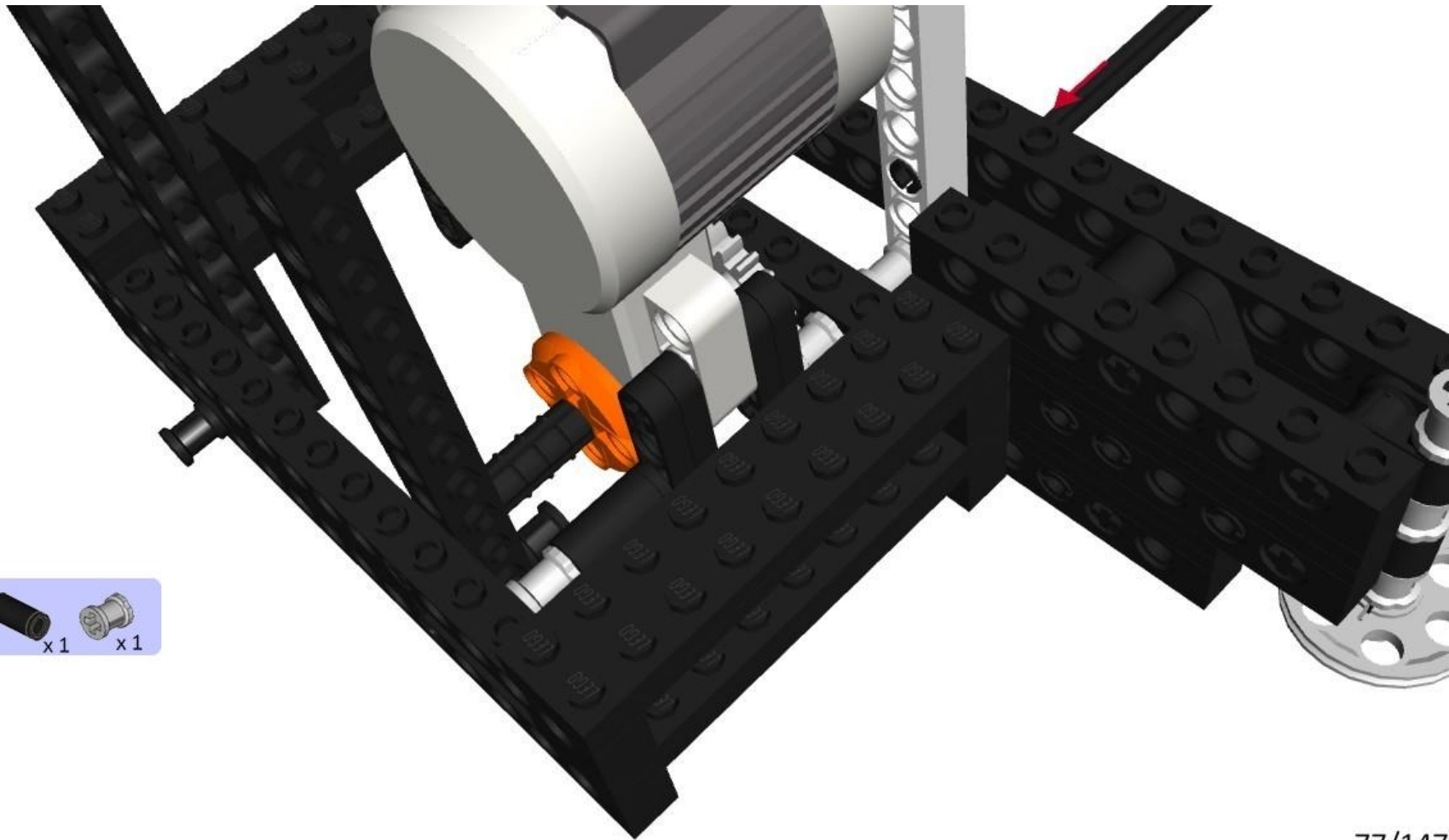




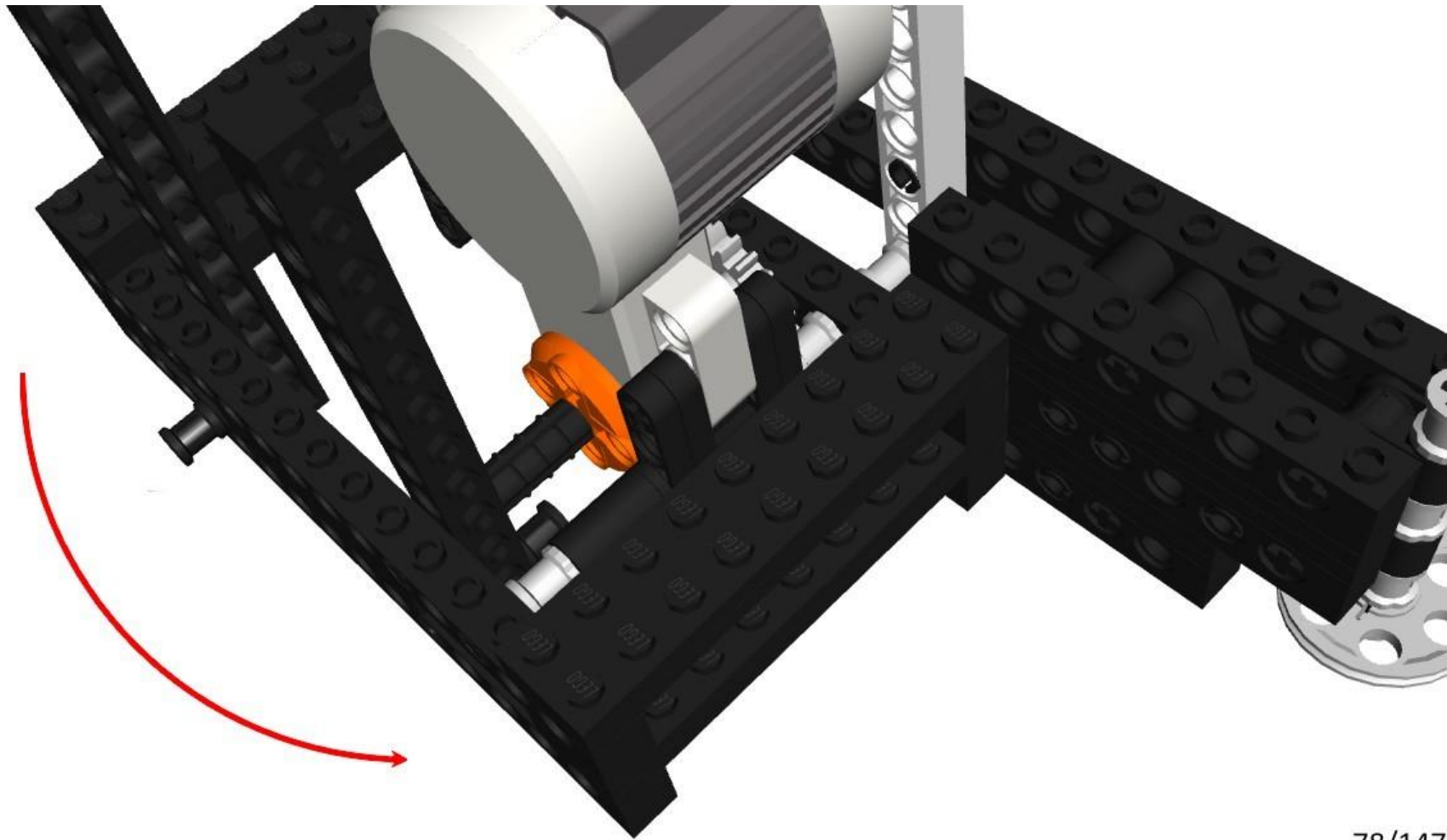
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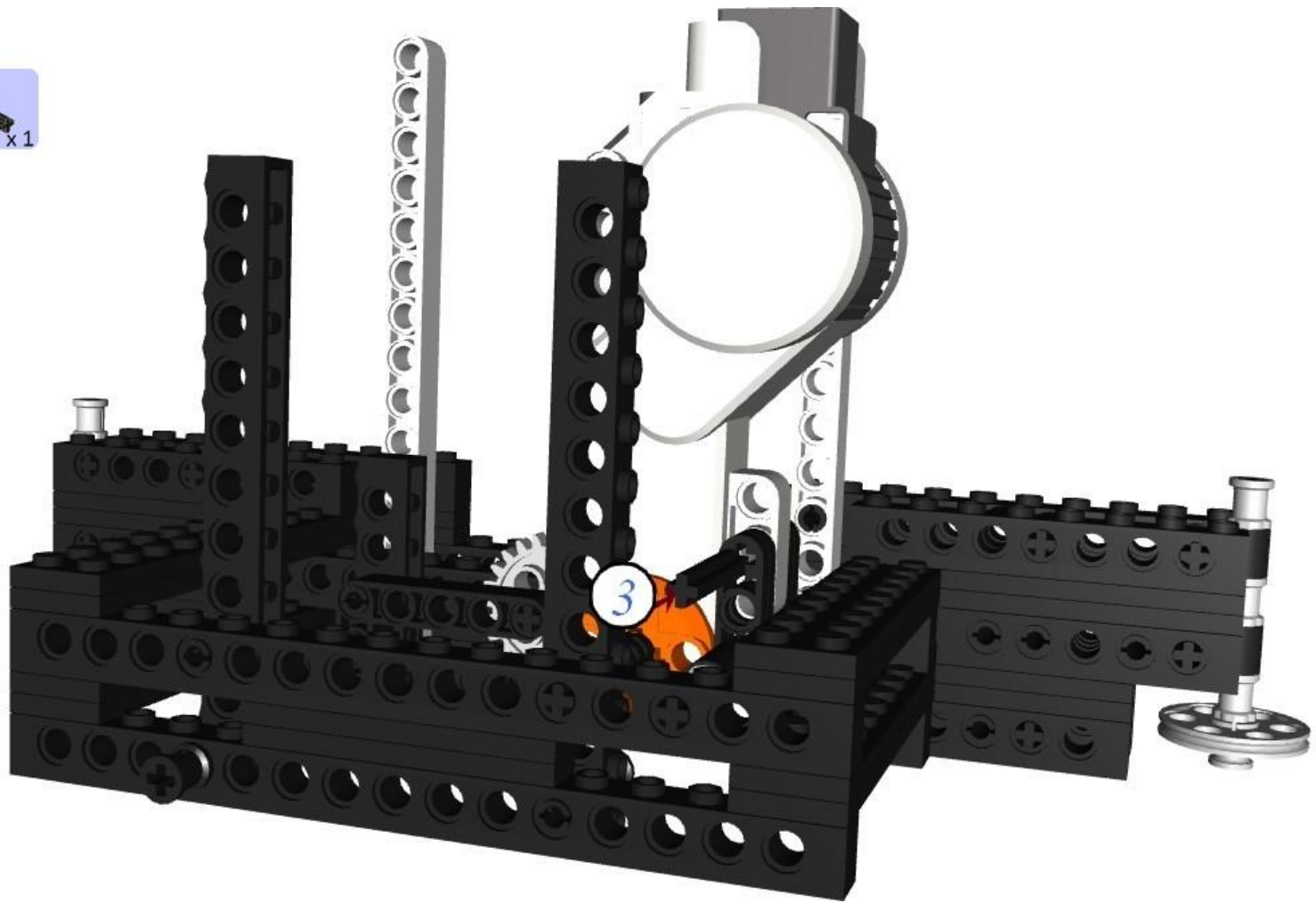




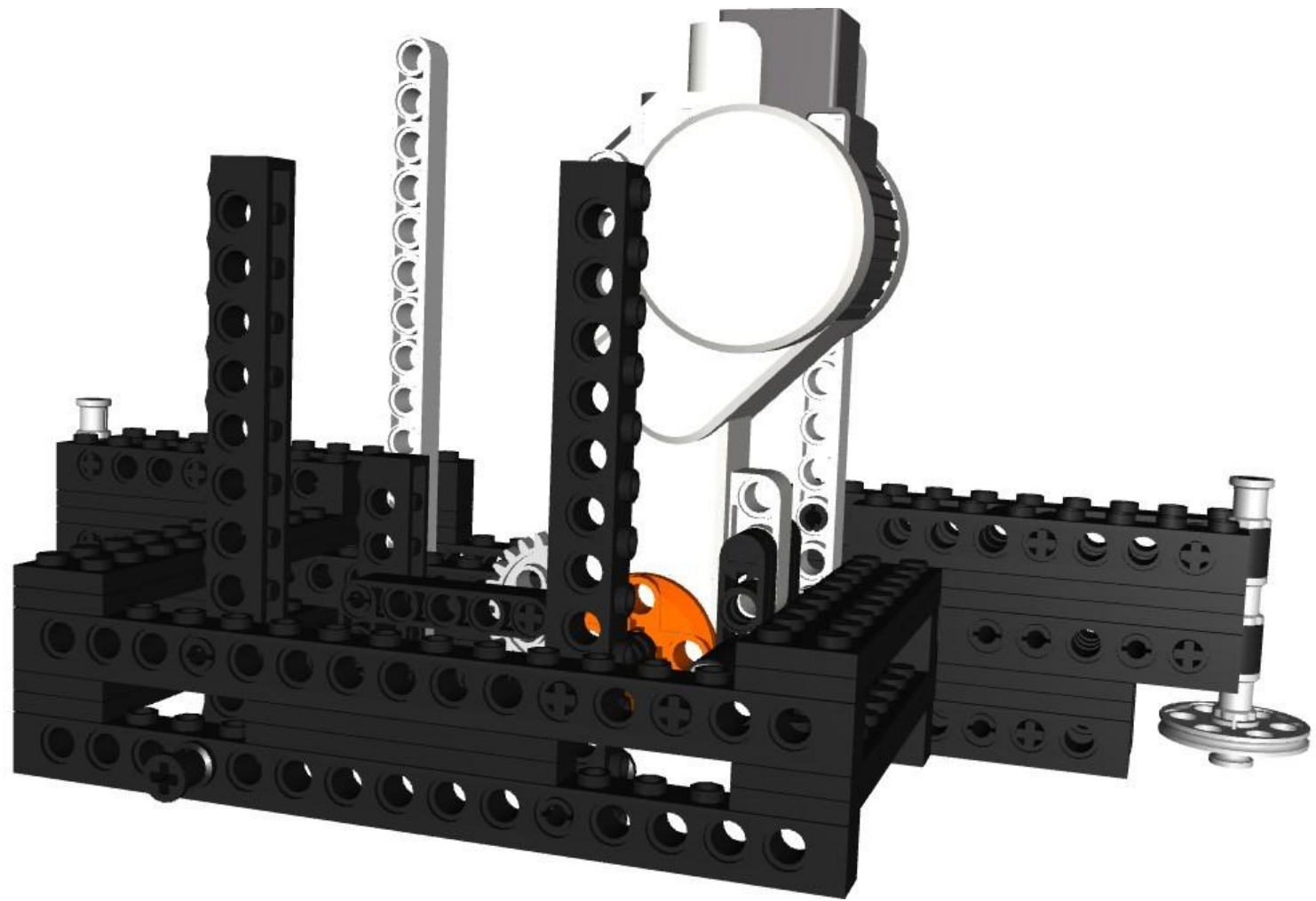
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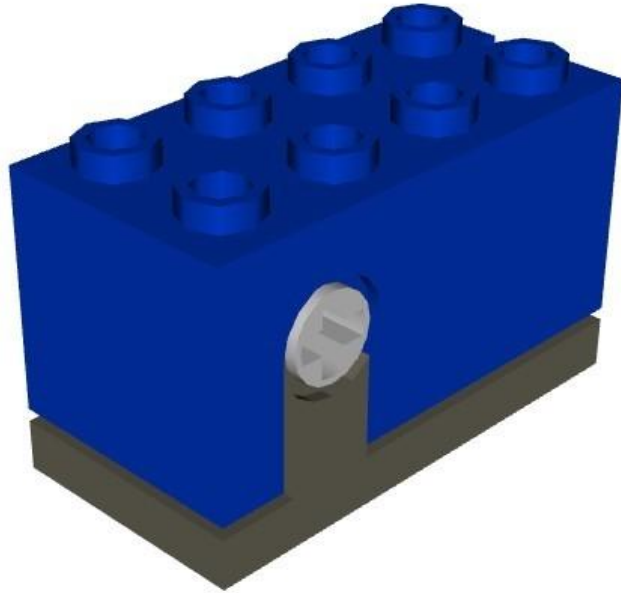
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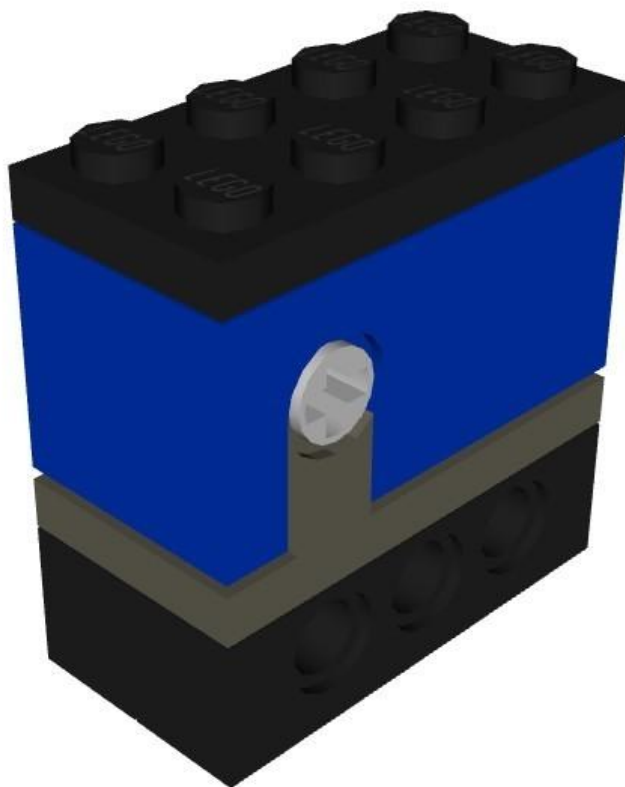
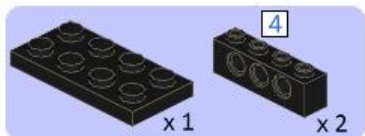


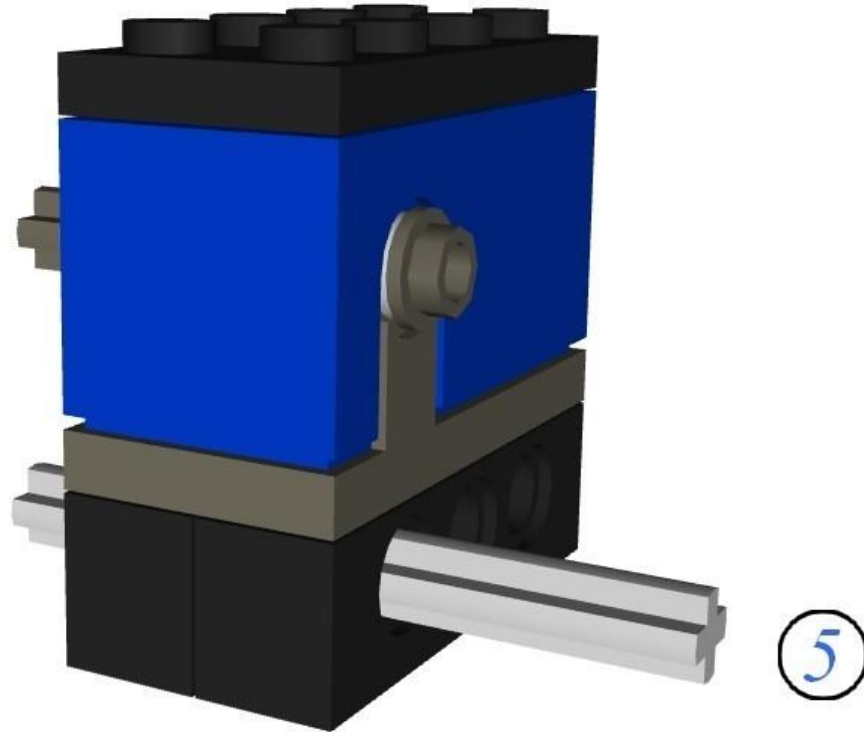
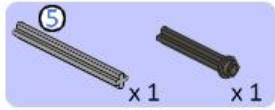
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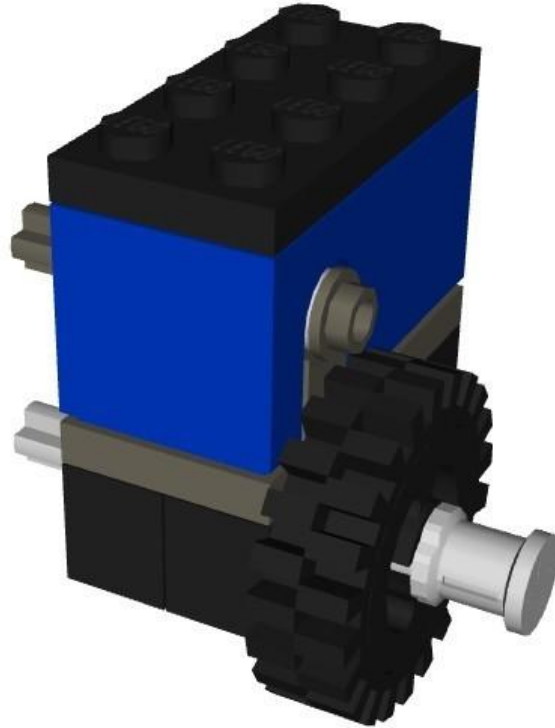
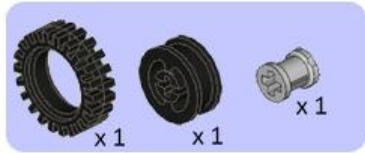


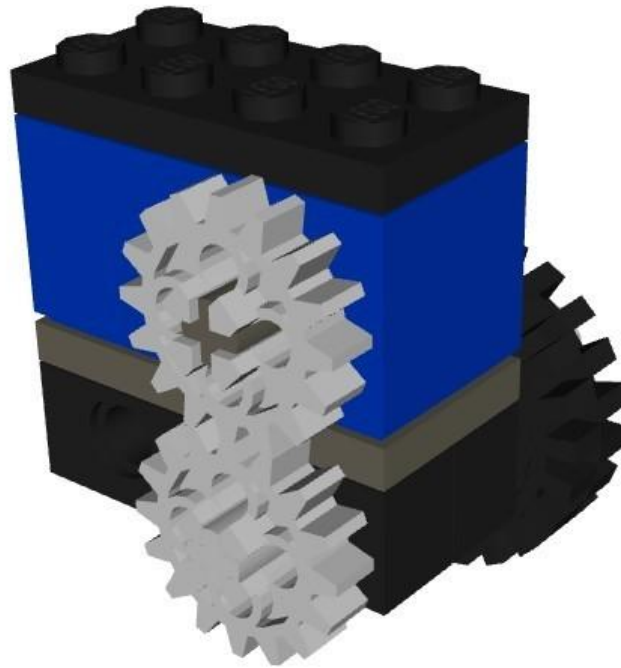
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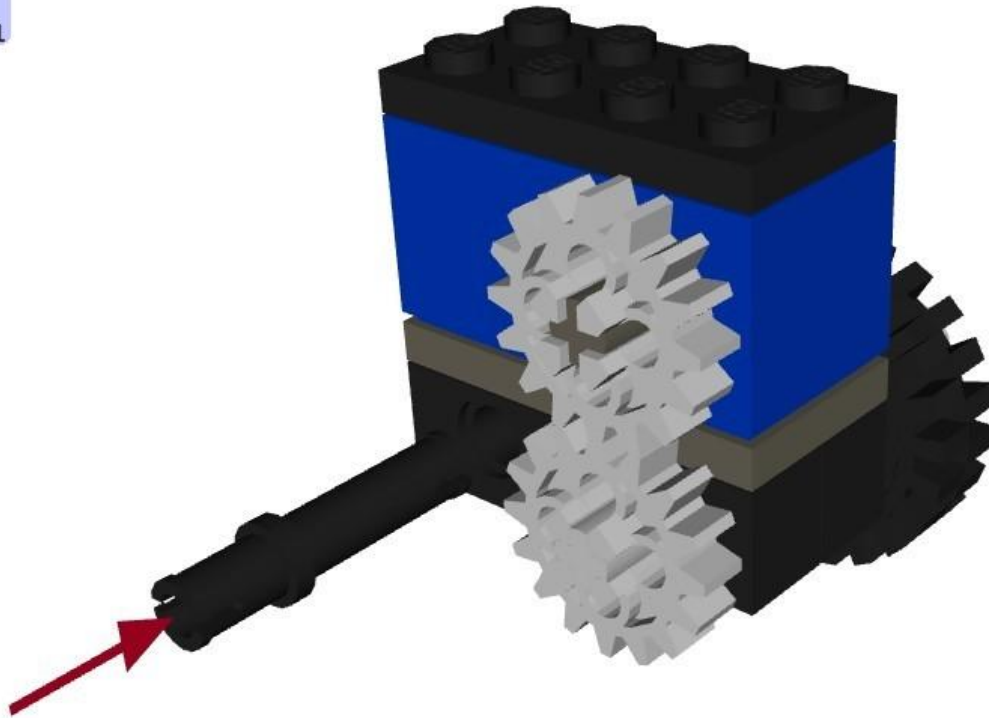


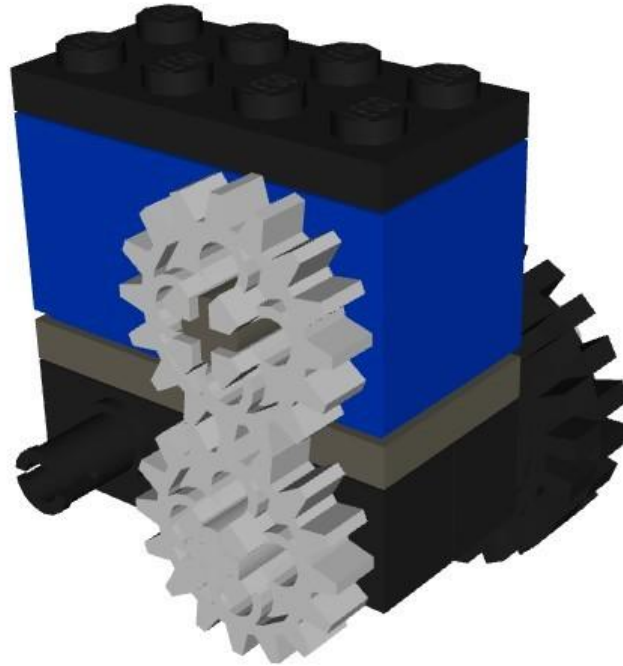


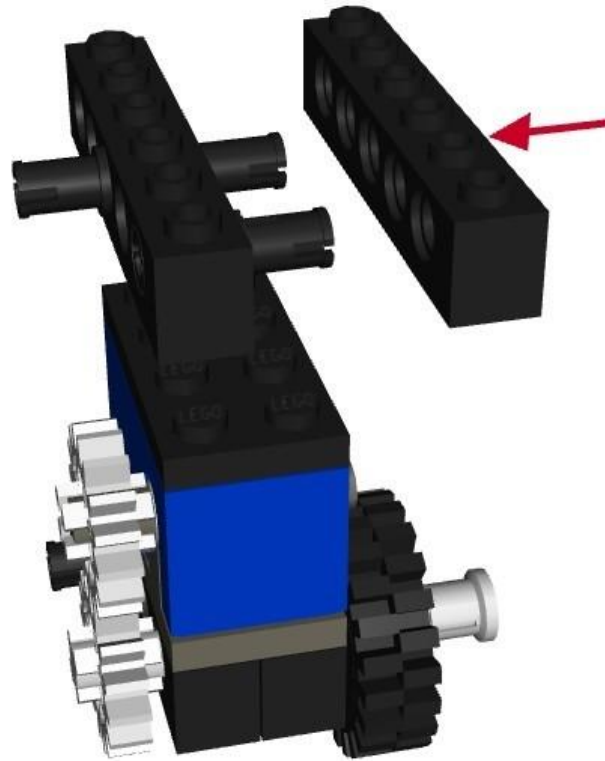
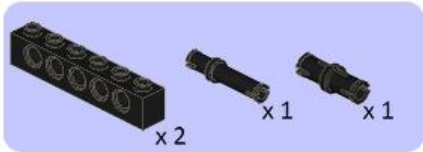


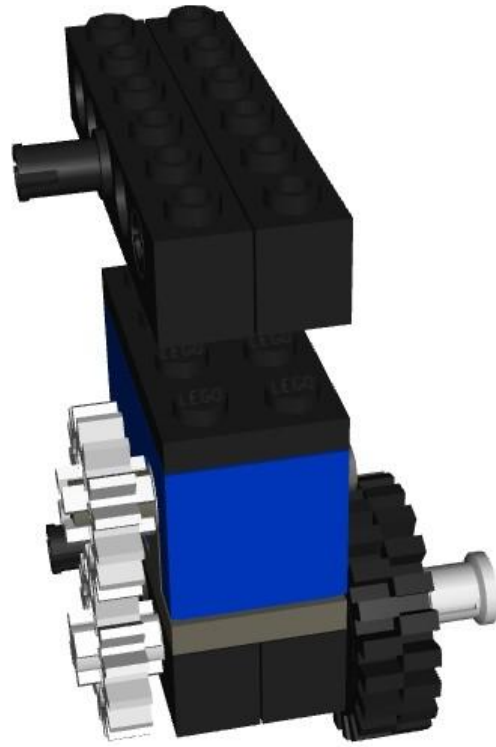


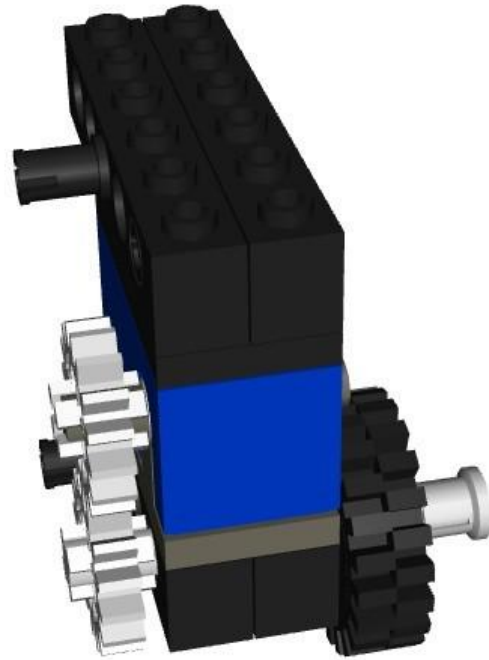


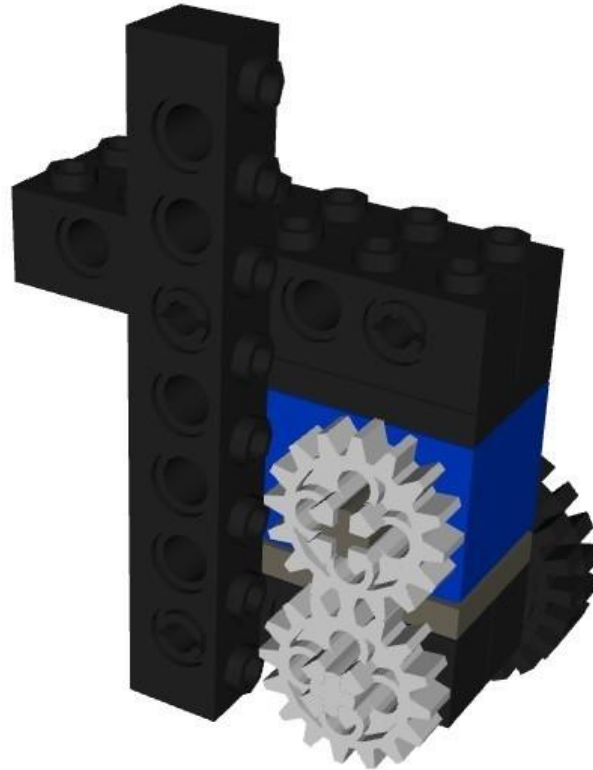
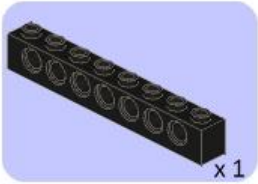


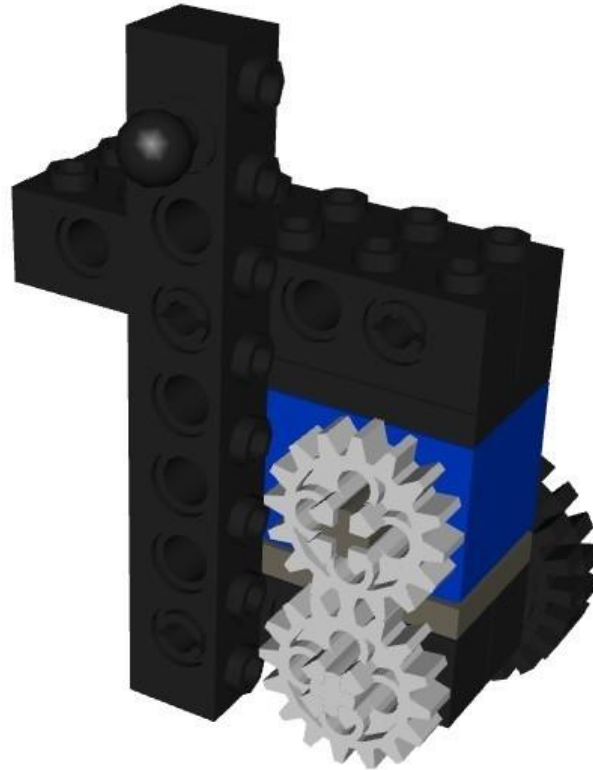


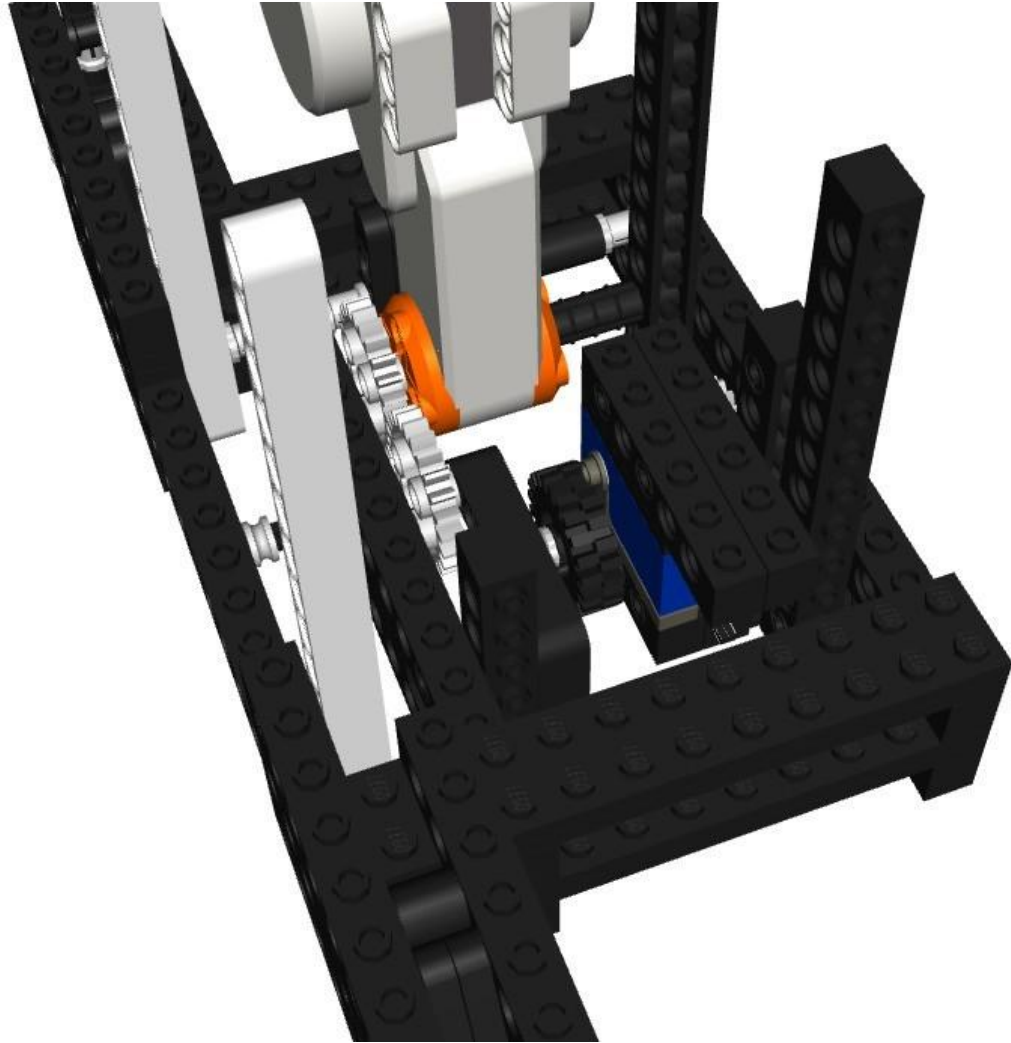


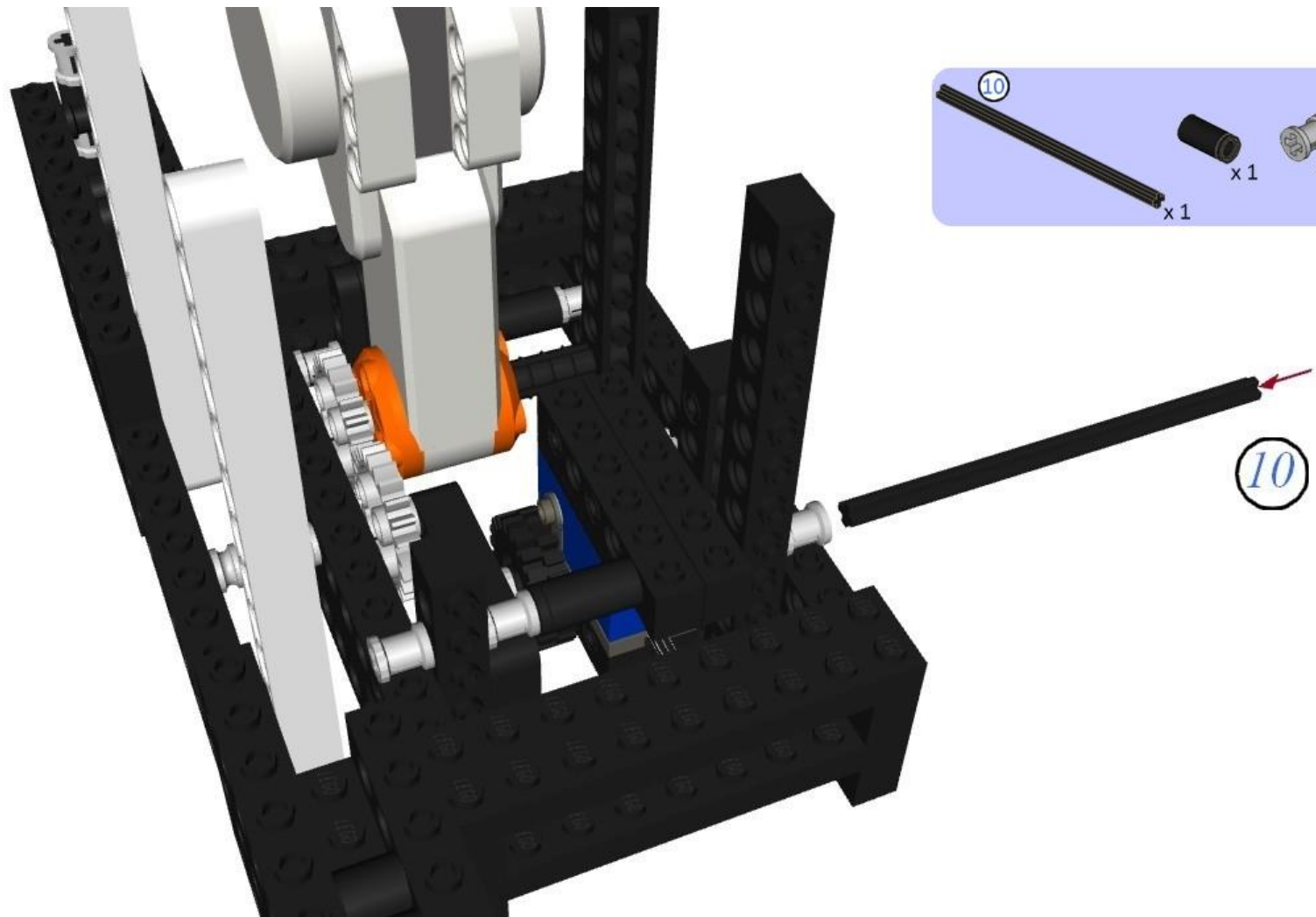


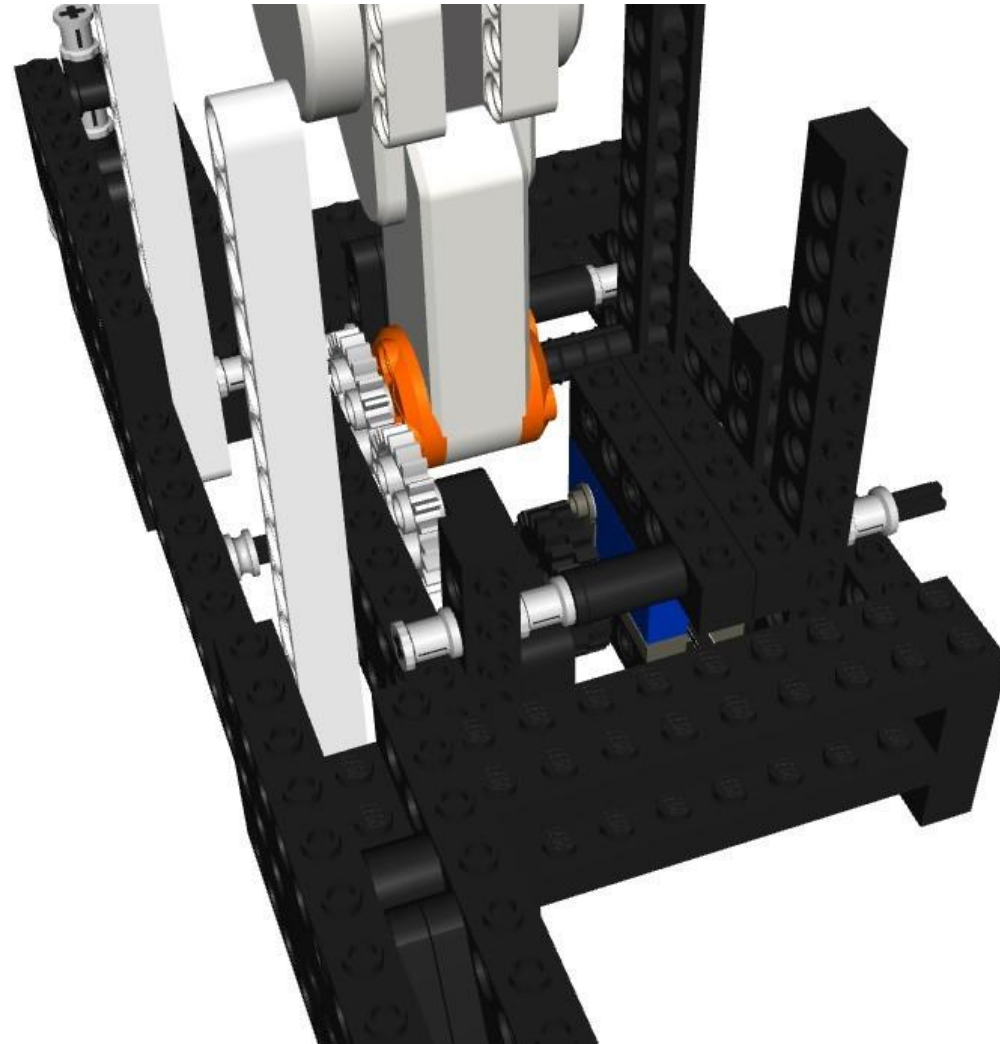


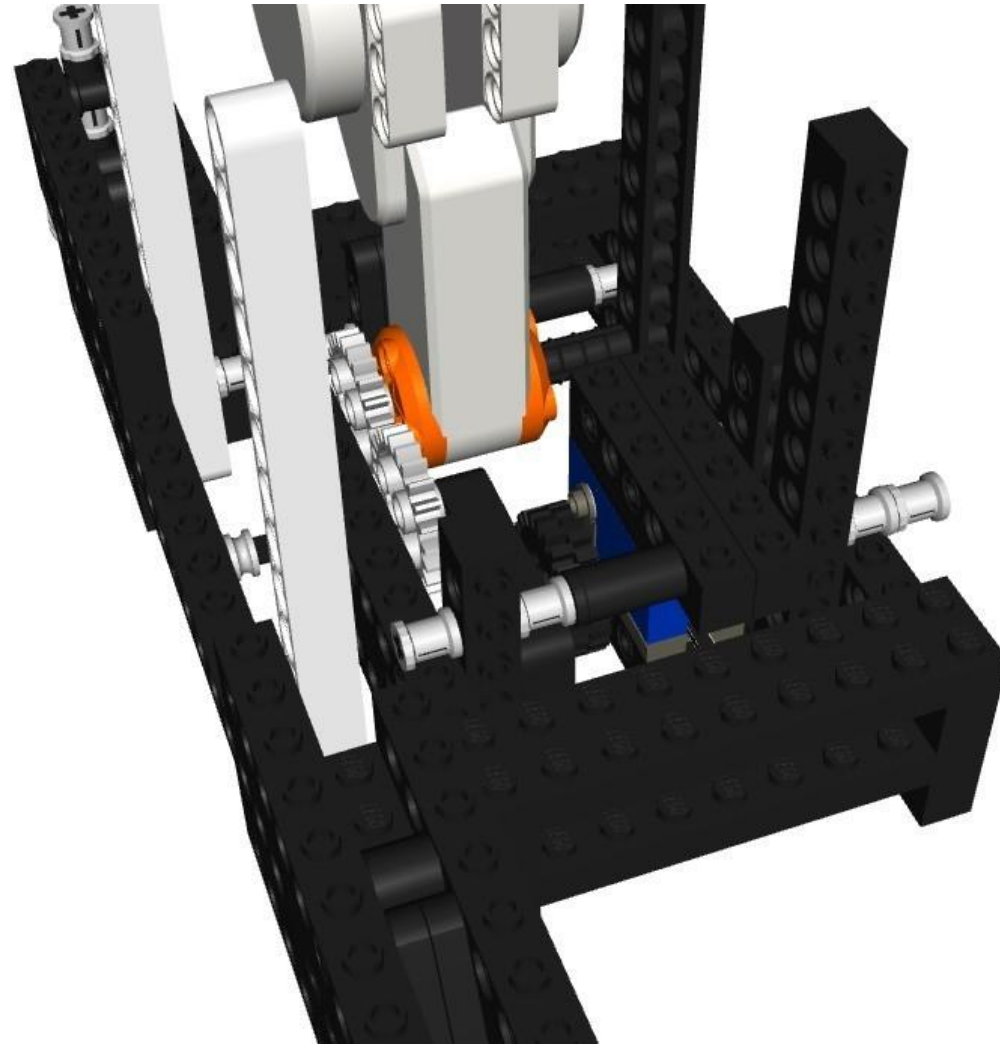


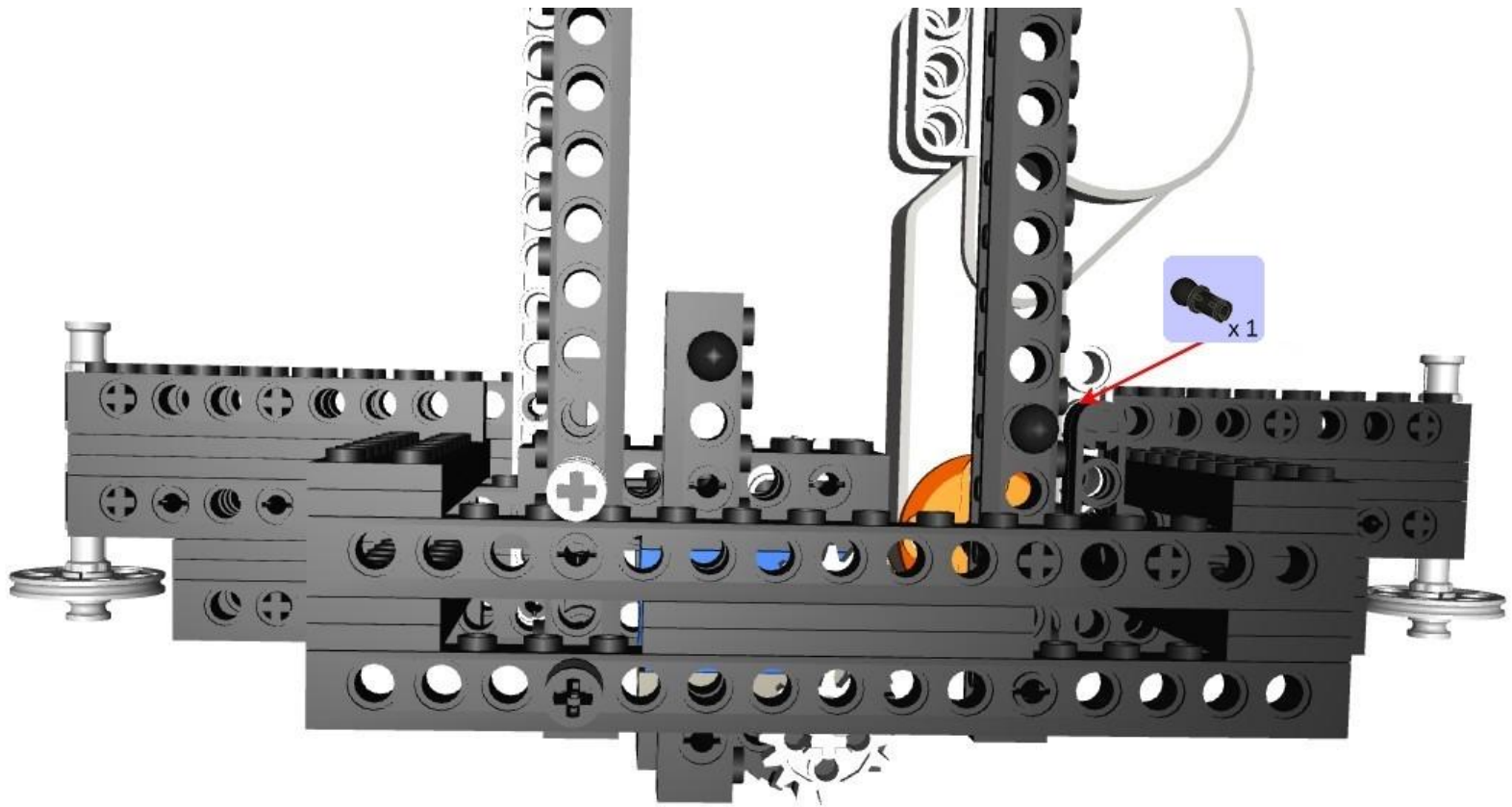






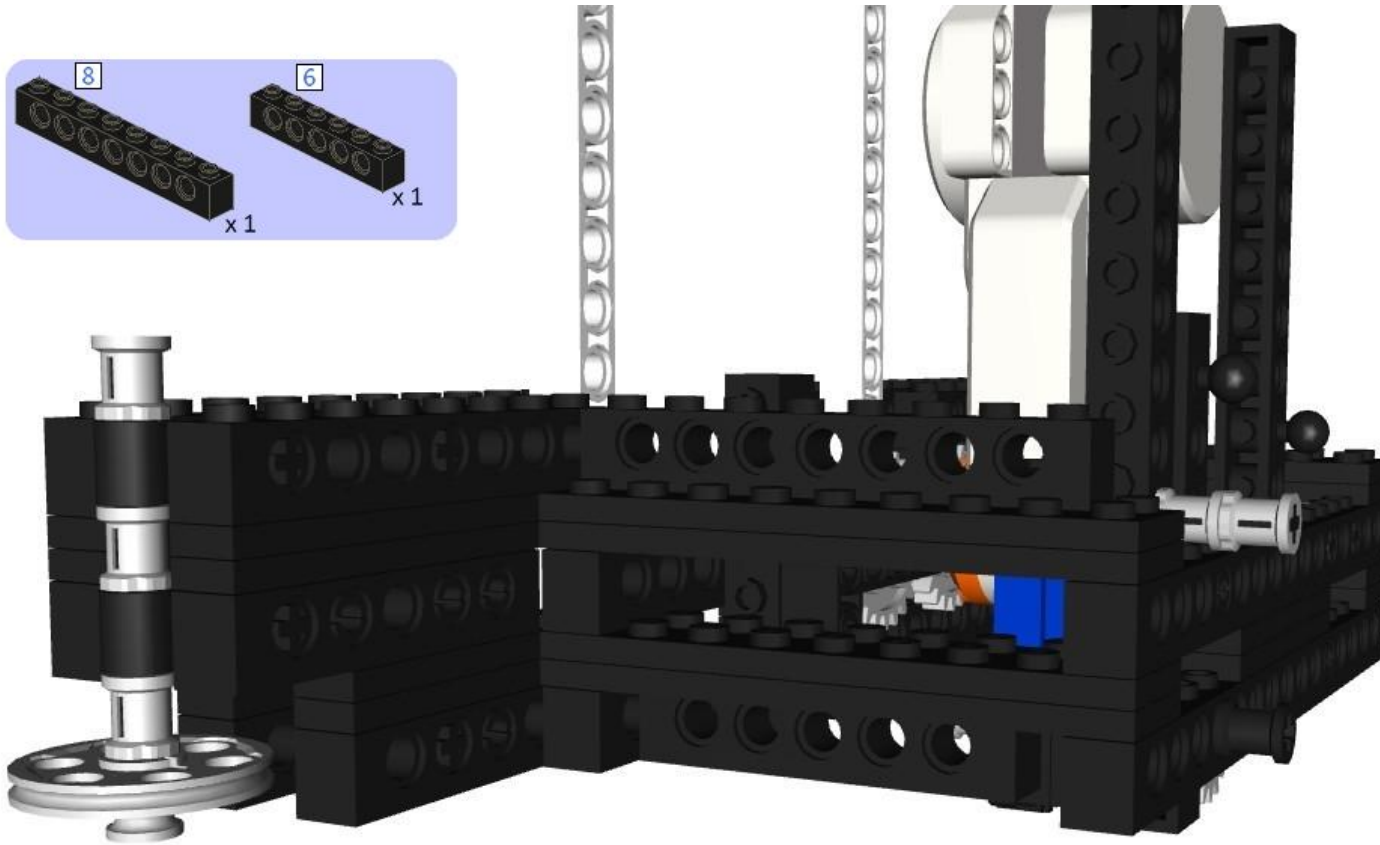
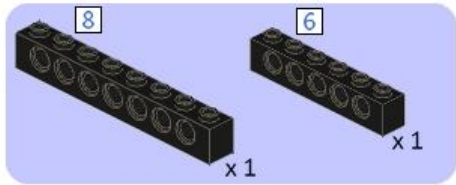


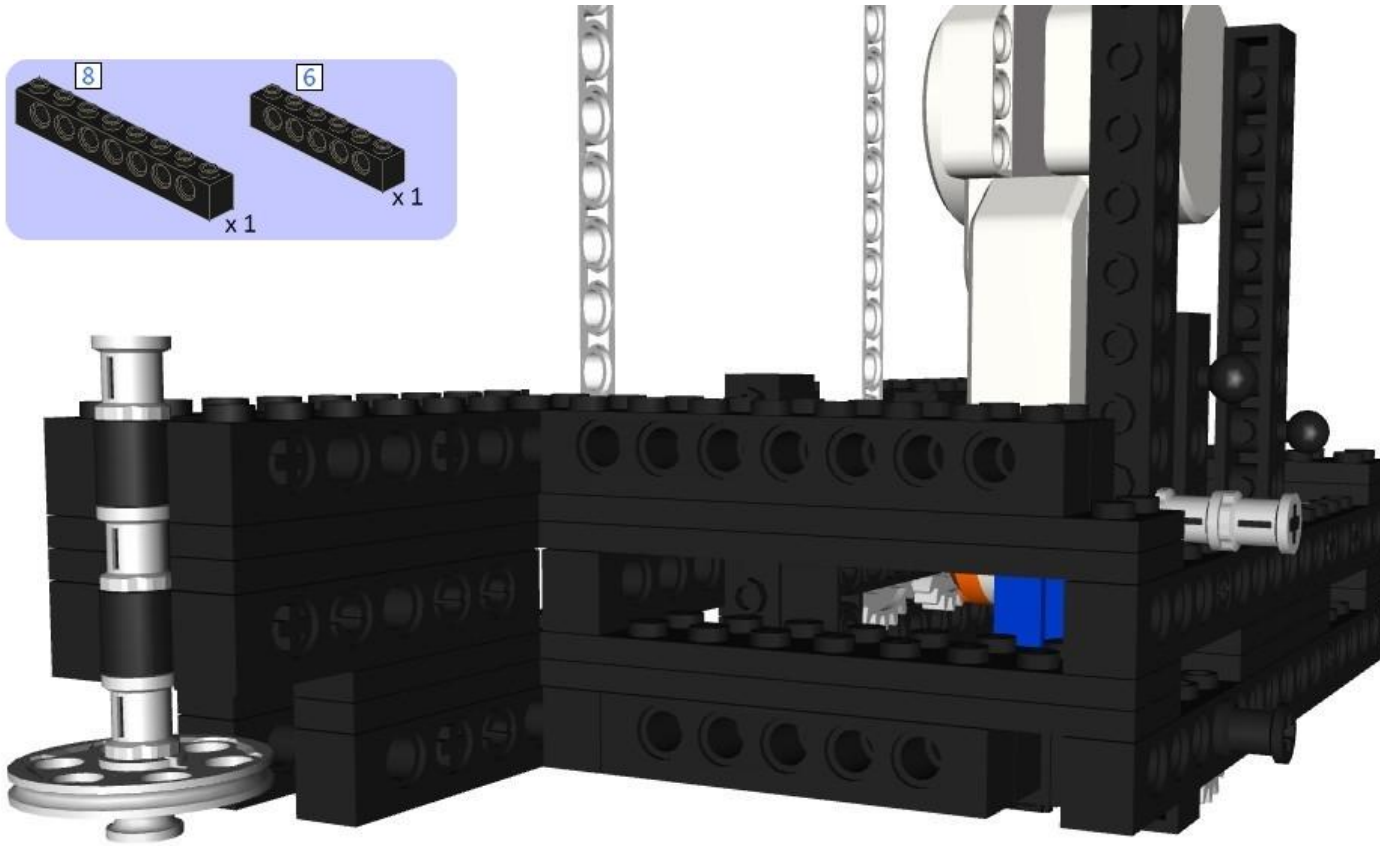
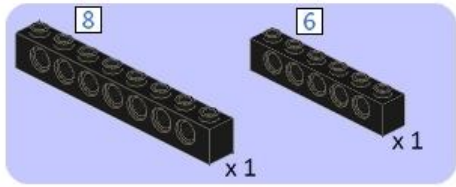


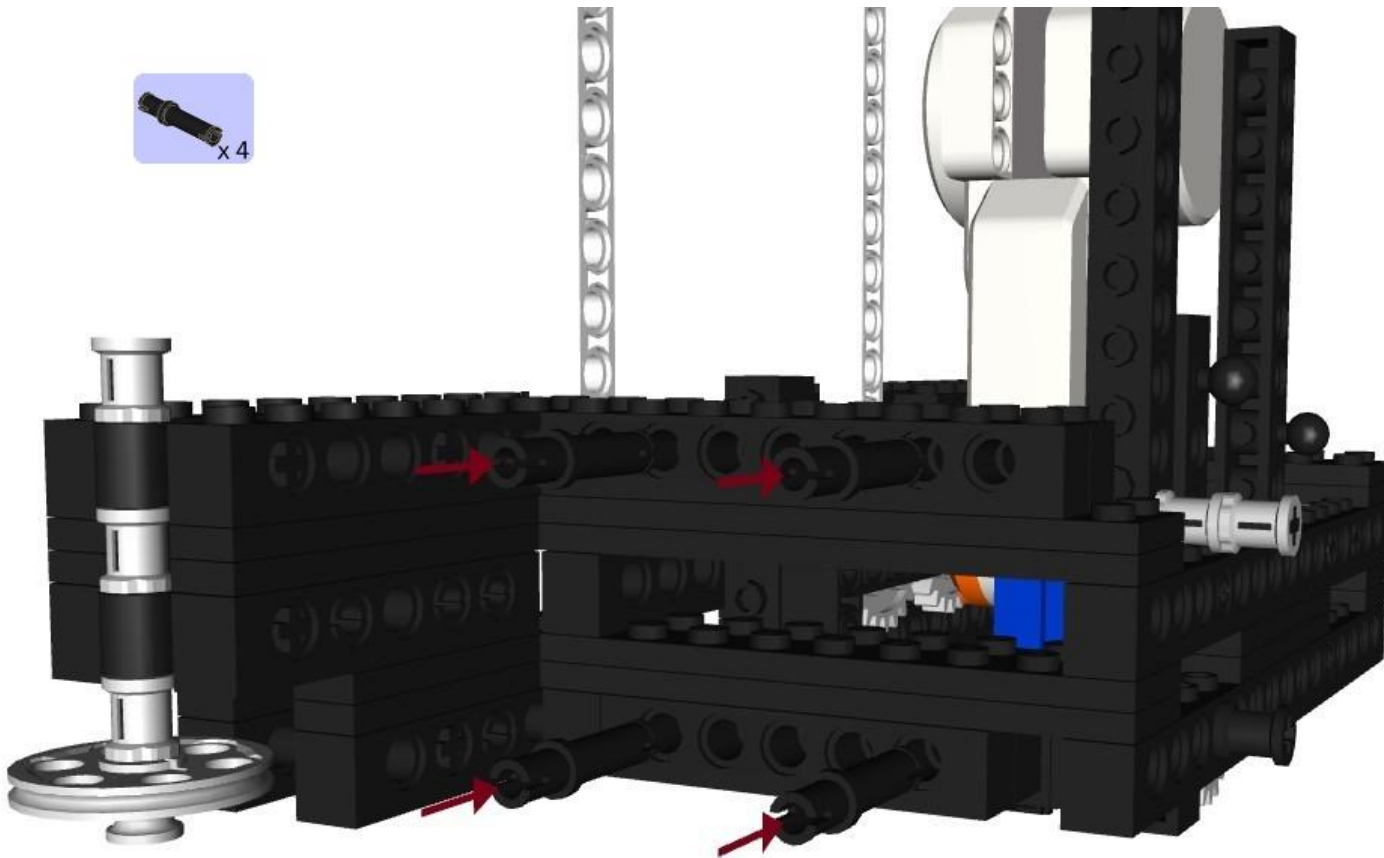


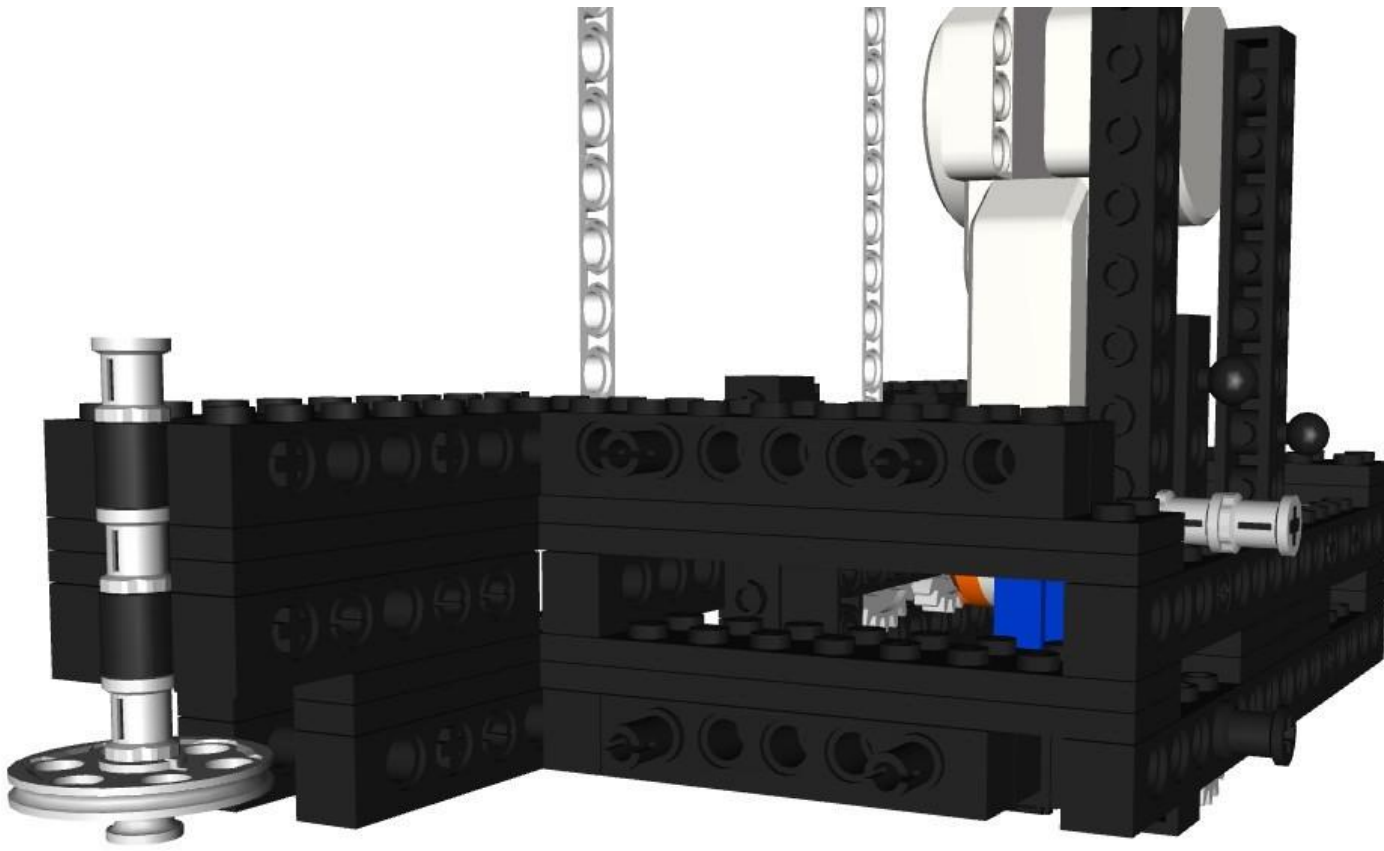


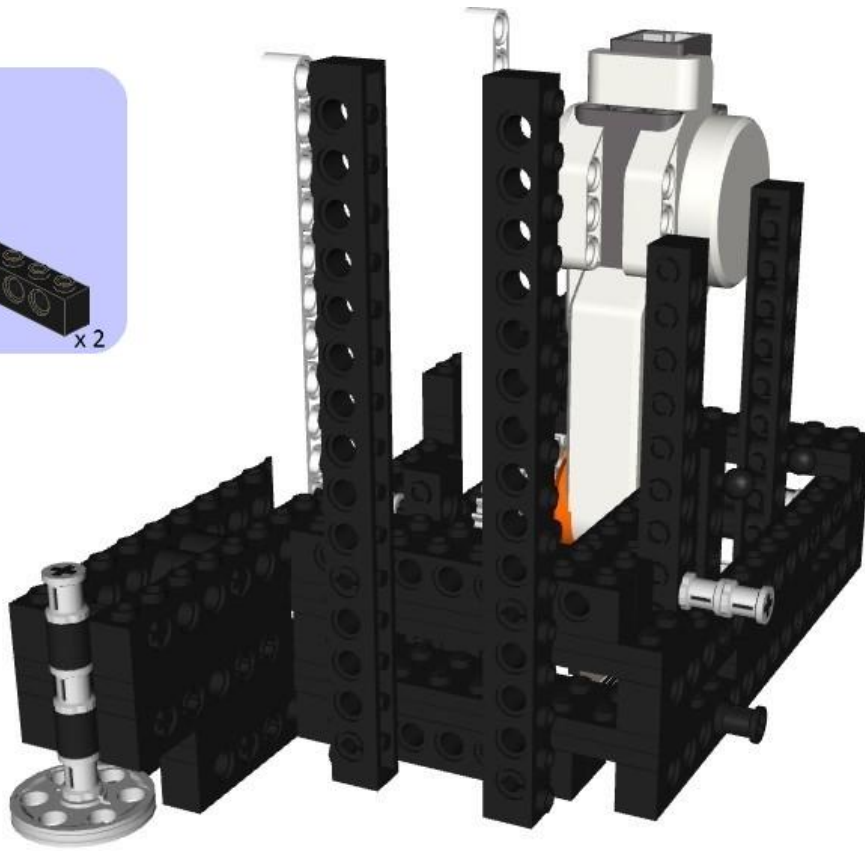
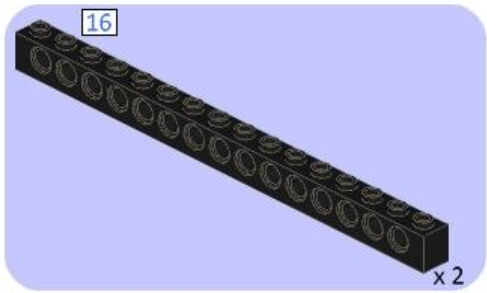
Mettre un élastique bleu  x1 qui rejoint les deux  x1

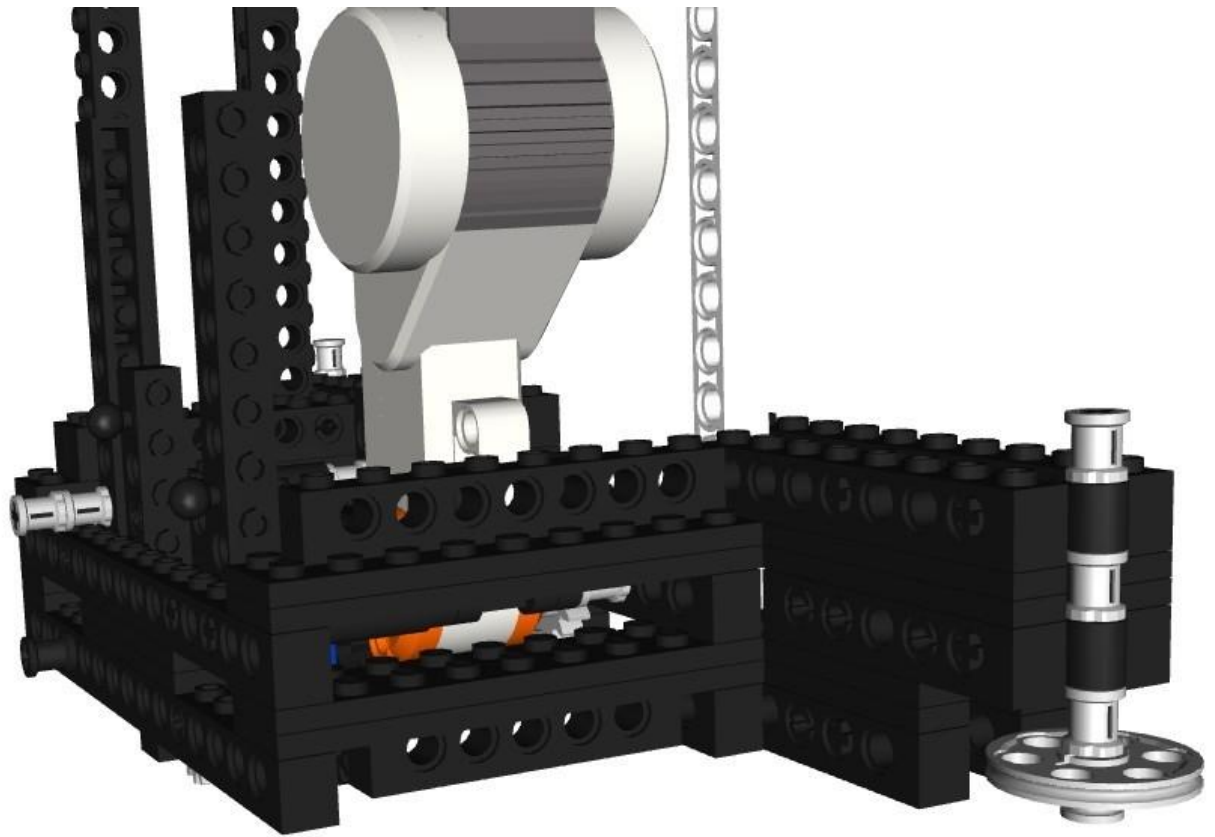
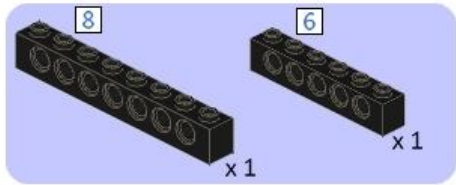


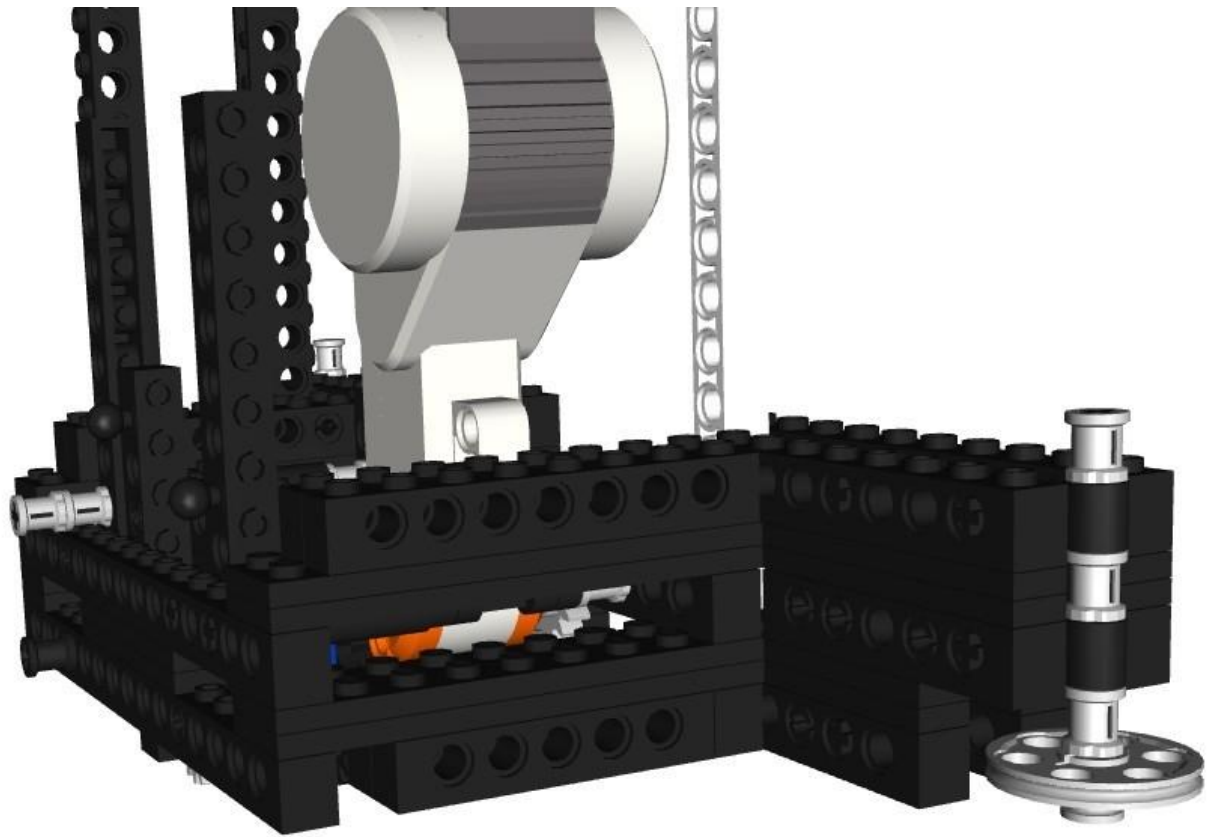
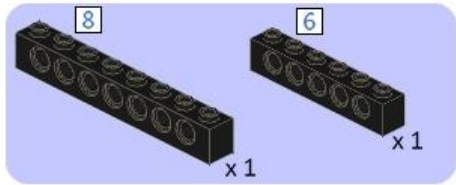


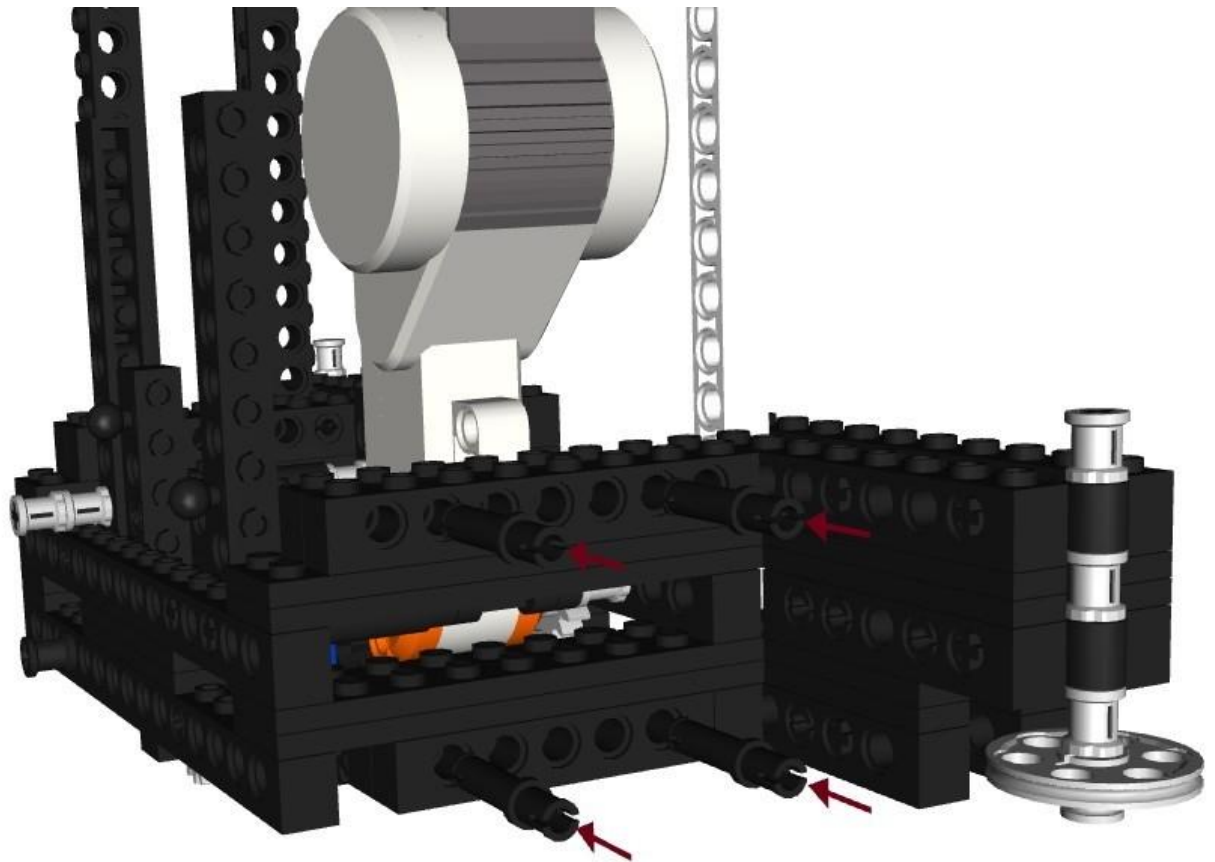


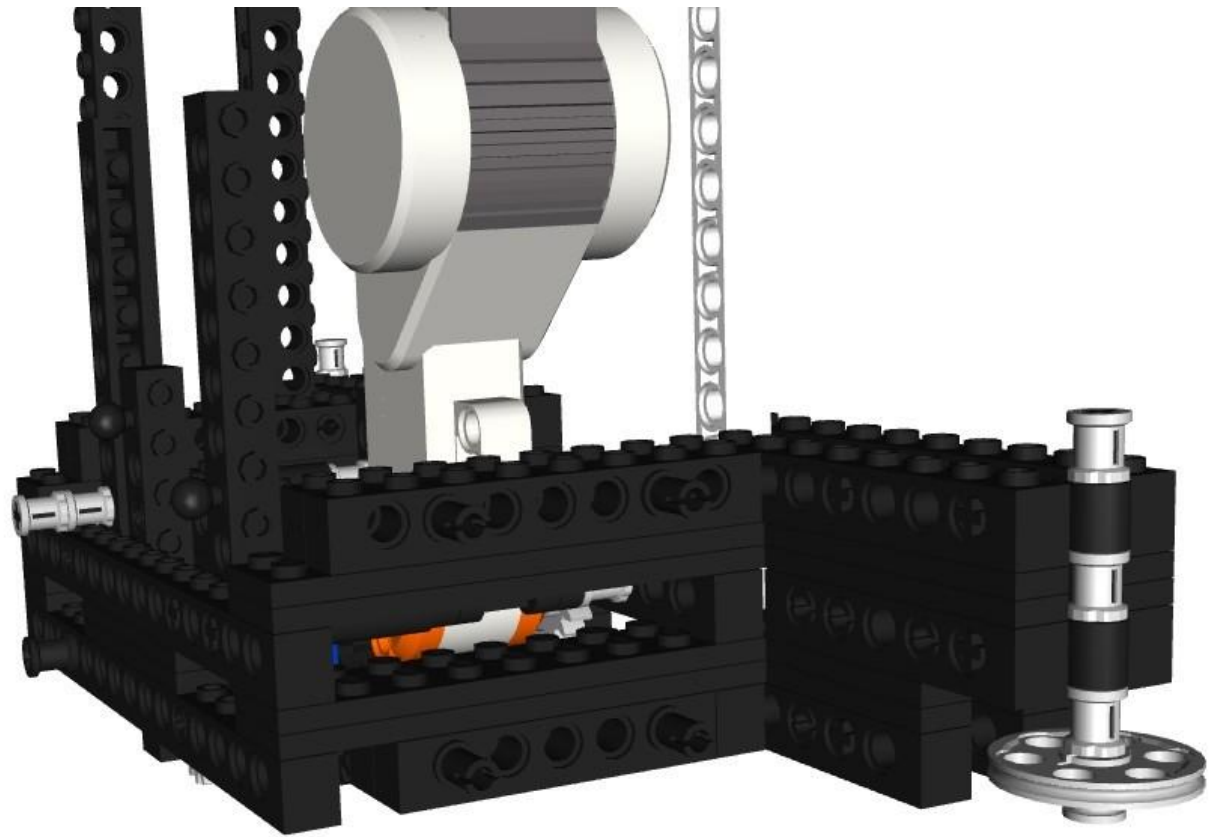


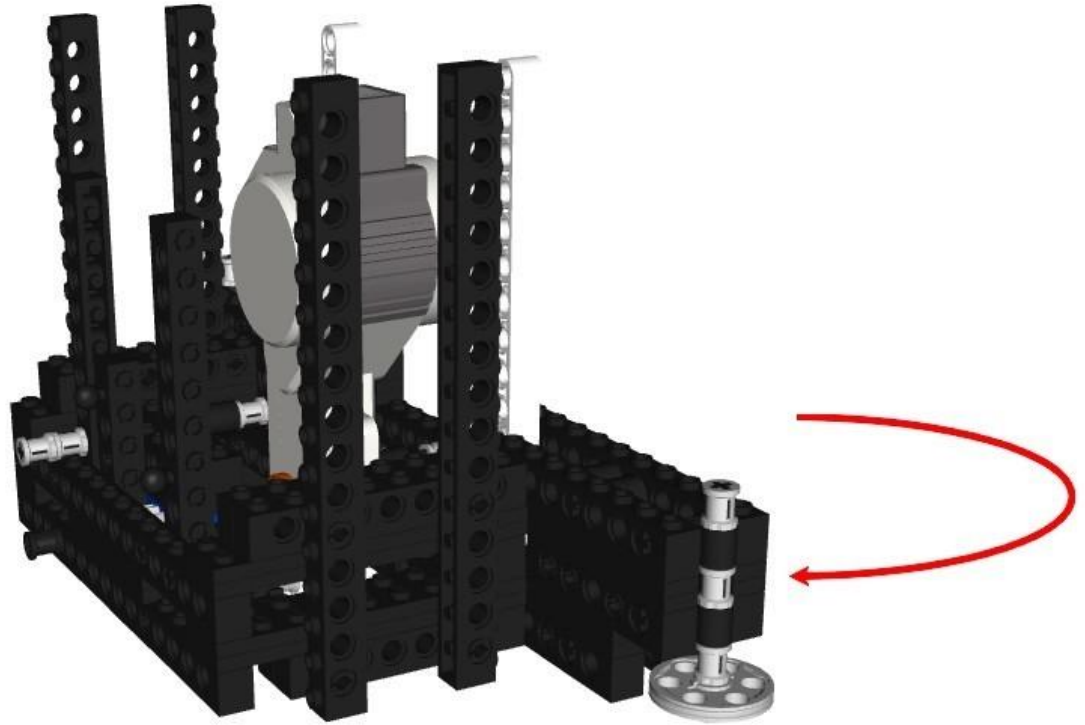
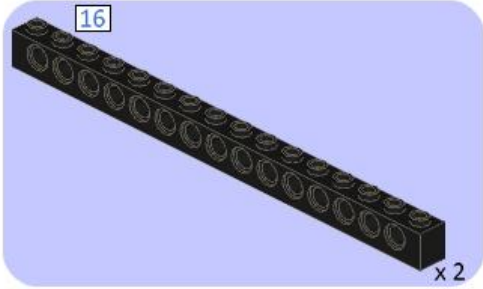


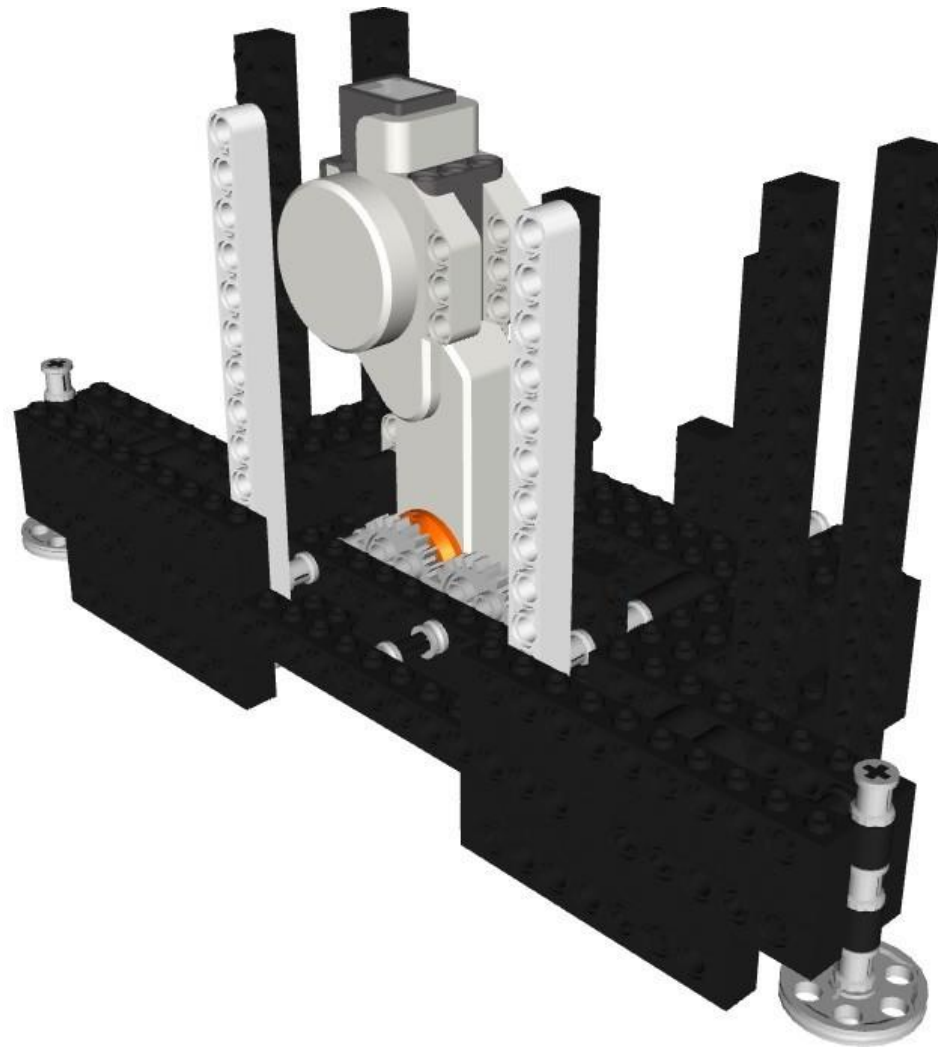


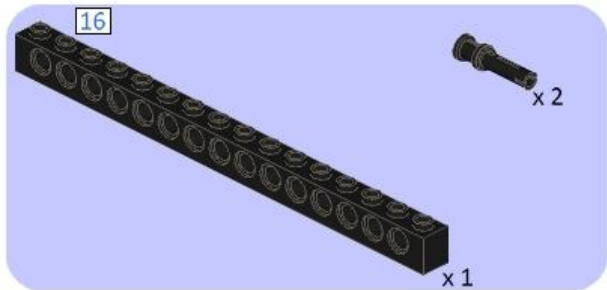
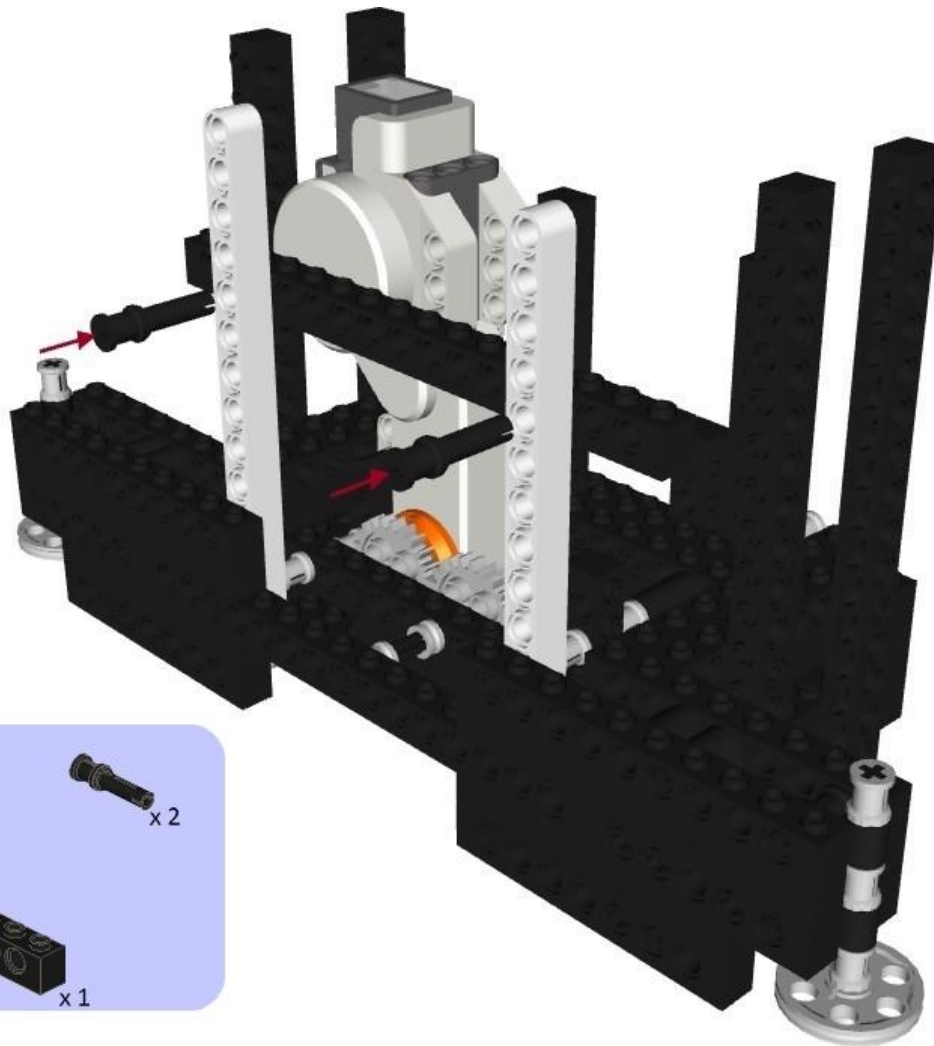


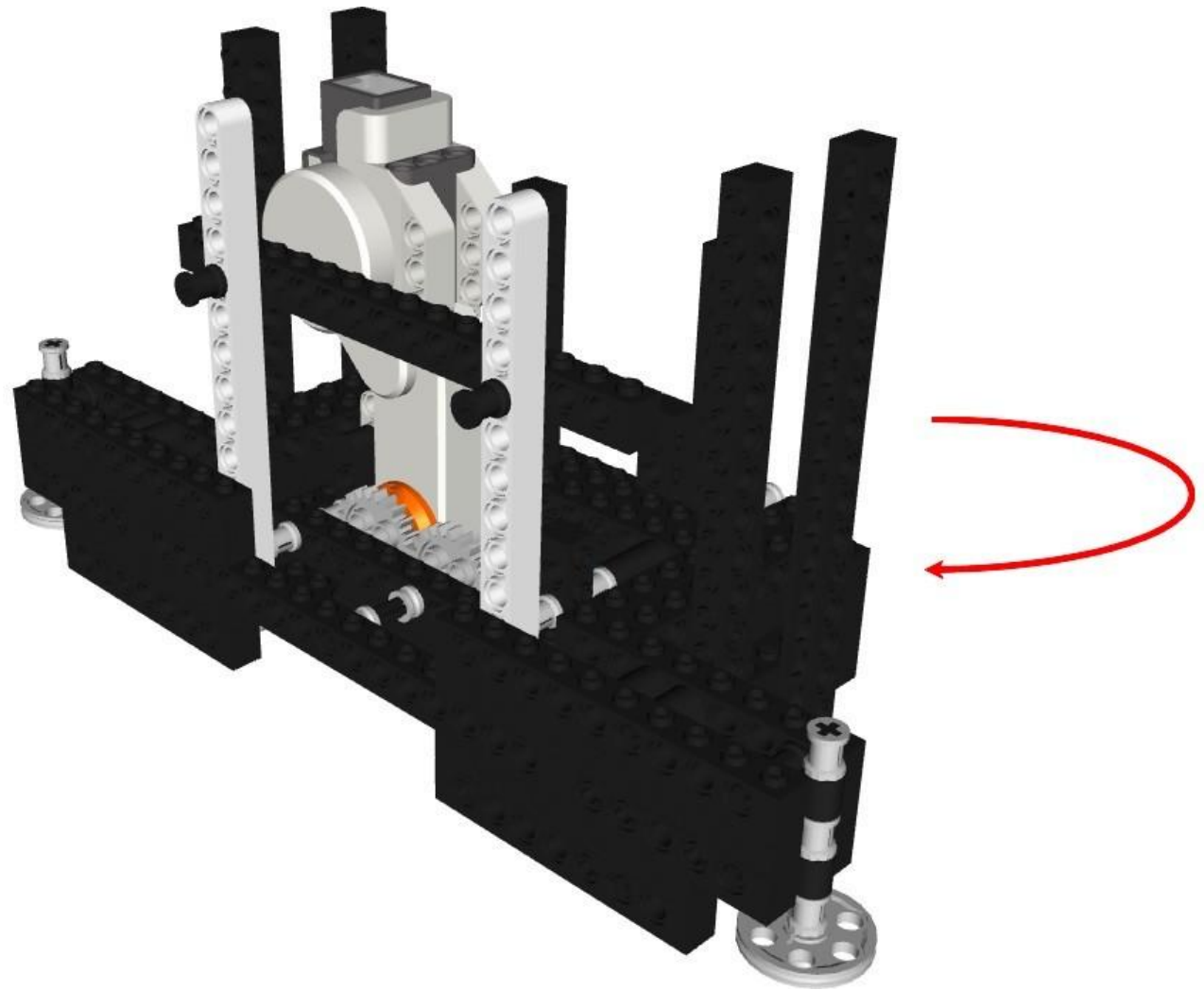


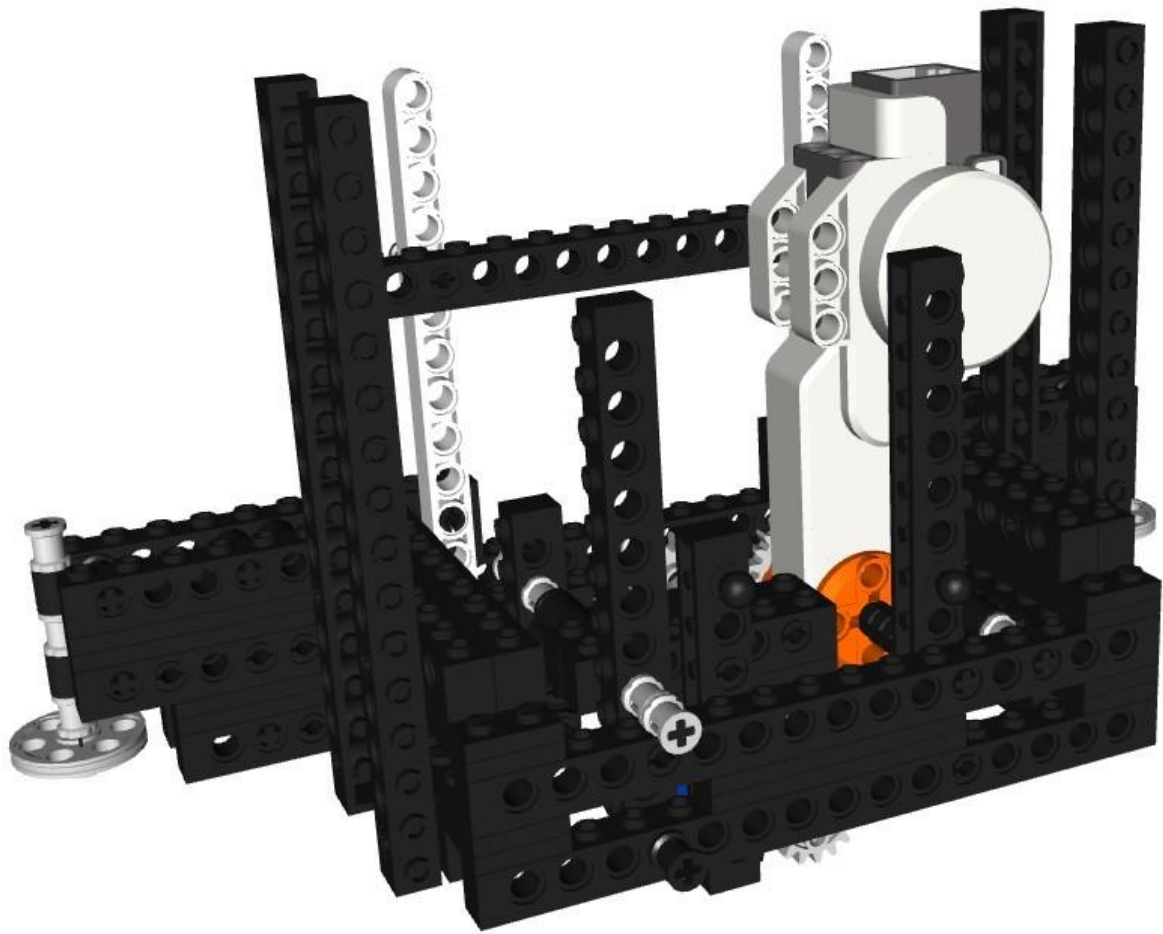




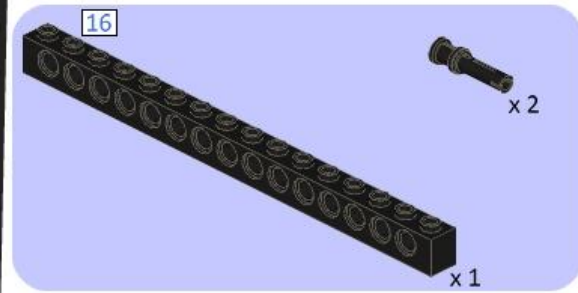
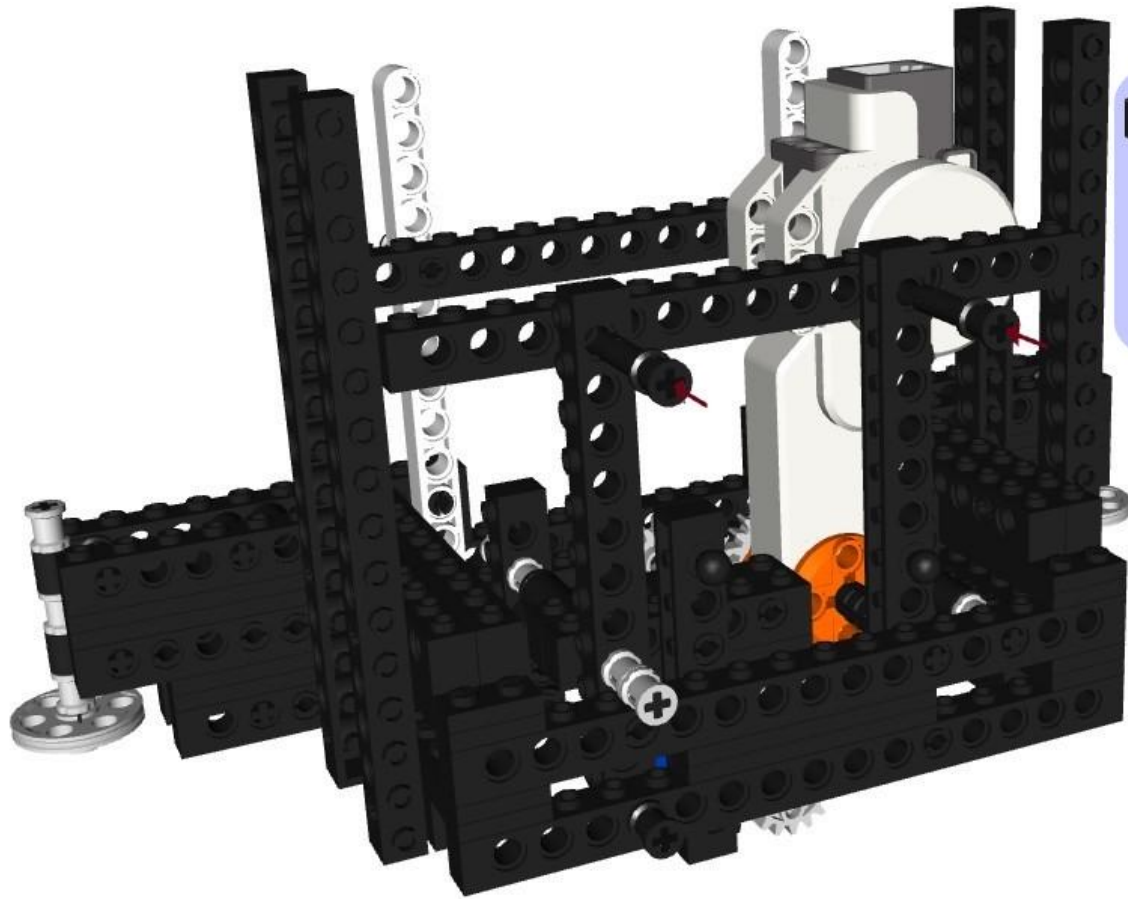


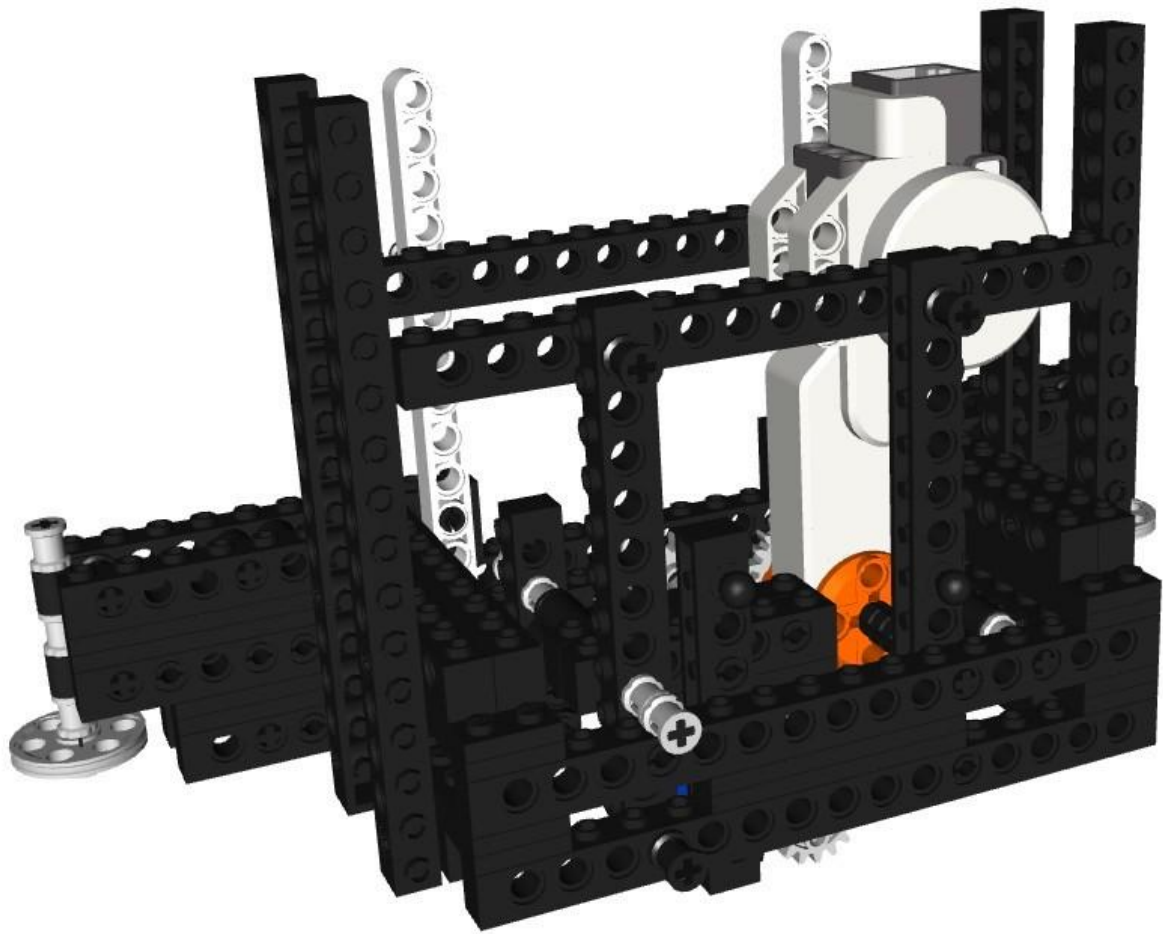


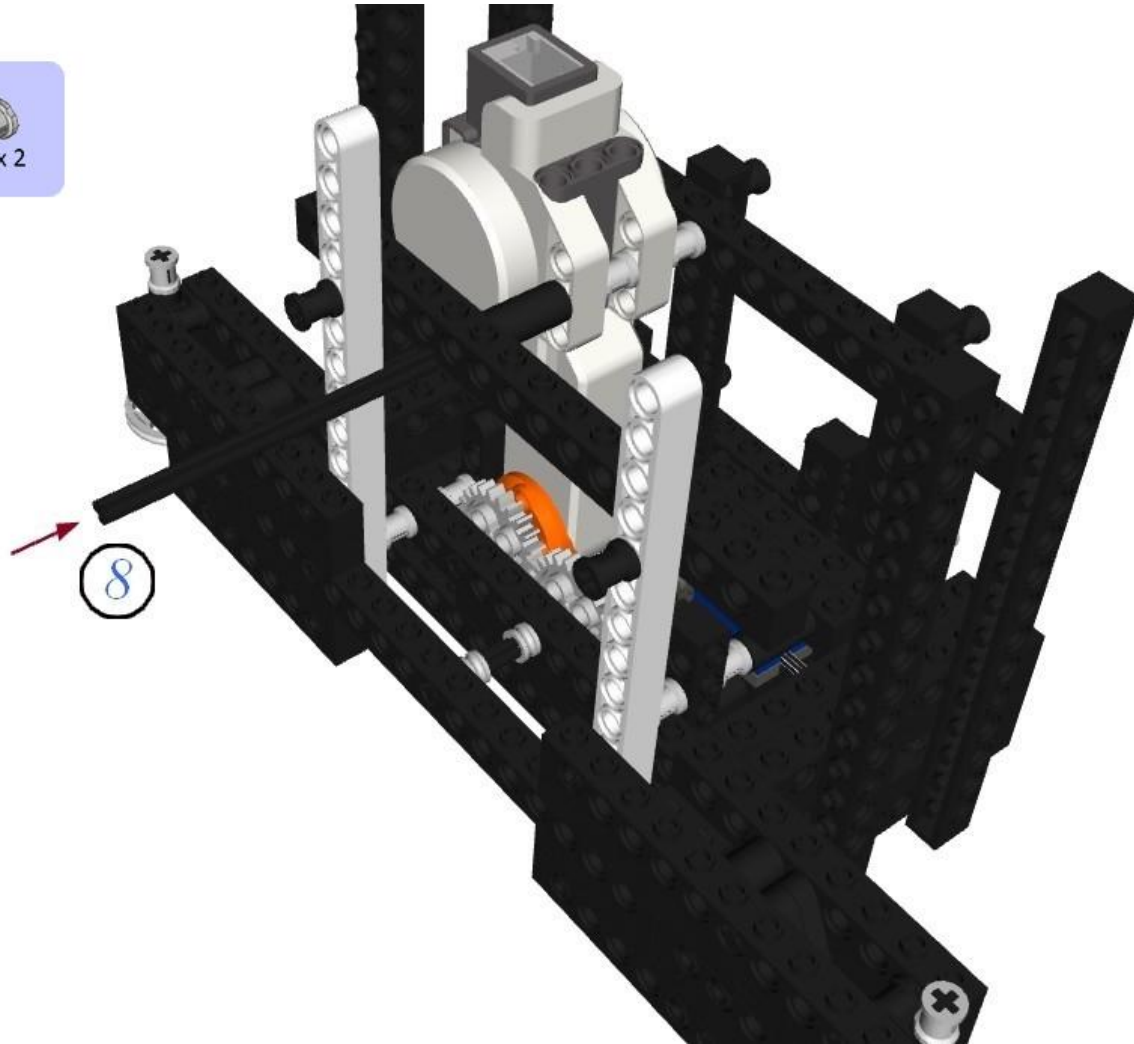


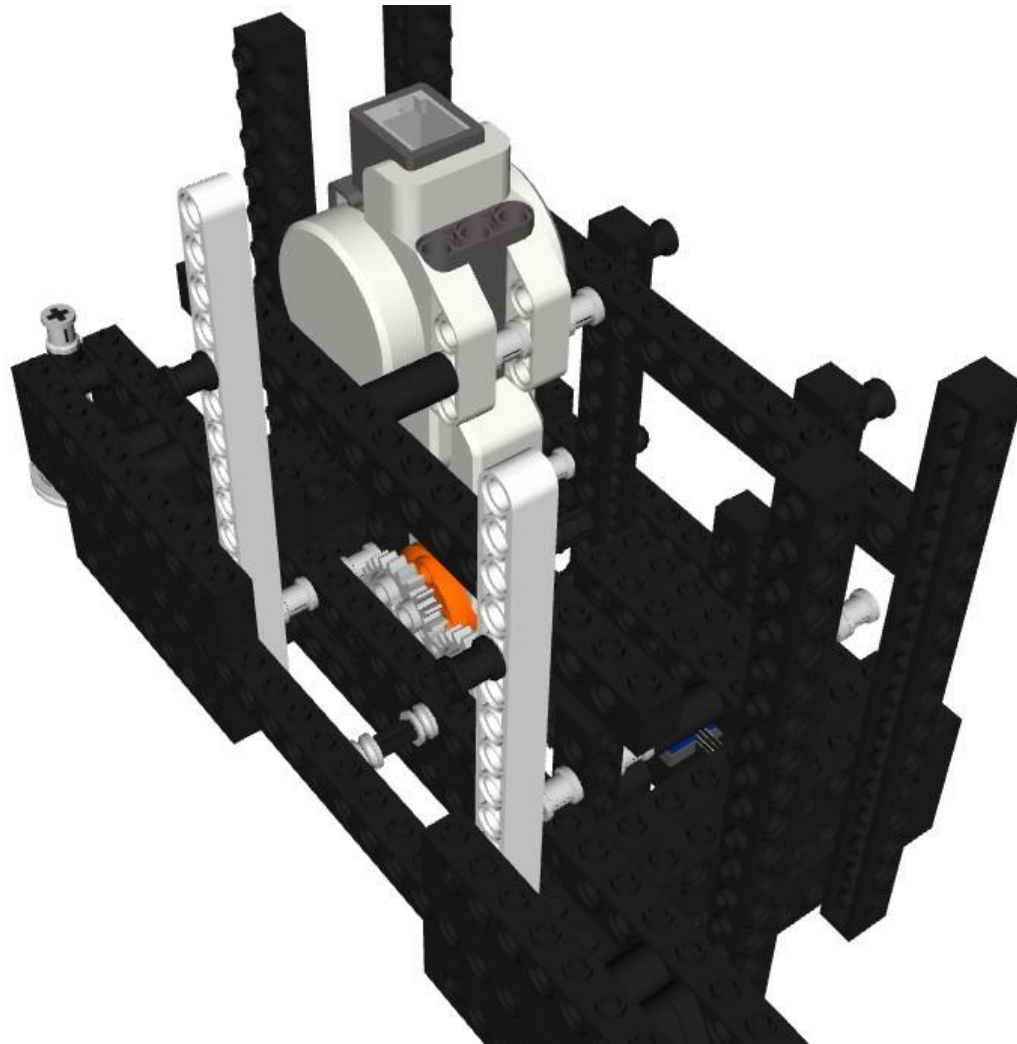


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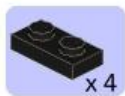


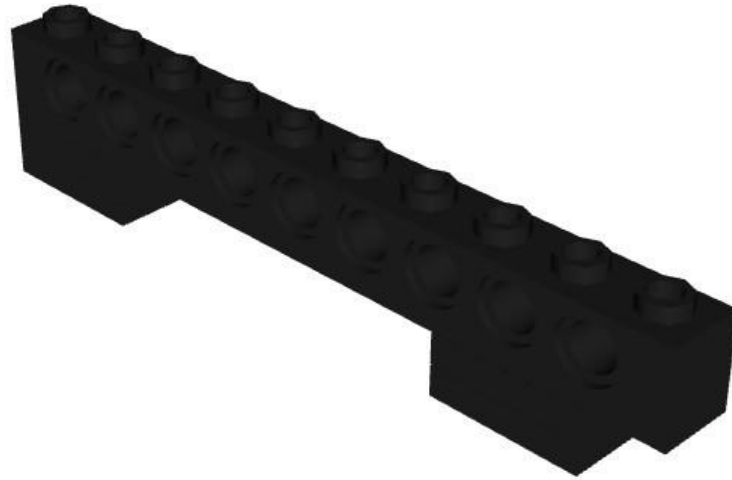
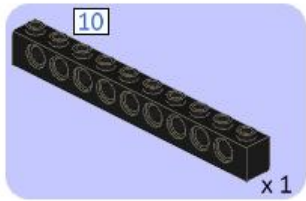


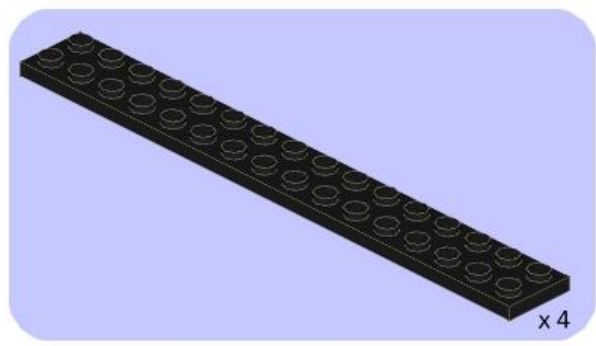
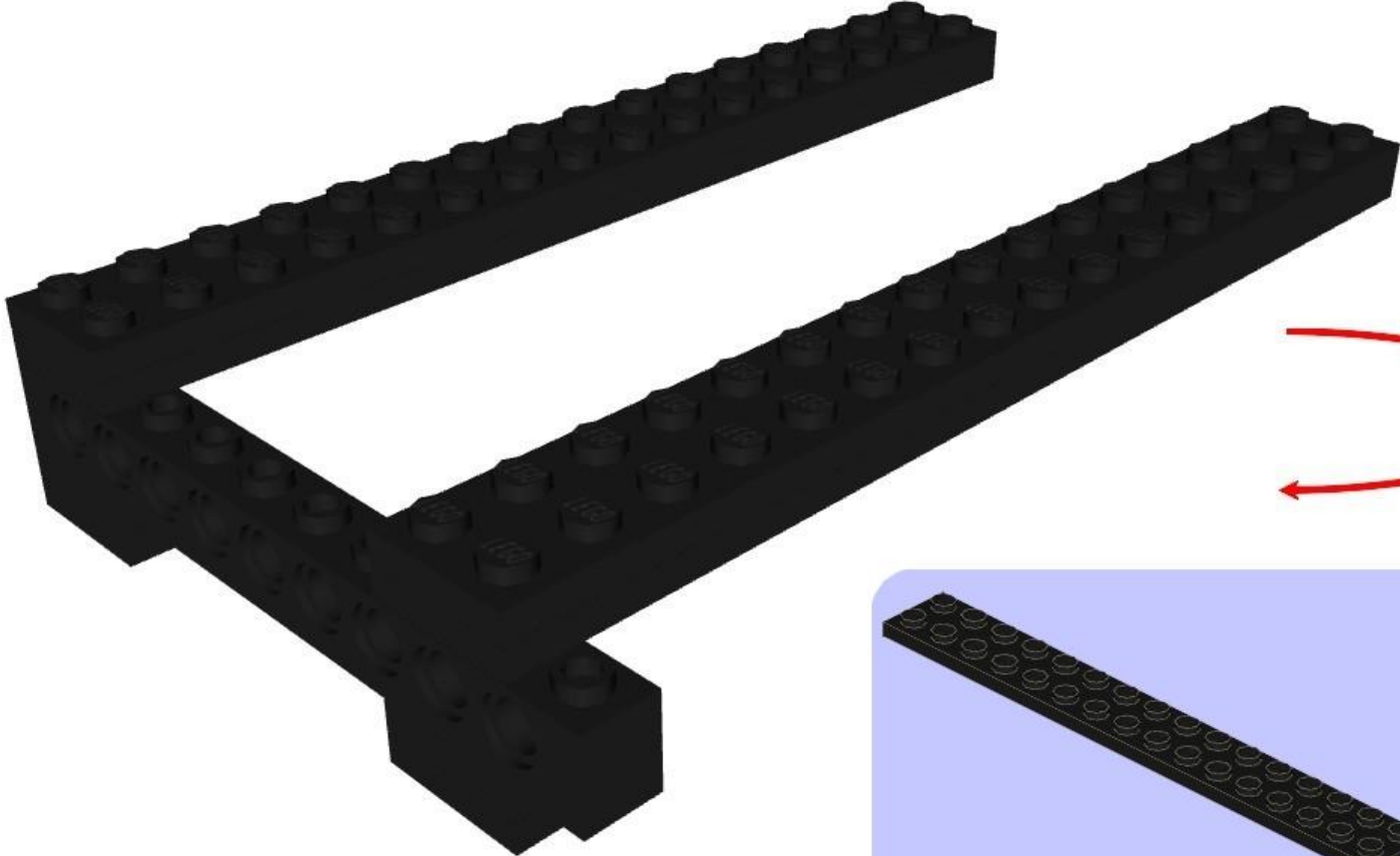


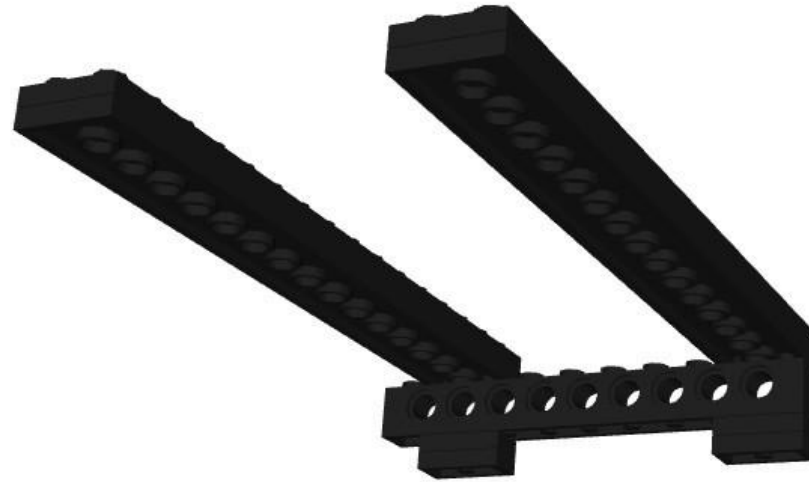


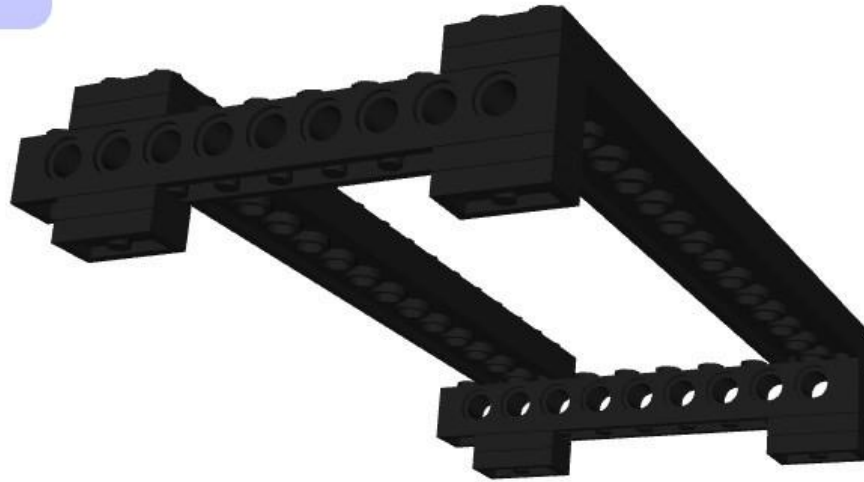
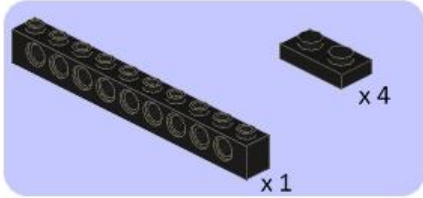
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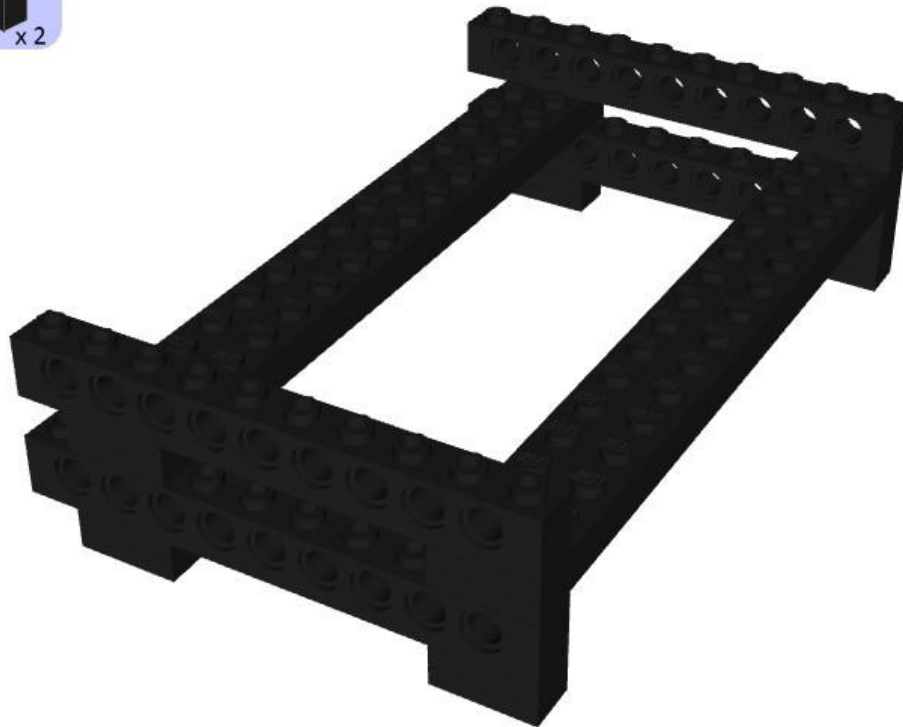


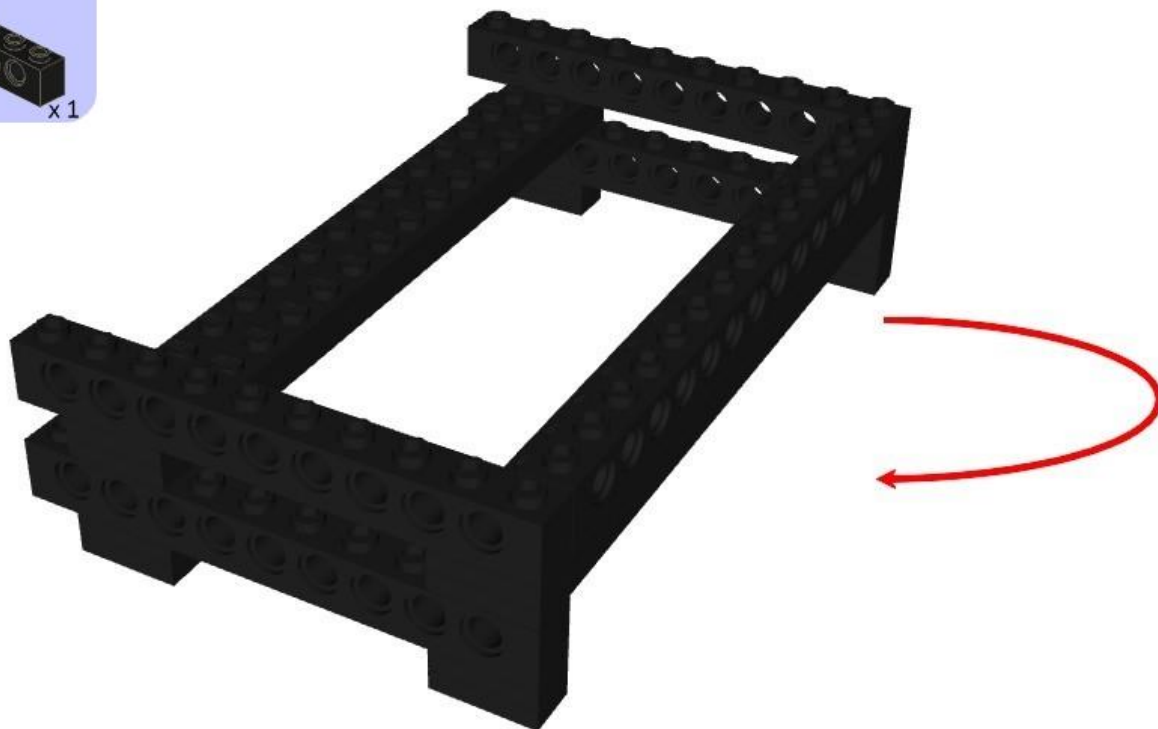
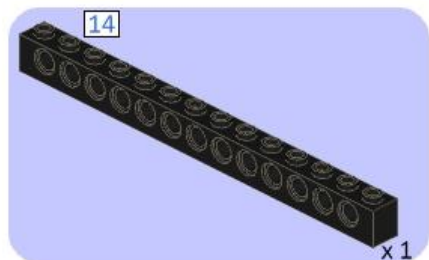




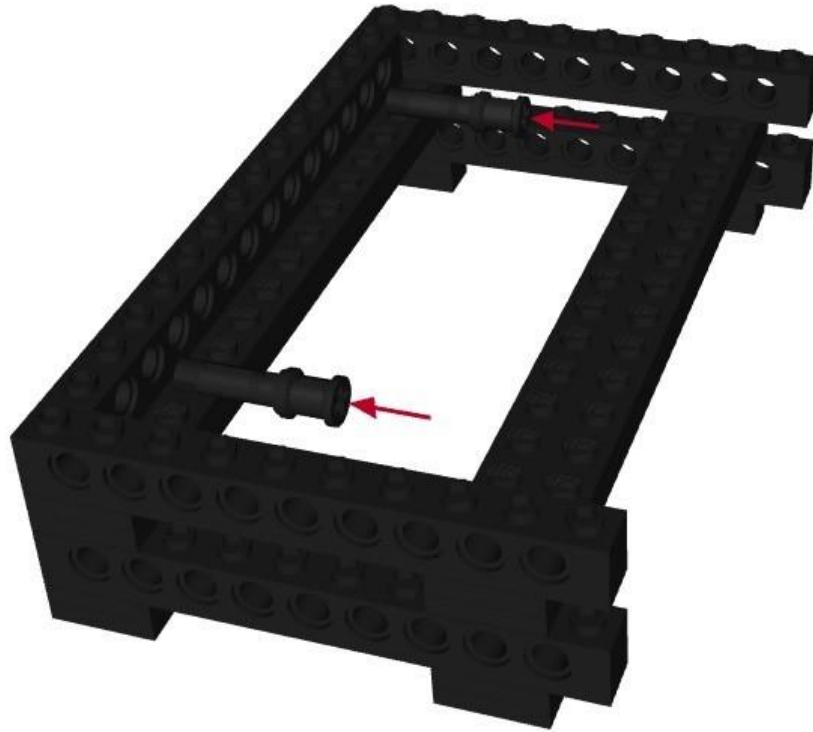


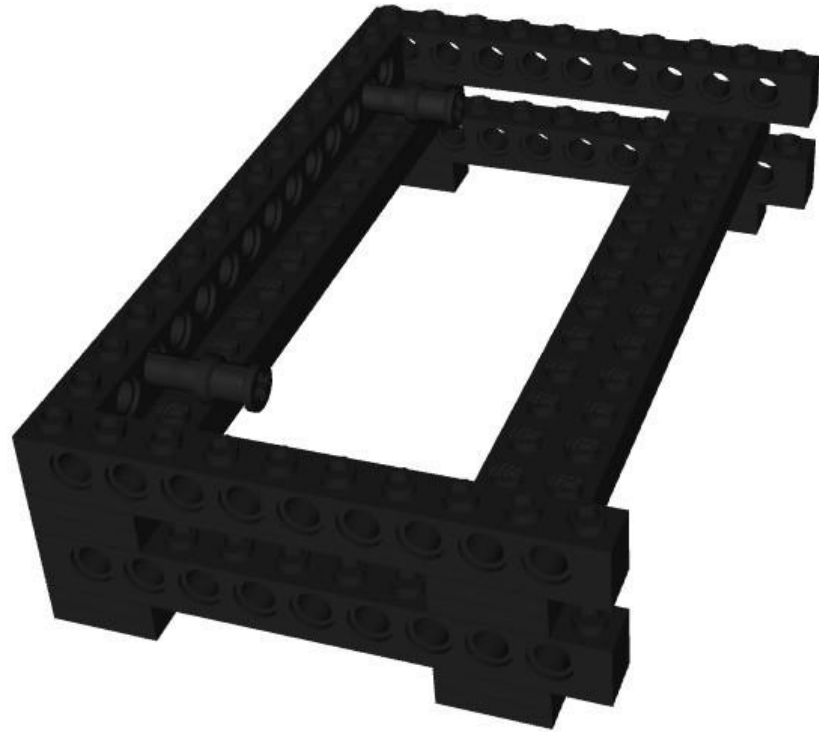


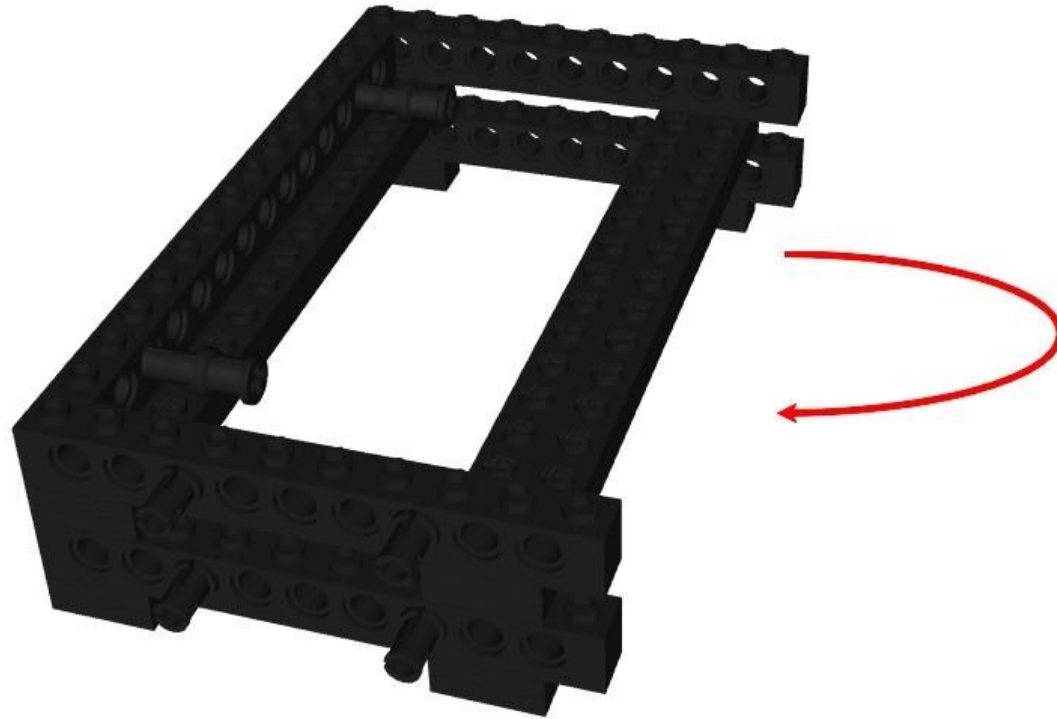


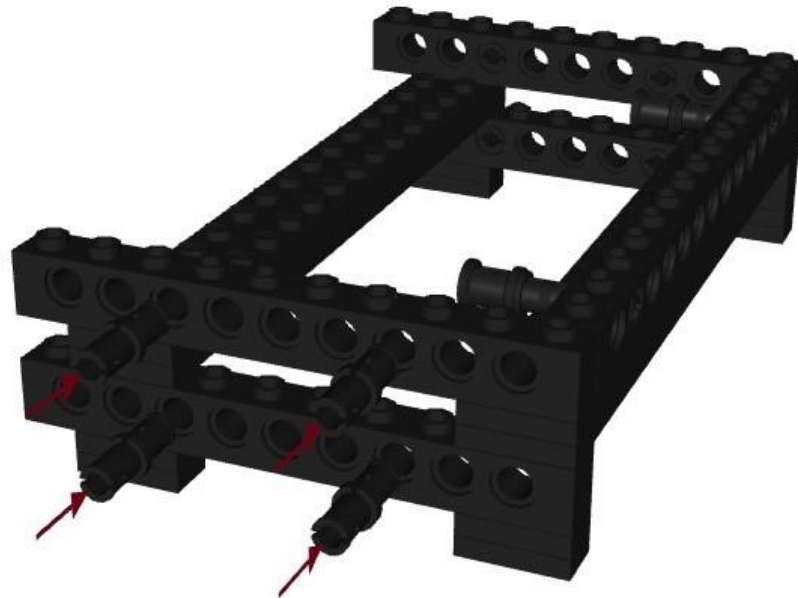


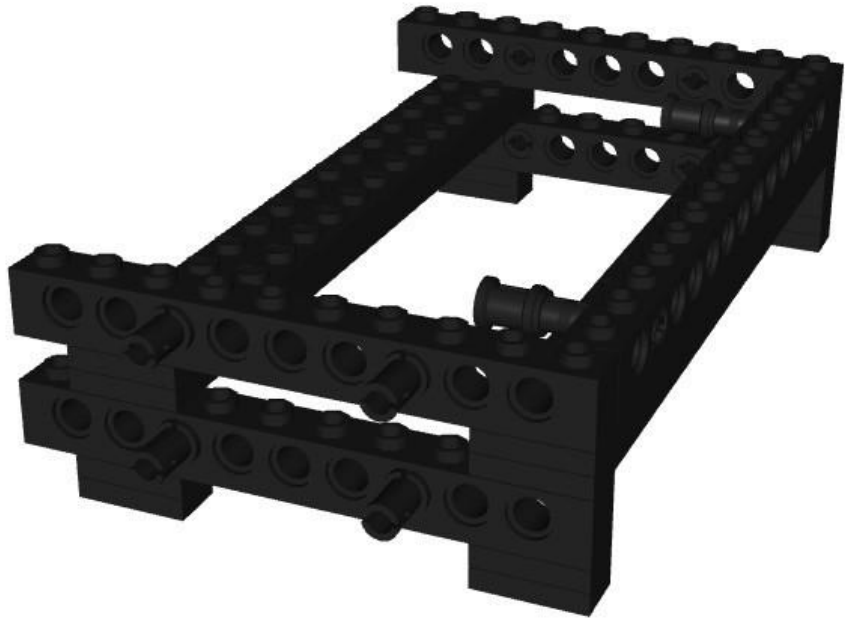


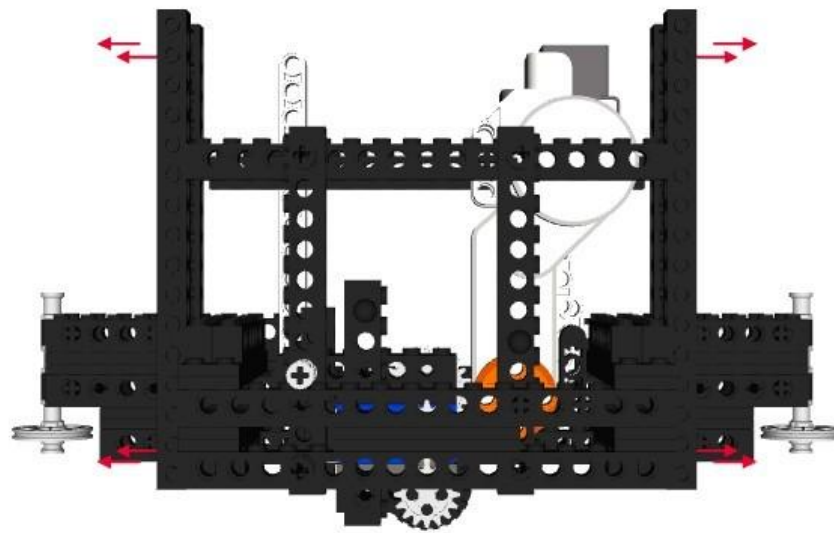


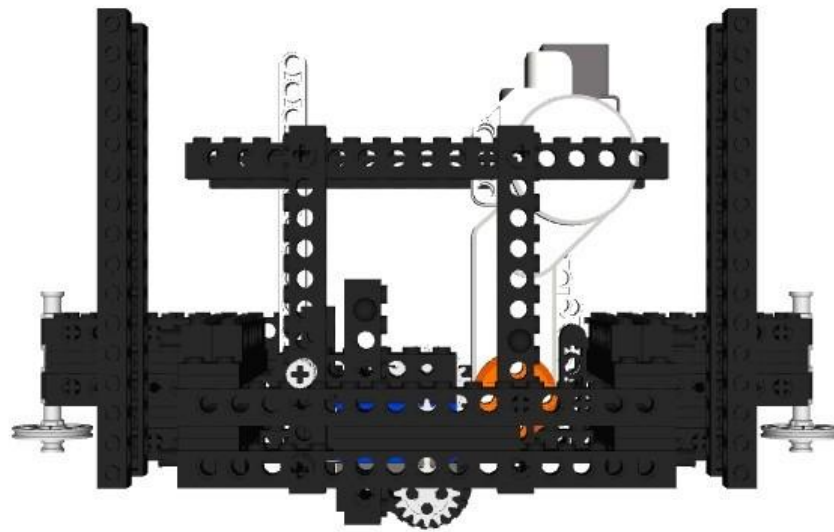


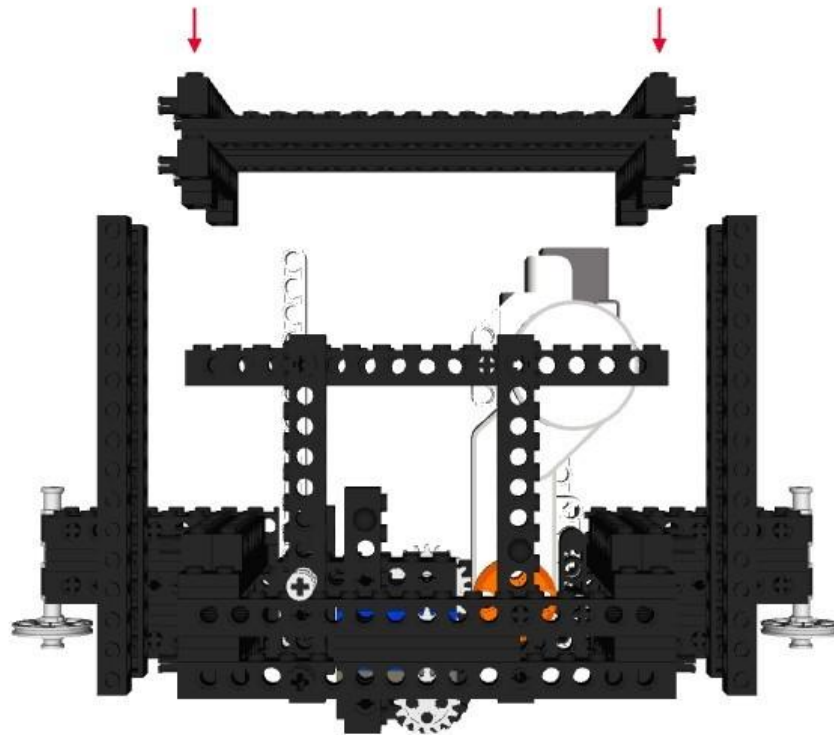


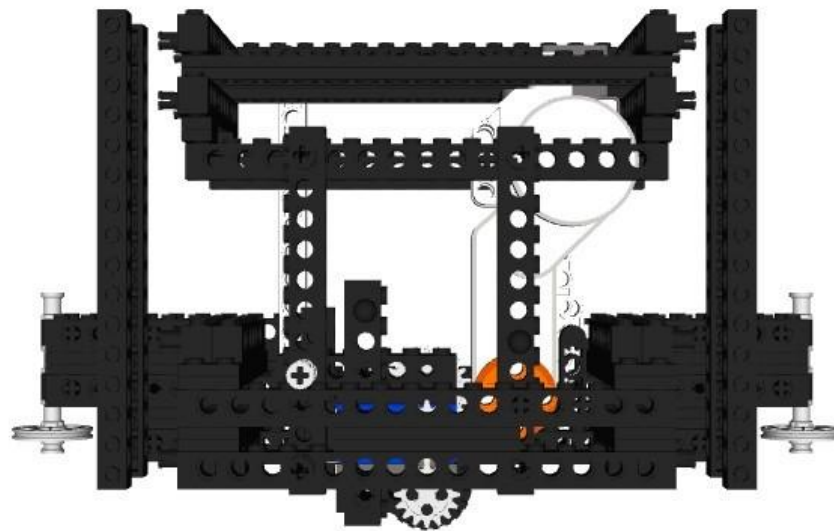


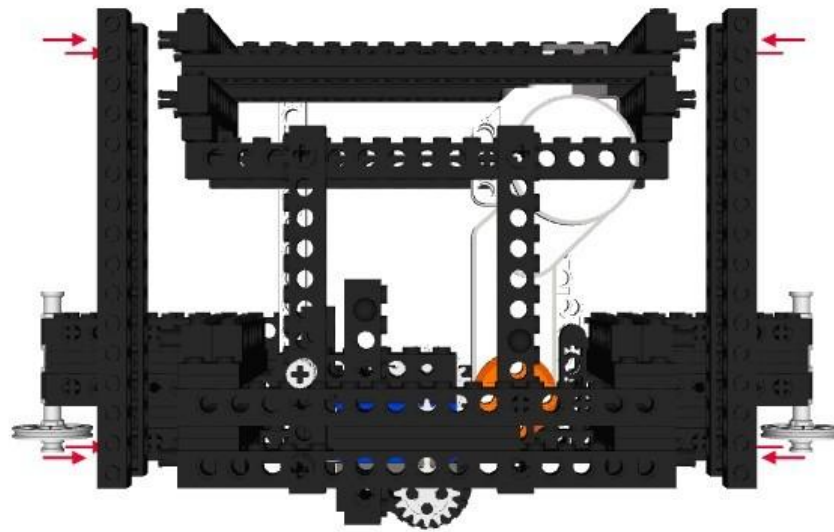


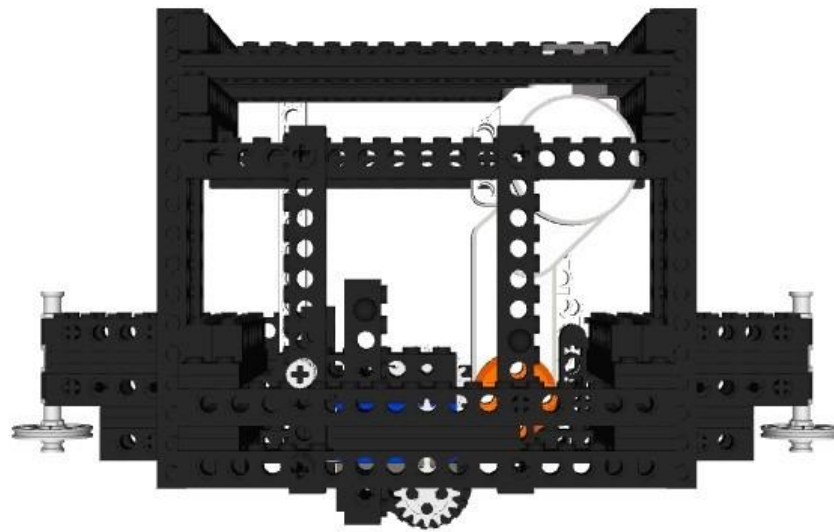


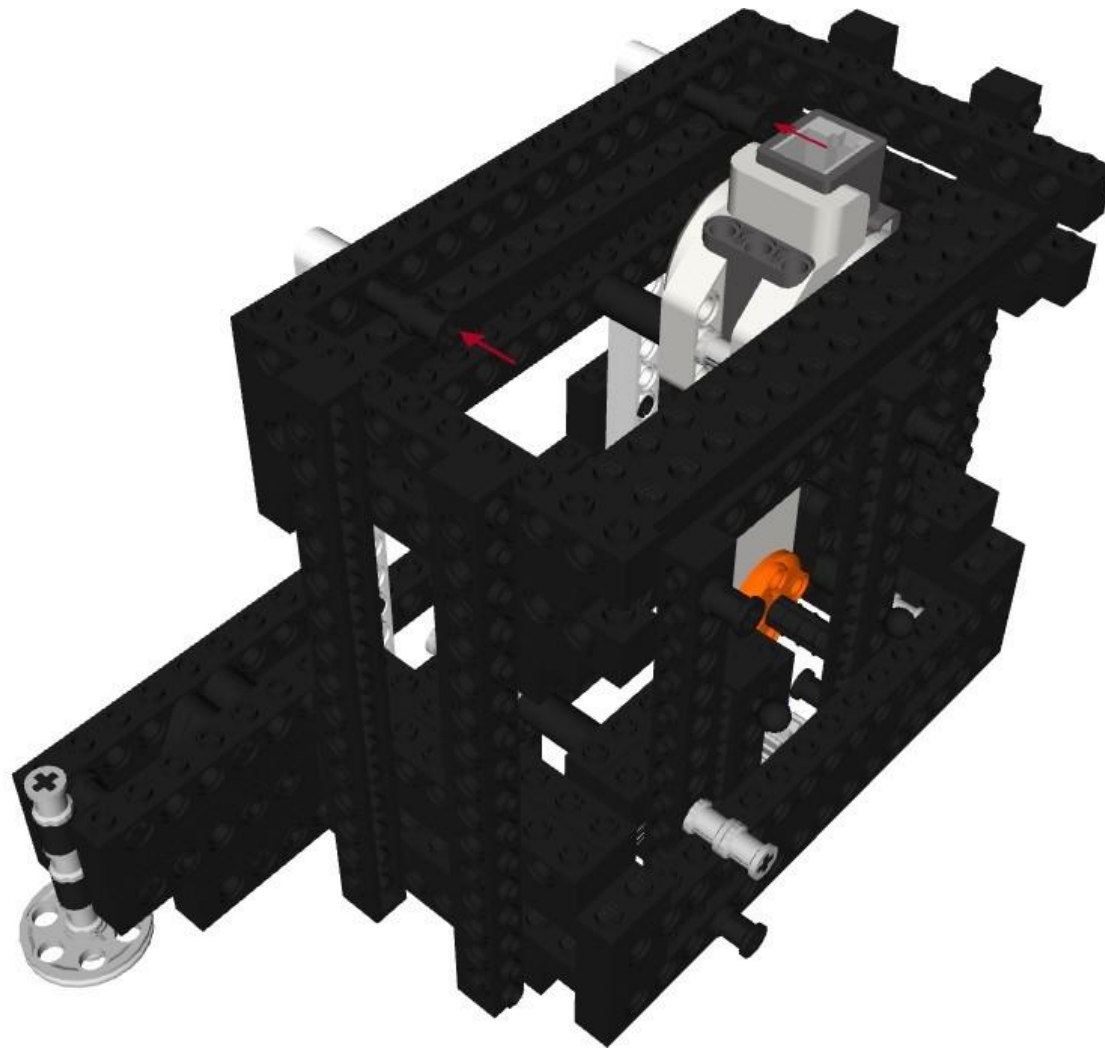




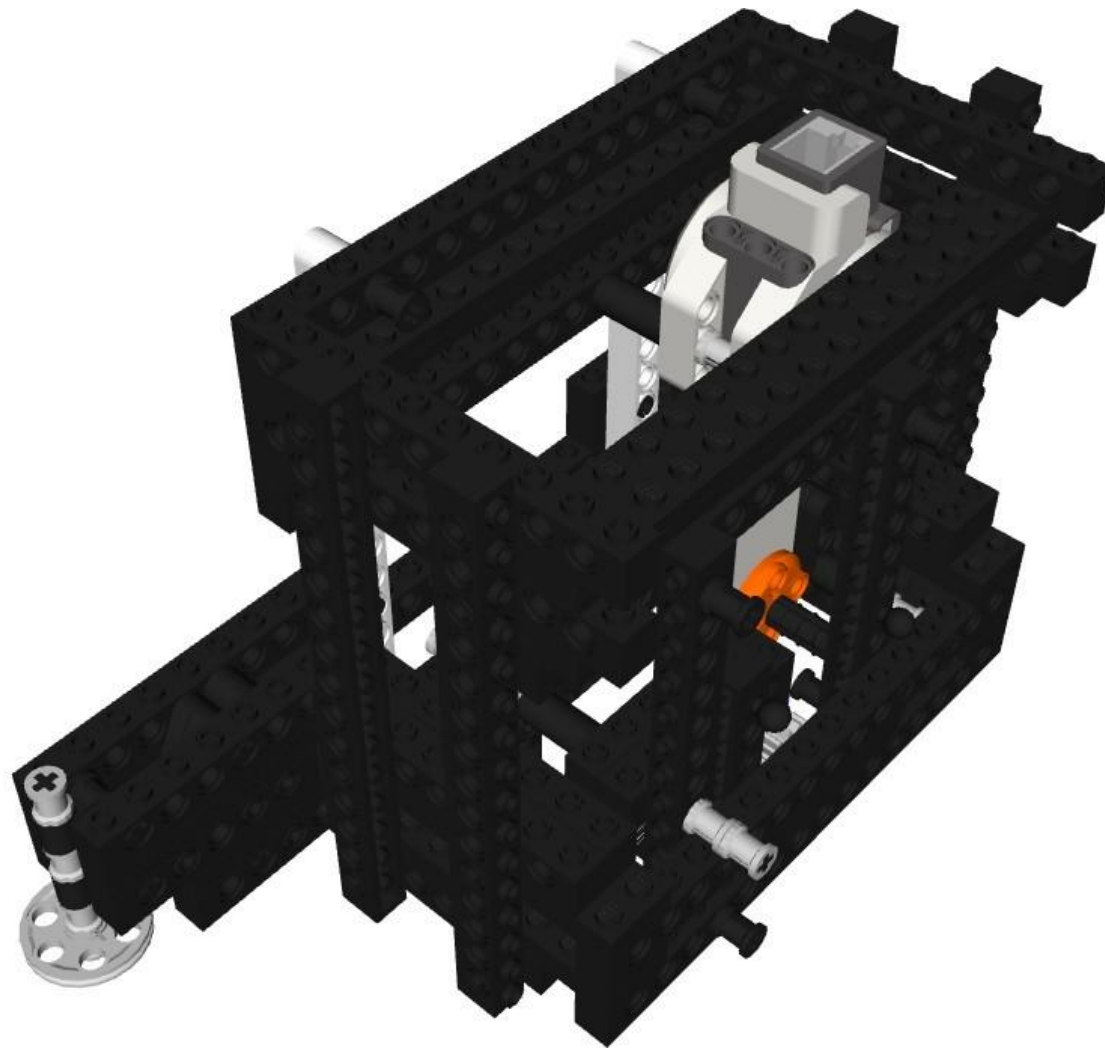




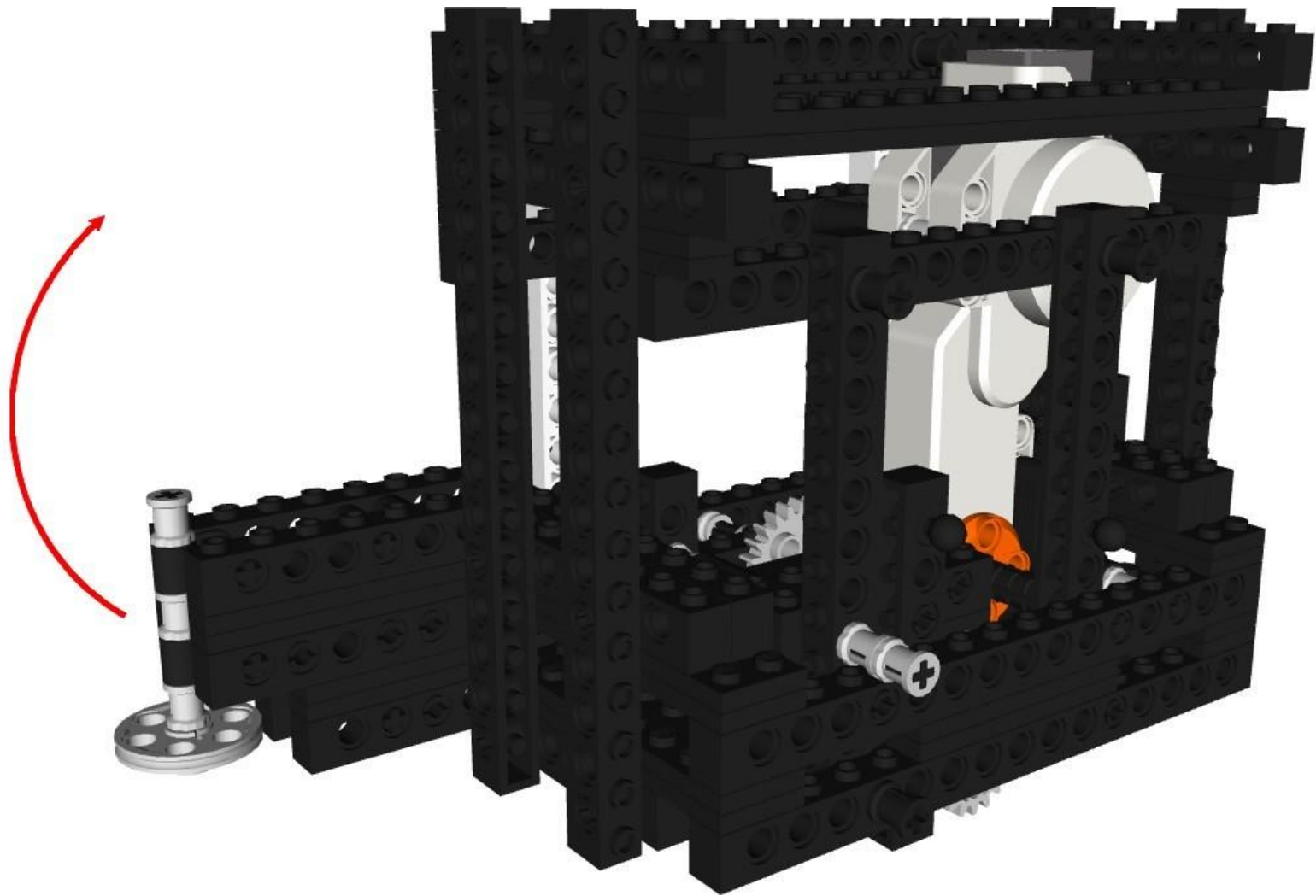




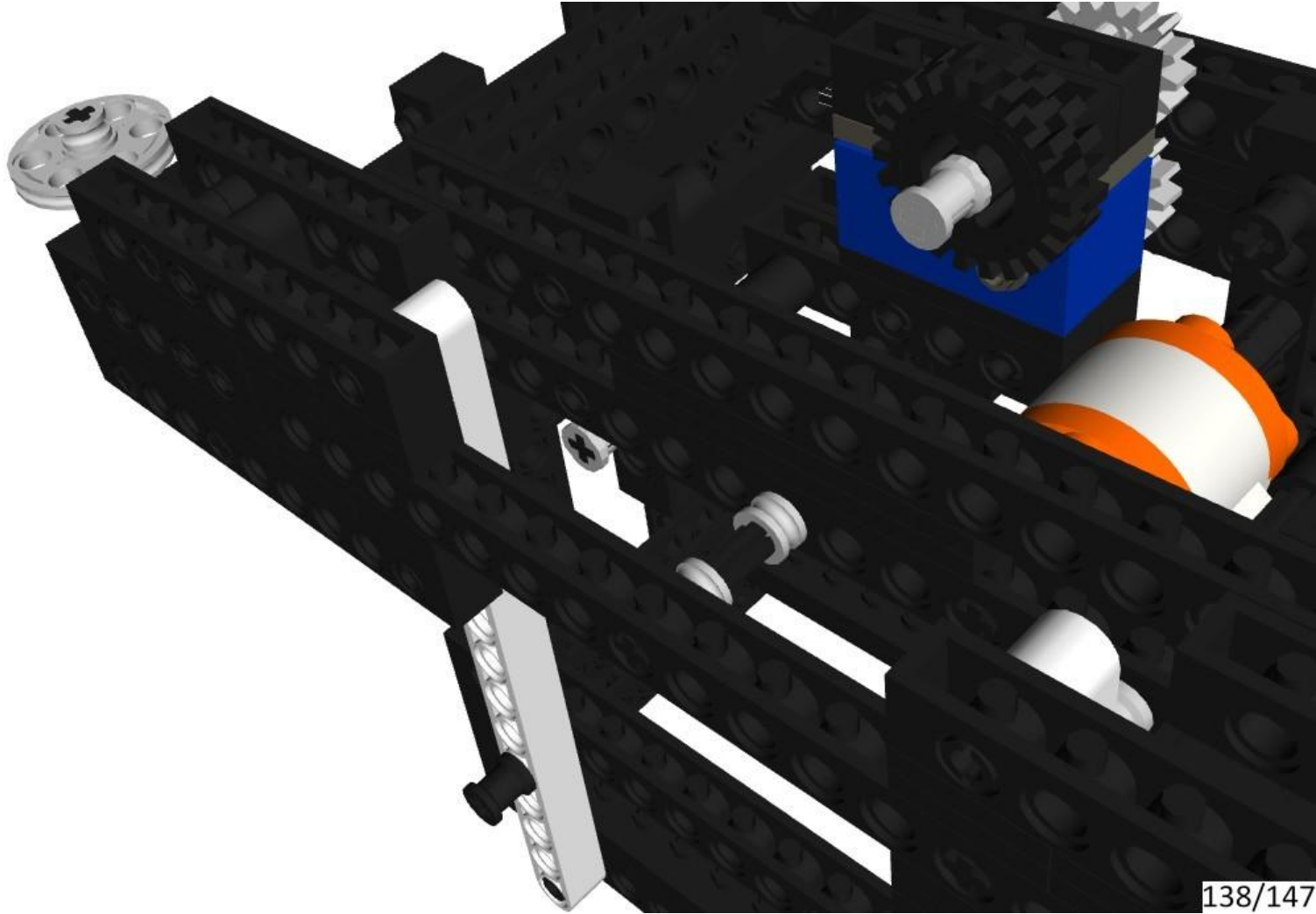
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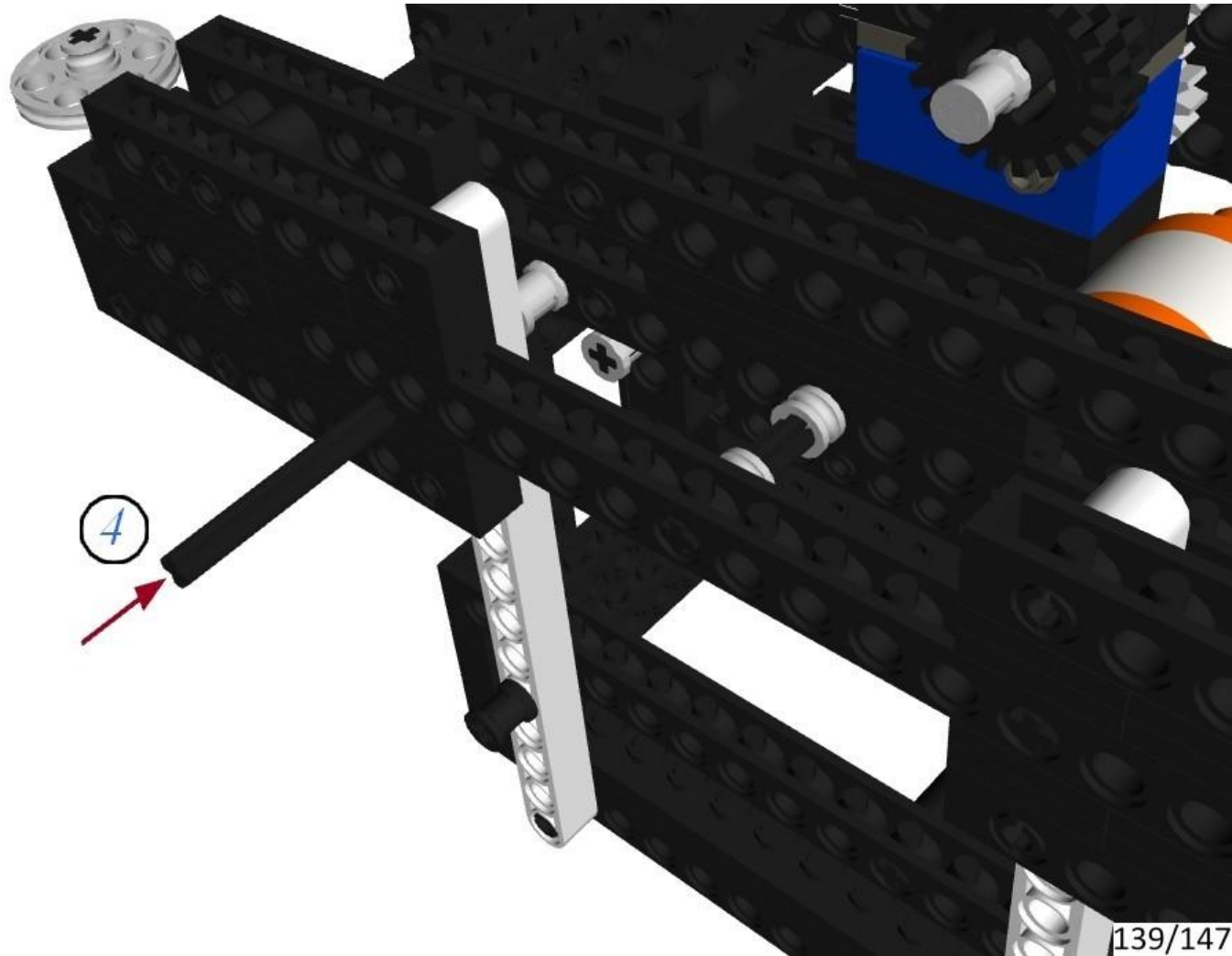
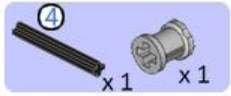
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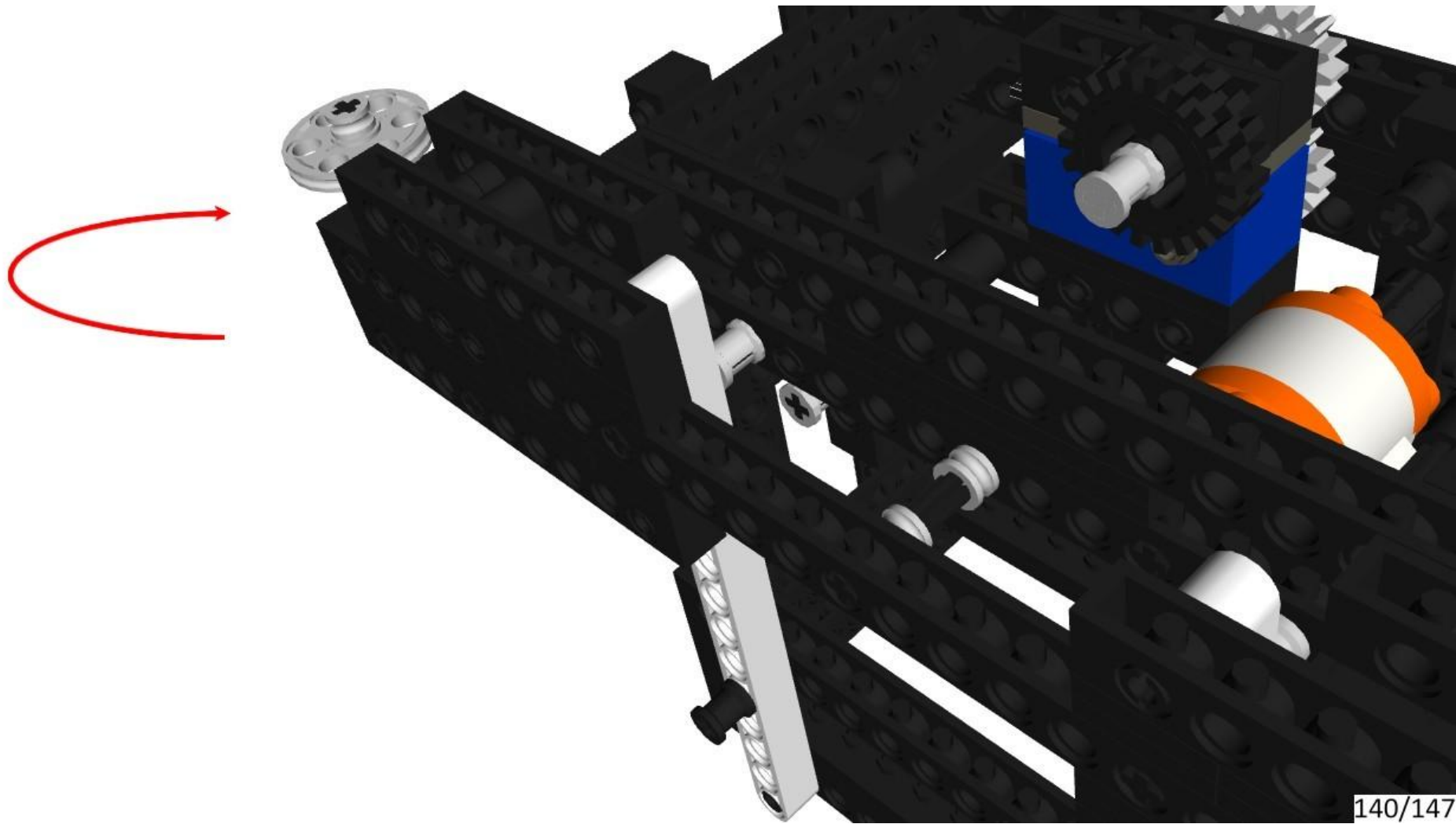


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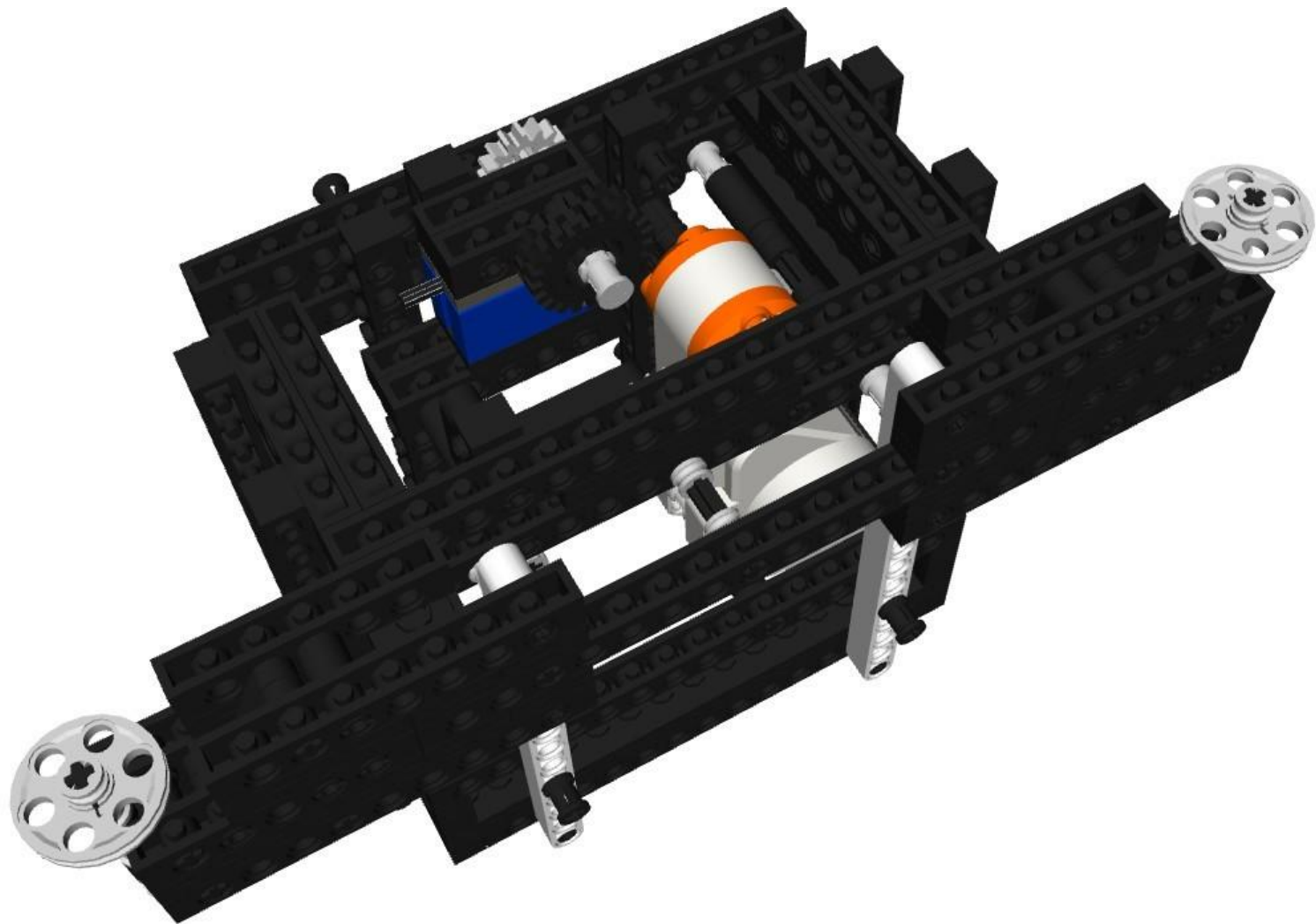


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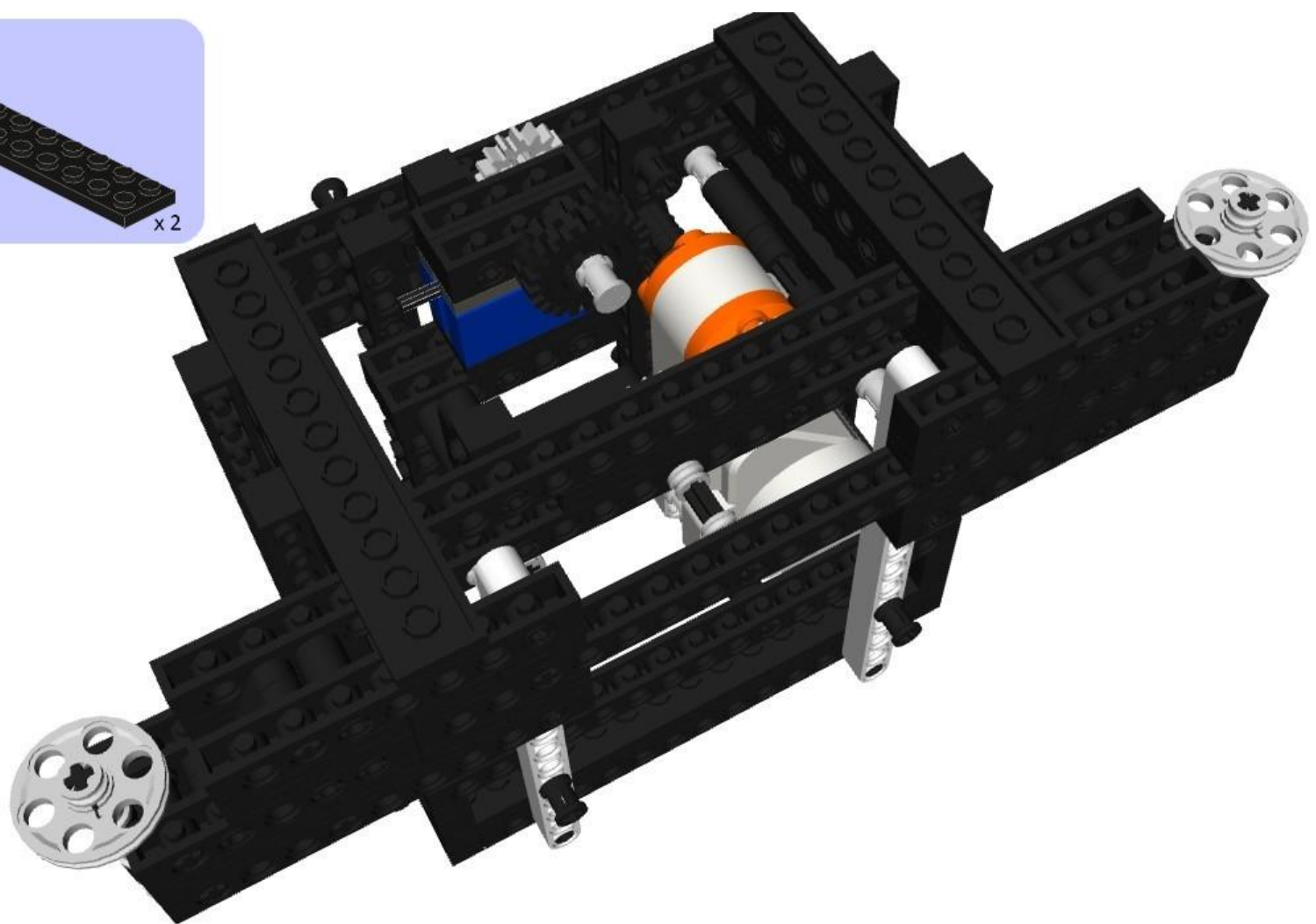
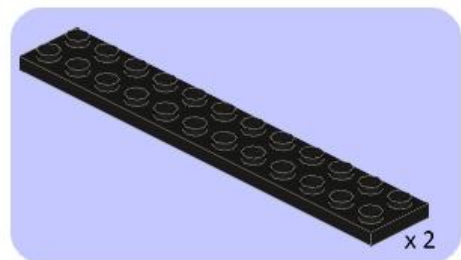


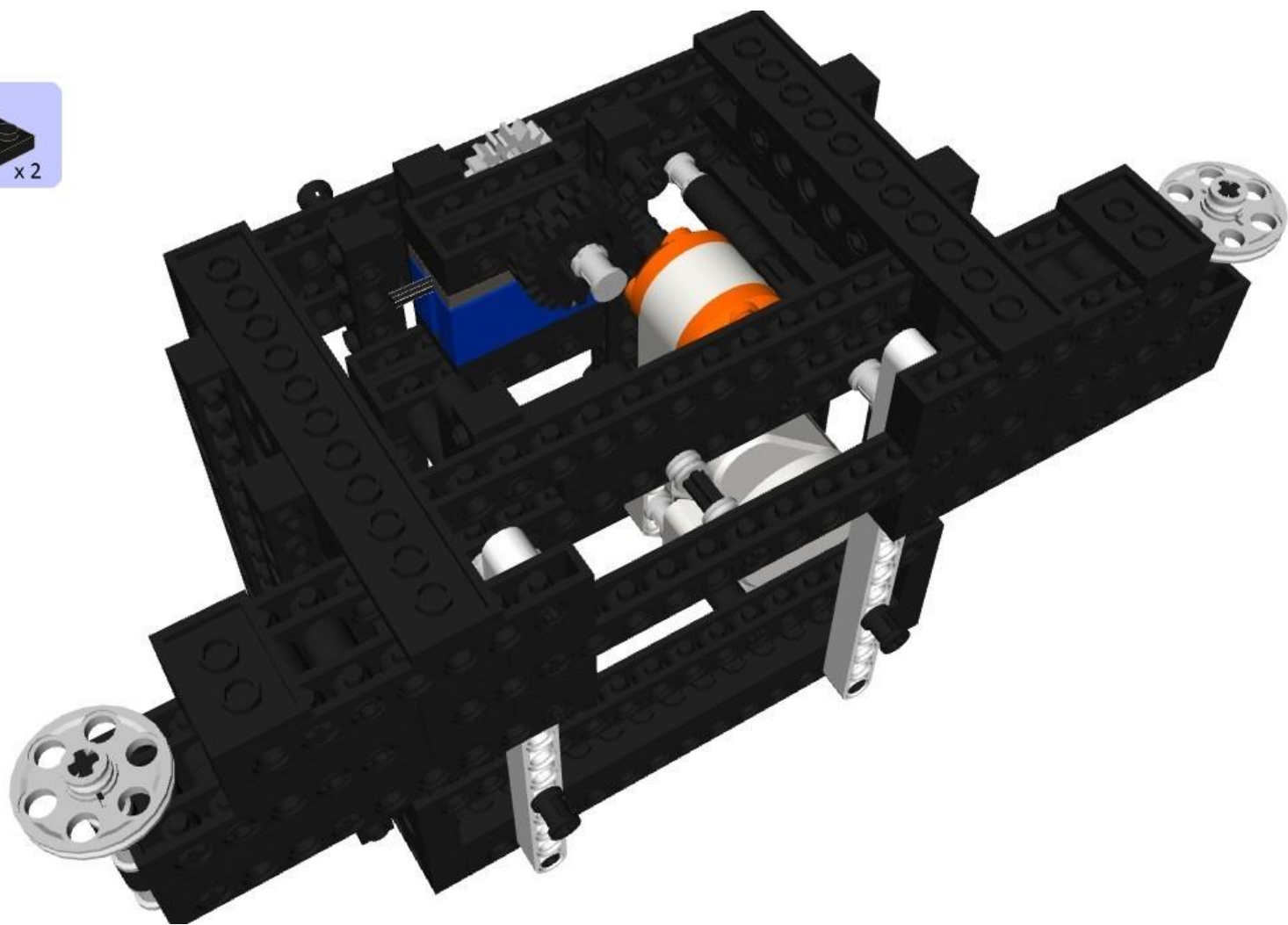
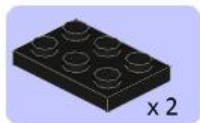


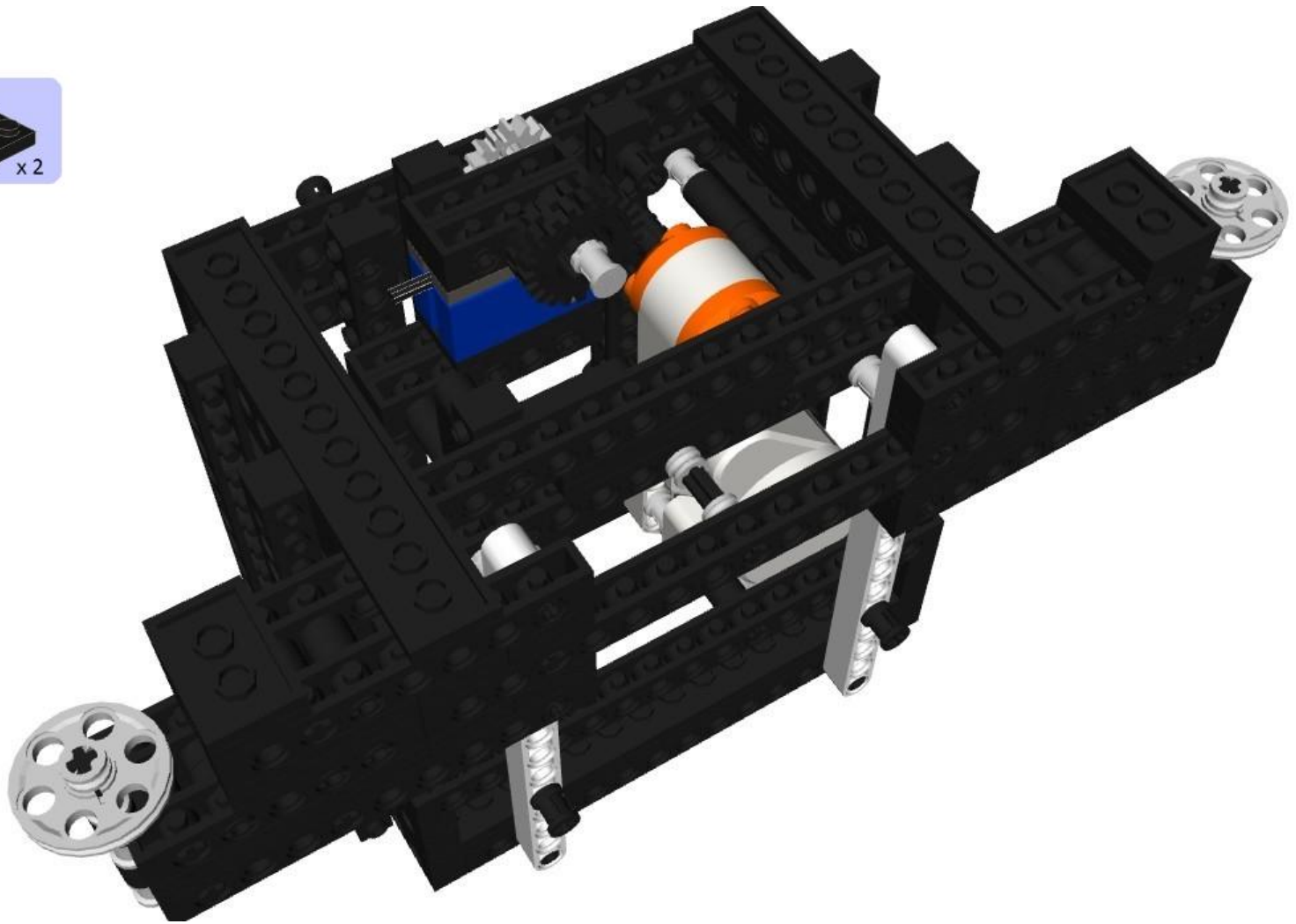
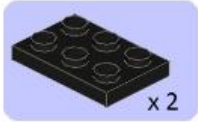
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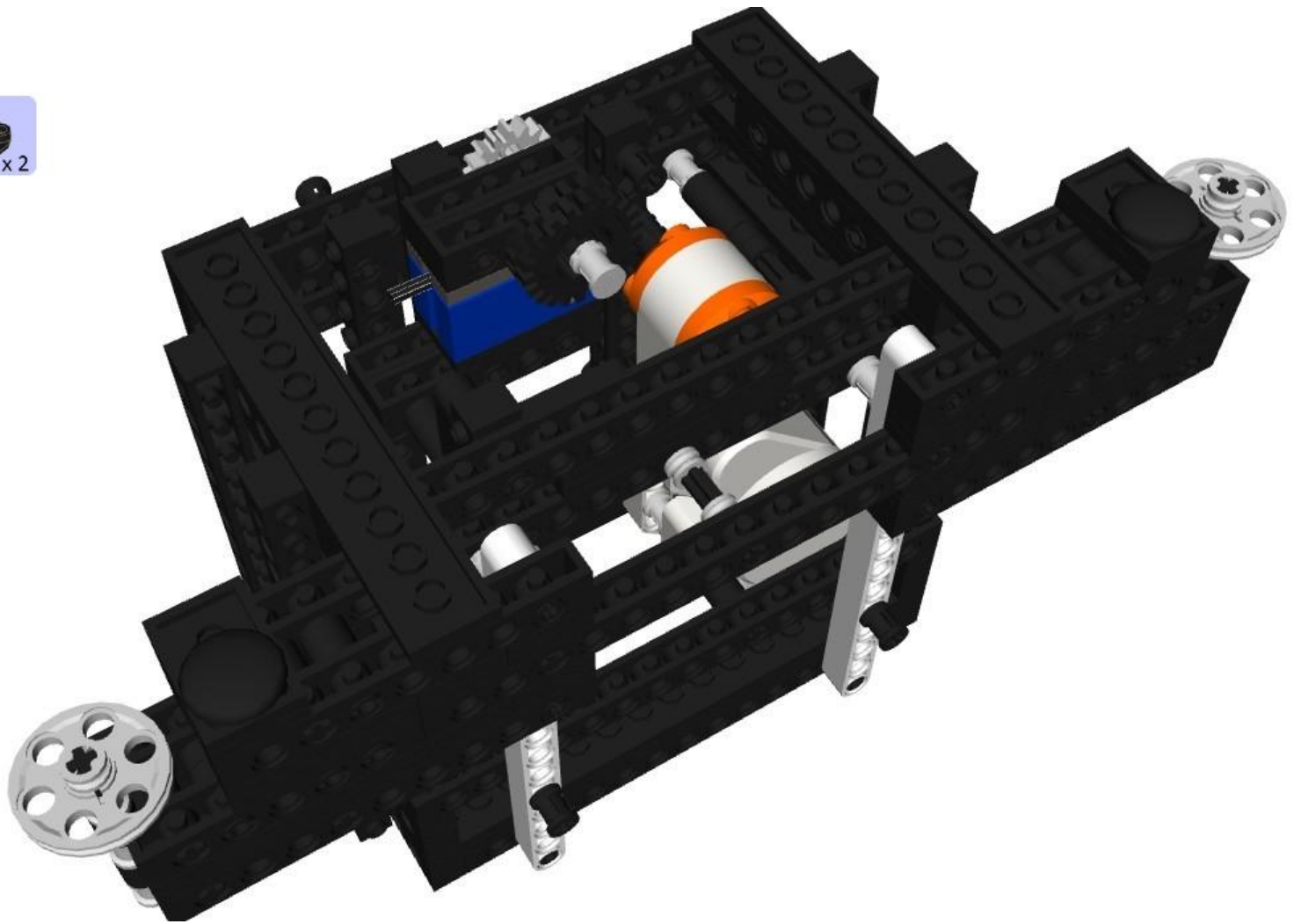


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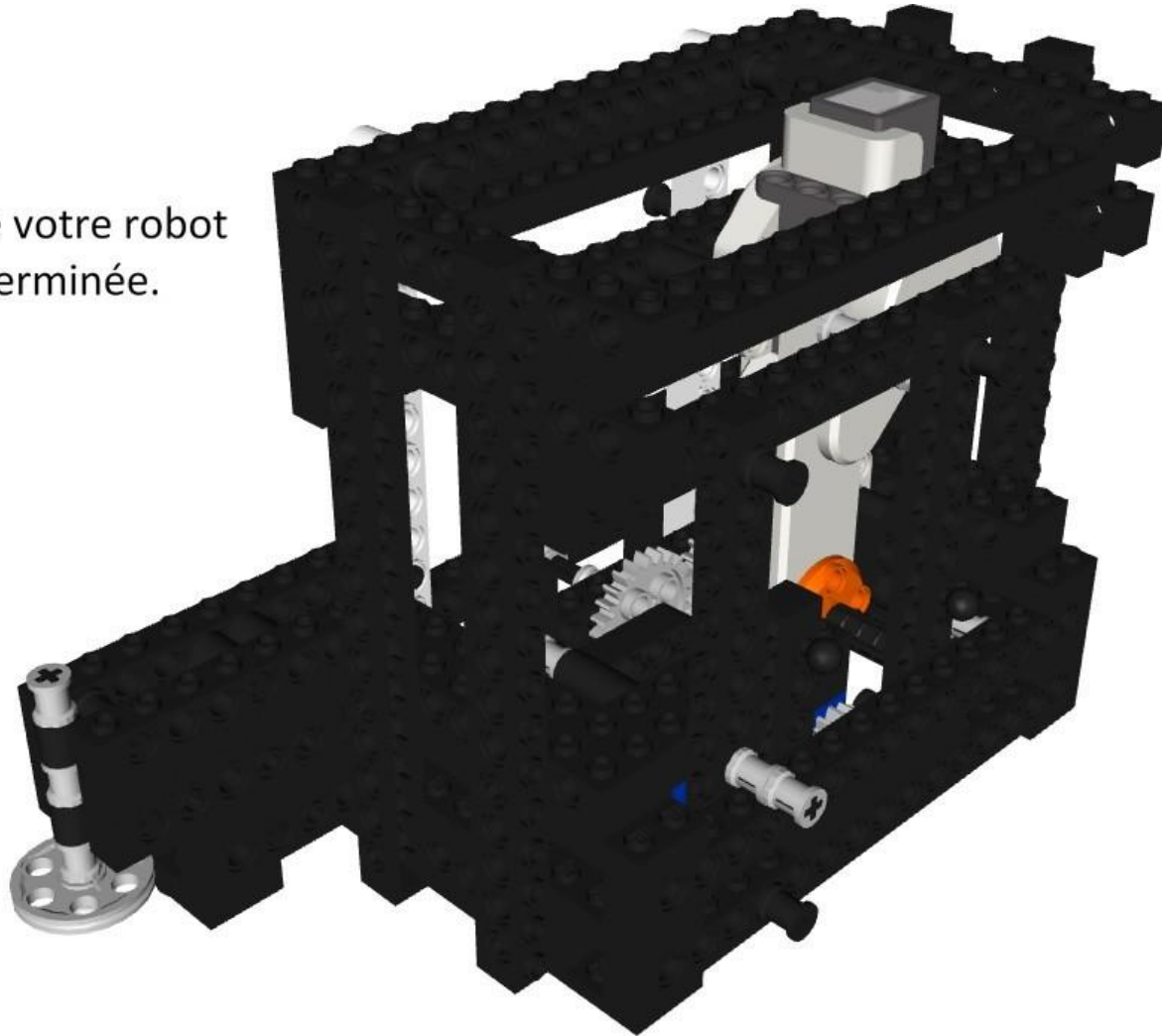




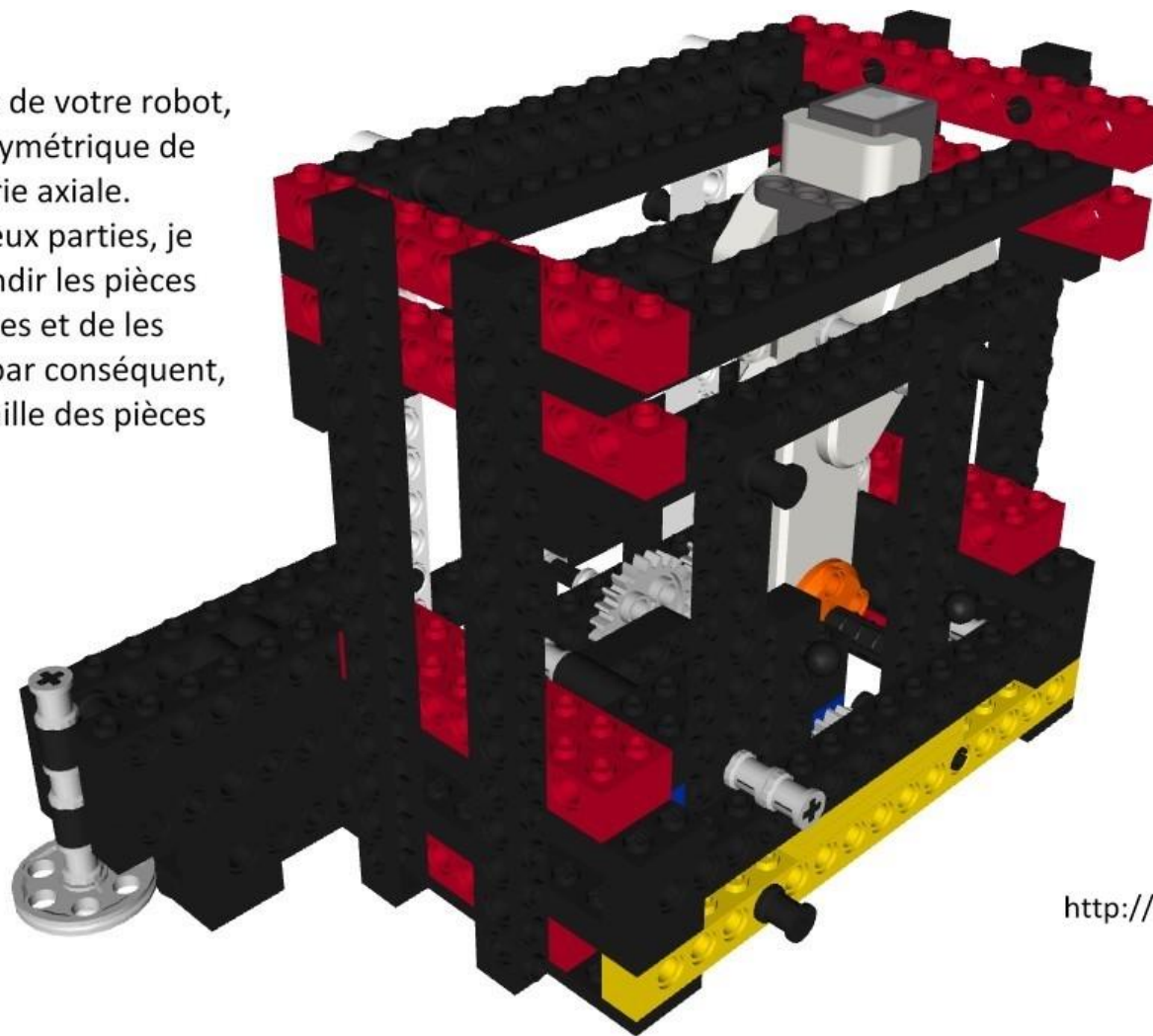


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La base droite de votre robot est maintenant terminée.



Pour terminer la base de votre robot, vous pouvez faire le symétrique de cette base par symétrie axiale. Pour assembler les deux parties, je vous conseille d'agrandir les pièces rouges des deux parties et de les attacher entre elles, par conséquent, il faudra changer la taille des pièces jaunes.



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